Switching Devices: Soft Starters, Semiconductor Switching Devices, Control Devices, AS-I





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| 3/110 | AS-Interface System overview |

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Siemens LV 10 · 2004

Soft Starters, Semiconductor Switching/Control Devices, AS-I

| Overview | | | | | |
|--|--|---|--|---|--------------|
| Products at a gla | ance | | | | |
| | | .0. | | | |
| 3RF21 | 3RF20 | 3RF23 | 3RW30/31 | 3RW34 | 3RW22 |
| | miconductor switching | r doviceo | | Order No. | Page |
| Semiconducto | | guevices | | | |
| 22.5 mm semico 45 mm semicono | nductor relays ductor relays | Construction width of 22. Compact and space-sav "Zero-point switching" ve Mounting onto existing here | ing design rsion | 3RF21, 3RF20 | 3/12 3/15 |
| Semiconducto SIRIUS SC sem | or contactors iconductor contactors | Complete units consisting optimized heat sink, "reading optimized heat space-save. Compact and space-save. Versions for resistive load loads "instantaneous swiiinstantaneous swiiinstantaneous swiiinstantaneous swiiins special designs "Low Notes Special designs" | ing design ds "zero-point switching" an tching" | d inductive | 3/22 |
| Function mod | ules | For extending the functiona relays and the 3RF23 semi | ality of the 3RF21 semicond | luctor | |
| Converters ent applications: • The converter is used to convert an analog input signal to an | | | | | 3 3/26 |
| Load monitors | | on/off ratio • Load monitoring of one or more loads (partial loads) | | | |
| Output regulator | rs | The output regulator sup conductor switching dev Closed-loop control: Full control | it value. | 3/28 | |
| | TART soft starters | | | | |
| For standard a SIRIUS soft star | | SIRIUS 3RW30/31 soft st ramp-down of three-phas Service range Pumps Compressors Conveyors | | smooth 3RW30, 3RW31 | 3/46 |
| SIKOSTART sof | t starters | SIKOSTART 3RW34 soft ramp-down of three-phase Methods of connection Inline circuit Inside-delta circuit Service range Pumps Compressors Fans Conveyors | starters for soft starting and se asynchronous motors | i smooth 3RW34 | 3/58 |
| For advanced SIKOSTART sof | | state SIKOSTART 3RW22 tions for higher-level requ up to 710 kW (at 400 V) • SIKOSTART 3RW22 soft | raking, and energy-saving ous motors | prous func- ng range of tarting and | 3/70 |

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Soft Starters, Semiconductor Switching/Control Devices, AS-I

Introduction

| Products at a glance | | | | | |
|---|---|--|--|------------|--|
| ececcece ececcecee | | | | | Manager State State Manager S |
| 3UF5 | 3UF1 8 | 6ED1 052 | 6ED1 055 | | 6ED1 057 |
| | | | | Order No. | Page |
| Motor management systems SIMOCODE-DP motor protection and control devices | Basic U Expans Control For use if the proof between Increase Saves co of the plate Multifunct Compression Integrate wiring) | sion module and module n low-voltage switchgear for motor eas industry; establishes the intellig the motor feeder and the process s plant availability sts during construction, commission ant tional, electronic motor protection a pensive motor and plant diagnostic d control programs (instead of exter mmunication via PROFIBUS DP, the | ent connection I&C system and plant monitoring s ensive hardware | 3UF5 | 3/86 |
| Current transformers for overload | I protection • Protectio • Ensures | n converters for activating overload proportional current transfer up to a | | 3UF1 8 | 3/97 |
| LOGO! logic modules | primary r | ated current | | | |
| LOGO! logic modules | tasks • Universa - Buildin doors, - Cabine - Machir compre | t, user-friendly, and low-cost solution g installation and wiring (lighting, s access control, barriers, ventilation t installation le and device construction (pumps essors, hydraulic lifts, conveyors l controls for conservatories and gr | hutters, awnings, systems, etc.) , small presses, | | |
| | - Signal | preprocessing for other controllers expansion depending on the applic | | | |
| LOGO! Modular basic variants | With inter | rface for connecting extension mod | dules | 6ED1 052-1 | 3/103 |
| LOGO! Modular pure variants | | grated interface for connecting exte | | 6ED1 052-2 | 3/104 |
| LOGO! Modular extension module | | ection to LOGO! Modular with digit nalog inputs | al inputs and out- | 6ED1 055-1 | 3/106 |
| LOGO! Modular communications r | | nunication between the LOGO! ma | ster and external | 6BK1 700-0 | 3/107 |
| LOGO!Contact | | g module for switching resistive loa | 6ED1 057-4 | 3/108 | |
| LOGO!Soft | Multiling | ual software for switching program | generation for | 6ED1 058-0 | 3/109 |
| AS-Interface | 200010 | | | | |
| System overview | transferre | nd analog signals at plant or machi ad by AS-Interface in binary form | | | 3/110 |
| | AS-Interf | ace is the universal interface betwe | en the higher-level | | |

AS-Interface is the universal interface between the higher-level control levels and simple binary actuators and sensors

General data

Overview

SIRIUS SC semiconductor switching devices

- Semiconductor relays
- Semiconductor contactors
- Function modules

SIRIUS SC - for almost unending activity

Conventional electromechanical switching devices are often overtaxed by the rise in the number of switching operations. A high switching frequency results in frequent failure and short replacement cycles. However, this does not have to be the case, because with the latest generation of our SIRIUS SC semiconductor switching devices we provide you with semiconductor relays and contactors with a particularly long service life – for almost unending activity even under the toughest conditions and under high mechanical load, but also in noise-sensitive areas.

Proved time and again in service

SIRIUS SC semiconductor switching devices have become firmly established in industrial use. They are used above all in applications where loads are switched frequently – mainly with resistive load controllers, with the control of electrical heat or the control of valves and motors in conveyor systems. In addition to its use in areas with high switching frequencies, thanks to its silent switching SIRIUS SC is also ideally suited to noise-sensitive areas such as offices or hospitals.

The most reliable solution for any application

Compared with mechanical switching devices, our SIRIUS SC semiconductor switching devices stand out because of their considerably higher service life. Thanks to the high product quality, their switching is extremely precise, reliable and above all insusceptible to faults. With its variable connection methods and a wide spread of control voltages, the SIRIUS SC family is universally applicable. Depending on the individual requirements of the application, our modular switching devices can also be quite easily expanded by the addition of standardized function modules.

Always on the sunny side with SIRIUS SC

Because SIRIUS SC offers even more:

- The space-saving and compact side-by-side mounting ensure reliable operation up to an ambient temperature of +60 °C.
- Thanks to fast project planning and the ease of installation and start-up you save not only time but also expense.

| Туре | Semiconduc | tor relays | Semicon- | Function mo | dules | | |
|---|-----------------------|------------|-----------------------|-------------|-------------------------|----------|-----------|
| | 22.5 mm | 45 mm | ductor contactors | Converters | onverters Load monitors | | Power con |
| | | | contactors | | Basic | Extended | trollers |
| Use | | | | | | | |
| Simple use of existing semiconductor relays | О | v | 0 | | | | |
| Complete "Ready to use" | О | 0 | ~ | | | | |
| Space-saving | ✓ | | ~ | ~ | V | | |
| Can be extended with modular function modules | ✓ | | ~ | | | | |
| Frequent switching and monitoring of loads and semiconductor relays/semiconductor contactors | ~ | | V | | ~ | ~ | |
| Monitoring of more than 6 partial loads | ~ | | ✓ | | | V | |
| Control of the heating power via an analog input | ✓ | | ~ | ~ | | | ~ |
| Power control | ✓ | | ~ | | | | v |
| Mounting | | | | | | | |
| Mounting on standard mounting rail or mounting plate | | | ✓ | | | | |
| Snapped directly onto semiconductor relay or contactor | | | | ~ | v - | v | ~ |
| For use with coolplate | ✓ | ~ | | | | | |
| Cable routing | | | | | | | |
| Connection of load circuit as for controlgear | ✓ | | ~ | | | | |
| Connection of load circuit from above | | ~ | | ~ | ✓ | V | v |
| | | | | | | | |

✓ Function is available ○ Function is possible

Benefits

- Considerable space savings thanks to a width of only 22.5 mm
- Variety of connection techniques: screw connection, springtype connection or ring terminal end, there is no problem - they are all finger-safe
- Flexible for all applications with function modules for retrofitting
- · Possibility of fuseless short-circuit resistant design

Advantages:

- Saves time and costs with fast installation and commissioning, short setting-up times and easy wiring
- Extremely long life, low maintenance, rugged and reliable
- \bullet Space-saving and safe thanks to side-by-side mounting up to an ambient temperature of +60 $^\circ\mathrm{C}$
- Modular design: standardized function modules and heat sinks can be used in conjunction with semiconductor relays to satisfy individual requirements
- Safety due to lifelong, vibration-resistant and shock-resistant spring-loaded terminal connection system even under tough conditions

Area of application

Applications

Example plastic machine industry:

Thanks to their high switching endurance, SIRIUS SC semiconductor switching devices are ideally suited for use in the control of electroheat. This is because the more precise the temperature regulation process has to be, the higher the switching frequency. The accurate regulation of electroheat is used for example in many processes in the plastic machine industry:

- Band heaters heat the extrudate to the correct temperature in plastic extruders
- Heat emitters heat plastic blanks to the correct temperature
- Heat drums dry plastic granules
- Heating channels keep molds at the correct temperature in order to manufacture different plastic parts without defects.

The powerful SIRIUS SC semiconductor relays and contactors can be used to control several heating loads at the same time. By using a load monitoring module the individual partial loads can easily be monitored, and in the event of a failure a signal is generated to be sent to the controller.

Protecting the semiconductor relays and semiconductor contactors with miniature circuit-breakers (B MCB)

Short-circuit protection and line protection with miniature circuitbreakers is easy to achieve with SIRIUS SC semiconductor relays and semiconductor contactors in comparison with designing load feeders with fuses. A special version of the semiconductor contactors can be protected against damage in the case of a short-circuit with a miniature circuit-breaker with type B tripping characteristic. This allows the low-cost and simple design of fuseless load feeders with full protection of the switching device.

Design

There is no typical design of a load feeder with semiconductor relays or semiconductor contactors; instead, the great variety of connection systems and control voltages offers universal application opportunities. SIRIUS SC semiconductor relays and semiconductor contactors can be installed in fuseless or fused feeders, as required.

There are special versions with which it is even possible to achieve short-circuit strength in a fuseless design.

General data

Functions

Connection

All SIRIUS SC semiconductor switching devices are characterized by the great variety of connection methods. You can choose between the following connection techniques:

SIGUT connection system

The SIGUT connection system is the standard among industrial switching devices. Open terminals and a plus-minus screw are just two features of this technology. Two conductors of up to 6 mm² can be connected in just one terminal. As a result, loads of up to 50 A can be connected.

Spring-loaded connection system

This innovative technology manages without any screw connection. This means that very high vibration resistance is achieved. Two conductors of up to 2.5 mm² can be connected to each terminal. As a result, loads of up to 20 A can be dealt with.

Ring terminal end connection

The ring terminal end connection is equipped with an M5 screw. Ring terminal ends of up to 25 mm² can be connected. In this way it is possible to connect even high powers with current intensities of up to 88 A safely. Finger safety is provided in this case too with a special cover.

Switching functions

In order to guarantee an optimized control method for different loads, the functionality of our semiconductor switching devices can be adapted accordingly.

The "**zero-point switching**" method has proved to be ideal for resistive loads, i.e. where the power semiconductor is activated at zero voltage.

For inductive loads, on the other hand, for example in the case of valves, it is better to go with "**instantaneous switching**". By distributing the ON point over the entire sine curve of the mains voltage, disturbances are reduced to a minimum.

Performance characteristics

The performance of the semiconductor switching devices is substantially determined by the type of power semiconductors used and the internal design. In the case of the SIRIUS SC semiconductor contactors and semiconductor relays, only thyristors are used in place of less powerful Triacs.

Two of the most important features of thyristors are the blocking voltage and the maximum load integral:

Blocking voltage

Thyristors with a high blocking voltage can also be operated without difficulty in power systems with high interference voltages. Separate protective measures, such as a protective circuit with a varistor, are not necessary in most cases.

With SIRIUS SC, for example, thyristors with 800 V blocking voltage are fitted for operation in power systems up to 230 V. Thyristors with up to 1600 V are used for power systems with higher voltages.

Maximum load integral

One of the purposes of specifying the maximum load integral (Pt) is to determine the rating of the short-circuit protection. Only a large power semiconductor with a correspondingly high Pt value can be given appropriate protection against destruction from a short-circuit by means of a protective device matched to the application. However, SIRIUS SC is also characterized by the optimum matching of the thyristors (Pt value) with the rated currents. The rated currents specified on the devices in conformance with EN 60947-4-3 were confirmed by extensive testing. Further information is available on the Internet at: www.siemens.de/siriussc

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General data

Further information

Notes on integration in the load feeders

The SIRIUS SC semiconductor switching devices are very easy to integrate into the load feeders thanks to their industrial connection technology and design.

Particular attention must however be paid to the circumstances of the installation and ambient conditions, as the performance of the semiconductor switching devices is largely dependent on these. Depending on the version, certain restrictions must be observed. Detailed information, for example in relation to semiconductor contactors about the minimum spacing and to semiconductor relays about the choice of heat sink, is given in the product data sheets and the technical specifications in the A&D Mall.

Despite the rugged power semiconductors that are used, semiconductor switching devices respond more sensitively to shortcircuits in the load feeder. Consequently, special precautions have to be taken against destruction, depending on the type of design.

Siemens generally recommends using SITOR semiconductor protection fuses. These fuses also provide protection against destruction in the event of a short-circuit even when the semiconductor contactors and semiconductor relays are fully utilized.

Alternatively, if there is lower loading, protection can also be provided by standard fuses or miniature circuit-breakers. This protection is achieved by overdimensioning the semiconductor switching devices accordingly. The technical specifications in the A&D Mall and the product data sheets contains details both about the semiconductor fuse protection itself and about use of the SIRIUS SC devices with conventional protection equipment.

The SIRIUS SC semiconductor switching devices are suitable for interference-free operation in industrial power systems without further measures. If they are used in public power systems, it may be necessary for conducted interference to be reduced by means of filters. This does not include the special type 3RF23 20-.CA.. "low noise" semiconductor contactors. These comply with the class B limit values up to a rated current of 16 A. If other versions are used, and at currents of over 16 A, standard filters can be used in order to comply with the limit values. The decisive factors when it comes to selecting the filters are essentially the current loading and the other parameters (operational voltage, design type, etc.) in the load feeder.

Suitable filters can be ordered from EPCOS AG (see Appendix -> External Partners). For more information go to www.epcos.com

Selection and ordering data

Accessories

| | Designation | Labeling area/color | DT | Order No. | PS* | Weight per PU approx. |
|------------------------------------|--|--------------------------------|----|----------------|---------------|-----------------------------|
| | | $W \times H$ mm × mm | | | | kg |
| Blank identification pla | tes | | | | | |
| | Item code labels for "SIRIUS" ¹⁾ | 10×7 pastel turquoise | D | 3RT19 00-1SB10 | 816 units | 0.030 |
| | | 20×7 pastel turquoise | А | 3RT19 00-1SB20 | 340 units | 0.067 |
| | "SIRIUS" labels for sticking | 19 × 6 pastel turquoise | D | 3RT19 00-1SB60 | 4700 units | 0.003 |
| <u>∐∐∐∐</u> iģ Item code labels | | 19×6 zinc yellow | С | 3RT19 00-1SD60 | 4700 units | 0.003 |

1 frame = 20 labels

 Computer labeling system for individual labeling of item code labels available from:

murrplastik Systemtechnik GmbH (see Appendix -> External Partners).

Overview

Semiconductor relays

SIRIUS SC semiconductor relays are suitable for surface mounting on existing cooling surfaces. Installation is quick and easy, involving just two screws. The special technology of the power semiconductor ensures there is excellent thermal contact with the heat sink. Depending on the nature of the heat sink, the capacity reaches up to 88 A on resistive loads. The 3RF21 semiconductor relays can be expanded with various function modules to adapt them to individual applications.

The semiconductor relays are available in 2 different widths:

- 3RF21 semiconductor relay with a width of 22.5 mm
- 3RF20 semiconductor relay with a width of 45 mm

Both variants are only available in the "zero-point switching" version. This standard version is ideally suited for operation with resistive loads.

General data

Further information

Notes on selection

These notes are intended for general orientation and will no doubt be sufficient for most applications. If the installation conditions differ significantly from the examples described here, you can contact our Technical Assistance team for further help.

| Telephone: | +49 9131 7 43833 |
|------------|--------------------------------------|
| Fax: | +49 9131 7 42899 |
| e-mail: | nst.technical-assistance@siemens.com |

For more information on the Internet go to www.siemens.de/lowvoltage/technical-assistance

Selecting semiconductor relays

When selecting semiconductor relays, in addition to information about the power system, the load and the ambient conditions it is also necessary to know details of the planned design. The semiconductor relays can only conform to their specific technical specifications if they are mounted with appropriate care on an adequately dimensioned heat sink. The following procedure is recommended:

- Determine the rated current of the load and the mains voltage
- Select the relay design and choose a semiconductor relay with higher rated current than the load
- Determine the thermal resistance of the proposed heat sink
- Check the correct relay size with the aid of the diagrams

For more information on the Internet go to www.siemens.com/siriussc

22.5 mm semiconductor relays

Overview

22.5 mm semiconductor relays

With its compact design, which stays the same even at currents of up to 88 Å, the 3RF21 semiconductor relay is the ultimate in space-saving construction, at a width of 22.5 mm. The logical connection arrangement, with the power infeed from above and connection of the load from below, ensures tidy installation in the control cabinet.

Technical specifications

| Туре | | 3RF211 | 3RF212 | 3RF213 |
|--|--|---|--|---|
| General data | | | | |
| Ambient temperature during operation, derating from 40 °C when stored | °C °C | -25 +60 -55 +80 | | |
| Site altitude | m | 0 1000; derating from 1000 | | |
| Shock resistance acc. to IEC 60068-2-27 | g/ms | 15/11 | | |
| Vibration resistance acc. to IEC 60068-2-6 | g | 2 | | |
| Degree of protection | | IP20 | | |
| Electromagnetic compatibility (EMC) | | | | |
| Emitted interference • Conducted interference voltage acc. to IEC 60947-4-3 • Emitted, high-frequency interference voltage acc. to IEC 60947-4-3 | | Class A for industrial applications Class A for industrial applications | | |
| Noise immunity • Electrostatic discharge acc. to IEC 61000-4-2 (corresponds to degree of severity 3) • Induced RF fields acc. to IEC 61000-4-6 • Burst acc. to IEC 61000-4-4 • Surge acc. to IEC 61000-4-5 | kV MHz kV kV | Contact discharge 4; air discharg 0.15 80; 140 dBµV; behavior cr 2/5.0 kHz; behavior criterion 1 Conductor - ground 2; conductor | | |
| Connection technique | | Screw-type connection | Spring-loaded connection | Ring cable connection |
| Main contact connection Conductor cross-section Solid Finely stranded with end sleeve Finely stranded without end sleeves Solid or stranded AWG conductors Insulation stripping length Terminal screw • Tightening torque Cable lug • DIN • JIS | mm ² mm ² AWG mm Ib.in | 2 × (1.5 2.5), 2 × (2.5 6) 2 × (1.5 2.5), 2 × (2.5 6), 1 × 10 2 × (14 10) 10 M 4 2 2.5 18 22 - | 2 × (0,5 2.5) 2 × (0.5 1.5) 2 × (0.5 2.5) 2 × (18 14) 10 - - | - - - - - - - - - - - - - - - - - - - |
| Auxiliary/control contact connections Conductor cross-section Insulation stripping length Terminal screw • Tightening torque | mm ² AWG mm Nm Ib.in | 1x (0.5 2.5); 2x (0.5 1) 20 12 7 M 3 0.5 0.6 4.5 5.3 | 0.5 1.5 20 12 10 - - | 1x (0.5 2.5); 2x (0.5 1) 20 12 7 M 3 0.5 0.6 4.5 5.3 |
| _ | | | | |

| Туре | | 3RF212 | 3RF214 | 3RF216 |
|--|--------------|------------------------------|---------|---------|
| Main circuit | | | | |
| Rated operational voltage U _e • Tolerance • Rated frequency | V % Hz | 24 230 -15 / +10 50/60 | 230 460 | 400 600 |
| Rated insulation voltage U _i | V | 600 | | |
| Blocking voltage | V | 800 | 1200 | 1600 |
| Rate of voltage rise | V/µs | 1000 | | |

22.5 mm semiconductor relays

| Order No. | / _{max} 1) at R _{thha} / | T _u = 40 °C | U | 60947-4-3 T _u = 40 °C | <i>l_e</i> to UL at R _{thha} | /CSA / <i>T</i> _u = 50 °C | Power loss for <i>I_{max}</i> | Minimum load current | Leakage current |
|--|---|------------------------|----------------|-------------------------------------|--|---|--|-------------------------|-----------------|
| | A | K/W | А | K/W | A | K/W | W | A | mA |
| Main circuit | | | | | | | | | |
| 3RF21 20 | 20 | 2.0 | 20 | 2.0 | 20 | 1.7 | 28.6 | 0.5 | 10 |
| 3RF21 30-1 | 30 | 1.1 | 30 | 1.1 | 30 | 0.88 | 44.2 | 0.5 | 10 |
| 3RF21 50-1 3RF21 50-2 3RF21 50-3 | 50 50 50 | 0.68 0.68 0.68 | 50 20 50 | 0.68 4.2 0.68 | 50 20 50 | 0.53 3.3 0.53 | 66 66 66 | 0.5 0.5 0.5 | 10 10 10 |
| 3RF21 70-1 | 70 | 0.4 | 50 | 0.95 | 50 | 0.8 | 94 | 0.5 | 10 |
| 3RF21 90-1 3RF21 90-2 3RF21 90-3 | 88 88 88 | 0.33 0.33 0.33 | 50 20 88 | 1.25 5.0 0.33 | 50 20 83 | 1.02 4.0 0.29 | 118 118 118 | 0.5 0.5 0.5 | 10 10 10 |

 I_{max} provides information about the performance of the semiconductor relay. The actual permitted operational current I_e can be smaller depending on the connection method and cooling conditions.

| Order No. | Rated impulse withstand capacity <i>I</i> tsm | Pt value |
|------------------------------|---|------------------|
| | A | A ² s |
| Main circuit | | |
| 3RF21 20 | 200 | 200 |
| 3RF21 30AA.2 | 300 | 450 |
| 3RF21 30AA.4 3RF21 30AA.6 | 300 400 | 450 800 |
| 3RF21 50 | 600 | 1800 |
| 3RF21 70AA.2 | 1200 | 7200 |
| 3RF21 70AA.4 3RF21 70AA.6 | 1200 1150 | 7200 6600 |
| 3RF21 90 | 1150 | 6600 |

| Туре | | 3RF210 | 3RF212 |
|---|----------|--|--|
| Control circuit | | | |
| Method of operation | | DC operation | AC operation |
| Rated control supply voltage Us | V | 24 to EN 61131-2 | 110 230 |
| Max. rated control voltage | V | 30 | 253 |
| Rated control current at U _s | mA | 15 | 6 |
| Rated frequency of the control supply voltage | Hz | - | 50/60 |
| Response voltage for tripping current | V mA | 15 2 | 90 2 |
| Drop-out voltage | V | 5 | 40 |
| Operating times closing time opening time | ms ms | 1 additionally max. one half-wave 1 additionally max. one half-wave | 40 additionally max. one half-wave 40 additionally max. one half-wave |

22.5 mm semiconductor relays

| | ccessories | | |
|--|---|--|--|
| | onverters | Load monitors | |
| | | Basic | Extended |
| | | | |
| Type current = 20 A 3RF21 2102 3R | RF29 00-0EA18 | 3RF29 20-0FA08 | 3RF29 20-0GA13 |
| | RF29 00-0EA18 | 3RF29 20-0FA08 | 3RF29 20-0GA16 |
| 3RF21 2122 - 3RF21 2124 - | | | 3RF29 20-0GA33 3RF29 20-0GA36 |
| 3RF21 2204 3R | RF29 00-0EA18 RF29 00-0EA18 | - - | |
| 3RF21 2304 3R | RF29 00-0EA18 RF29 00-0EA18 | | 3RF29 20-0GA13 3RF29 20-0GA16 |
| 3RF21 2322 - 3RF21 2324 - | | - | 3RF29 20-0GA33 3RF29 20-0GA36 |
| Type current = 30 A | | | |
| 3RF21 3104 3R | RE29 00-0EA18 RE29 00-0EA18 RE29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 50-0GA13 3RF29 50-0GA16 3RF29 50-0GA16 |
| 3RF21 3122 - 3RF21 3124 - 3RF21 3126 - | | - - - | 3RF29 50-0GA33 3RF29 50-0GA36 3RF29 50-0GA36 |
| Type current = 50 A | | | |
| 3RF21 5104 3R | RF29 00-0EA18 RF29 00-0EA18 RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 50-0GA13 3RF29 50-0GA16 3RF29 50-0GA16 |
| 3RF21 5122 - 3RF21 5124 - 3RF21 5126 - | | - | 3RF29 50-0GA33 3RF29 50-0GA36 3RF29 50-0GA36 |
| 3RF21 5204 3R | RF29 00-0EA18 RF29 00-0EA18 RF29 00-0EA18 | - - - | - - - |
| 3RF21 5306 3R | RF29 00-0EA18 RF29 00-0EA18 RF29 00-0EA18 | - | 3RF29 50-0GA13 3RF29 50-0GA16 3RF29 50-0GA16 |
| 3RF21 5322 - 3RF21 5324 - 3RF21 5326 - | | - | 3RF29 50-0GA33 3RF29 50-0GA36 3RF29 50-0GA36 |
| Type current = 70 A | | | |
| 3RF21 7104 3R | RE29 00-0EA18 RE29 00-0EA18 RE29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 90-0GA13 3RF29 90-0GA16 3RF29 90-0GA16 |
| 3RF21 7122 - 3RF21 7124 - 3RF21 7126 - | | - - | 3RF29 90-0GA33 3RF29 90-0GA36 3RF29 90-0GA36 |
| Type current = 90 A | | | |
| 3RF21 9104 3R | RF29 00-0EA18 RF29 00-0EA18 RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 90-0GA13 3RF29 90-0GA16 3RF29 90-0GA16 |
| 3RF21 9122 - 3RF21 9124 - 3RF21 9126 - | | | 3RF29 90-0GA33 3RF29 90-0GA36 3RF29 90-0GA36 |
| 3RF21 9206 3R | RF29 00-0EA18 RF29 00-0EA18 RF29 00-0EA18 | - | |
| 3RF21 9304 3R | RF29 00-0EA18 RF29 00-0EA18 RF29 00-0EA18 | - | 3RF29 90-0GA13 3RF29 90-0GA16 3RF29 90-0GA16 |
| 3RF21 9322 - 3RF21 9326 - 3RF21 9324 - | | - - | 3RF29 90-0GA33 3RF29 90-0GA36 3RF29 90-0GA36 |

22.5 mm semiconductor relays

Fused design with semiconductor protection (similar to type of coordination "2")¹⁾

The semiconductor protection for the SIRIUS SC controlgear can be implemented with different protective devices. This allows protection by means of LV HRC fuses of operational class gL/gG or miniature circuit-breakers. Siemens recommends the use of special SITOR semiconductor fuses. The table below lists the maximum permissible fuses for each SIRIUS SC controlgear. If a fuse is used with a higher rated current than specified, semiconductor protection is no longer guaranteed. However, smaller fuses with a lower rated current for the load can be used without problems.

For protective devices with operational class gL/gG and for 3NE1 SITOR full range fuses, the minimum cross-sections for the conductors to be protected must be taken into account.

| Order No. | All-range fuse LV design gR/SITOR | Semiconducto Cylindrical de | or protection fus sign | se | LV design | e protection fus Cylindrical de | protection fuse Cylindrical design | | | |
|---|---|----------------------------------|----------------------------------|----------------------------------|------------------------------------|------------------------------------|---------------------------------------|-------------------------------|-------------------------|--|
| | 3NE1 | 10 × 38 mm aR/SITOR 3NC1 0 | 14 × 51 mm aR/SITOR 3NC1 4 | 22 × 58 mm aR/SITOR 3NC2 2 | gL/gG/3NA 10 × 38 mm gL/gG/3NW | | 14 × 51 mm gL/gG/3NW | 22 × 58 mm gL/gG/3NW | 5SB | |
| | | | | | | | | | | |
| 3RF21 22 3RF21 24 | 3NE1 814-0 3NE1 813-0 | 3NC1 020 3NC1 016 | 3NC1 420 3NC1 420 | 3NC2 220 3NC2 220 | 3NA2 803 3NA2 801 | 3NW6 001-1 - | 3NW6 101-1 3NW6 101-1 | - | 5SB1 71 5SB1 41 | |
| 3RF21 32 3RF21 34 3RF21 36 | 3NE1 815-0 3NE1 815-0 3NE1 815-0 | 3NC1 032 3NC1 025 3NC1 032 | 3NC1 432 3NC1 432 3NC1 432 | 3NC2 232 3NC2 232 3NC2 232 | 3NA2 803 3NA2 803 3NA2 803-6 | - - | 3NW6 103-1 3NW6 101-1 - | - - | 5SB3 11 5SB1 71 - | |
| 3RF21 52 3RF21 54 3RF21 56 | 3NE1 817-0 3NE1 802-0 3NE1 803-0 | - | 3NC1 450 3NC1 450 3NC1 450 | 3NC2 250 3NC2 250 3NC2 250 | 3NA2 810 3NA2 807 3NA2 807-6 | - - | 3NW6 107-1 - - | 3NW6 207-1 3NW6 205-1 - | 5SB3 21 5SB3 11 - | |
| 3RF21 72 ²⁾ 3RF21 74 ²⁾ 3RF21 76 ²⁾ | 3NE1 820-0 3NE1 020-2 3NE1 020-2 | - | - | 3NC2 280 3NC2 280 3NC2 280 | 3NA2 817 3NA2 812 3NA2 812-6 | - - | | 3NW6 217-1 3NW6 212-1 - | 5SB3 31 5SB3 21 - | |
| 3RF21 92 ²⁾ 3RF21 94 ²⁾ 3RF21 96 ²⁾ | 3NE1 021-2 3NE1 021-2 3NE1 020-2 | - | - | 3NC2 200 3NC2 280 3NC2 280 | 3NA2 817 3NA2 812 3NA2 812-6 | - - | | 3NW6 217-1 3NW5 212-1 - | 5SB3 31 5SB3 21 - | |

1) Type of coordination "2" acc. to EN 60947-4-1:

In the event of a short-circuit, the controlgear in the load feeder must not endanger persons or the installation. They must be suitable for further operation. For fused configurations, the protective device must be replaced.

2) These versions can also be protected against short-circuit with miniature circuit-breakers as described on page 3/16.

22.5 mm semiconductor relays

Selection and ordering data







| | | | | | 3RF21 20-1AA02 | | | | 3RF21 20-2AA02 | | | | 3RF21 20-3AA02 | | |
|-----------------------|-----------------|--------------|----------|--------|-----------------------------------|---------------------|-----------------------------|------|---|--------|-----------------------------|----|-----------------------|--------|-----------------------------|
| Type current 1) | able p curre | nt and | or type | | Screw connection ²⁾ | PS* | Weight per PU approx. | DT | Spring-loaded connection ³⁾ | PS* | Weight per PU approx. | DT | Ring cable connection | PS* | Weight per PU approx. |
| A | kW | kW | kW | | Order No. | | kg | | Order No. | | kg | | Order No. | | kg |
| Zero-p | point | switcl | hing, r | ated | l operational vol | tage <i>U</i> e | = 24 V t | o 23 | 0 V | | | | | | |
| 20 30 | 2.3 3.5 | 4.6 6.9 | - | A A | 3RF21 20-1AA□2 3RF21 30-1AA□2 | | 0.052 0.052 | В | 3RF21 20-2AA⊟2 | 1 unit | 0.052 | В | 3RF21 20-3AA□2 | 1 unit | 0.052 |
| 50 70 | 5.8 8.1 | 11.5 16.1 | - | A | 3RF21 50-1AA□2 3RF21 70-1AA□2 | 1 unit | 0.052 | В | 3RF21 50-2AA□2 - | 1 unit | 0.052 | В | 3RF21 50-3AA□2 - | 1 unit | 0.052 |
| 88 | 10.4 | 20.7 | - | A | 3RF21 90-1AA□2 | | 0.052 | В | 3RF21 90-2AA□2 | 1 unit | 0.052 | В | 3RF21 90-3AA□2 | 1 unit | 0.052 |
| Zero-p | boint | switcl | hing, r | ated | l operational vol | tage U _e | = 230 V | to 4 | 60 V | | | | | | |
| 20 30 | 2 | 4.6 6.9 | 8 12 | A A | 3RF21 20-1AA□4 3RF21 30-1AA□4 | | 0.052 0.052 | В | 3RF21 20-2AA⊟4 - | 1 unit | 0.052 | В | 3RF21 20-3AA⊟4 - | 1 unit | 0.052 |
| 50 70 | - | 11.5 16.1 | 20 28 | A A | 3RF21 50-1AA□4 3RF21 70-1AA□4 | | 0.052 0.052 | В | 3RF21 50-2AA□4 - | 1 unit | 0.052 | В | 3RF21 50-3AA□4 - | 1 unit | 0.052 |
| 88 | - | 20.7 | 36 | А | 3RF21 90-1AA□4 | 1 unit | 0.052 | В | 3RF21 90-2AA□4 | 1 unit | 0.052 | В | 3RF21 90-3AA□4 | 1 unit | 0.052 |
| Zero-p | point | switcl | hing, r | ated | l operational vol | tage <i>U</i> e | = 400 V | to 6 | 00 V | | | | | | |
| 30 50 | - | - | 12 20 | B B | 3RF21 30-1AA□6 3RF21 50-1AA□6 | 1 unit | 0.052 0.052 | В | - 3RF21 50-2AA□6 | 1 unit | 0.052 | В | - 3RF21 50-3AA□6 | 1 unit | 0.052 |
| 70 88 | - | - | 28 36 | B B | 3RF21 70-1AAD6 3RF21 90-1AAD6 | | 0.052 0.052 | В | - 3RF21 90-2AA⊟6 | 1 unit | 0.052 | В | - 3RF21 90-3AA⊟6 | 1 unit | 0.052 |
| Order N rated c | | | | ge U, | | | | | | | | | | | |
| DC 24 \ AC 110 | V acc. | to EN 6 | | | 02 | | | | 0 | | | | 0 | | |

Other rated control supply voltages on request.

1) The type current provides information about the performance of the semiconductor relay. The actual permitted operational current Ie can be smaller depending on the connection method and cooling conditions.

2) Please note that this version can only be used for a rated current of up to 50 A and a conductor cross-section of 10 $\rm mm^2.$

3) Please note that this version can only be used for a rated current of up to 20 A and a conductor cross-section of 2.5 $\rm mm^2.$

| | Version | DT | Order No. | PS* | Weight per PU approx. |
|-------------|--|----|----------------|-------------|-----------------------------|
| Accessories | | | | | kg |
| Accessones | Screwdriver for spring-loaded connection system | A | 8WA2 880 | 1 unit | 0.034 |
| - | Terminal cover for 3RF21 semiconductor relays and 3RF23 semiconductor contactors with ring terminal end (after simple adaptation, this terminal cover can also be used for screw connection). | A | 3RF29 00-3PA88 | 10 units | 0.010 |

45 mm semiconductor relays

Overview

45 mm semiconductor relays

The semiconductor relays with a width of 45 mm provide for connection of the power supply lead and the load from above. This makes it easy to replace existing semiconductor relays in existing arrangements. The connection of the control cable also saves space in much the same way as the 22.5 mm design, as it is simply plugged on.

Technical specifications

| Туре | | 3RF20 |
|---|--|---|
| General data | | |
| Ambient temperature during operation, derating at 40 °C when stored | °C °C | -25 +60 -55 +80 |
| Site altitude | m | 0 1000; derating from 1000 |
| Shock resistance acc. to IEC 60068-2-27 | g/ms | 15/11 |
| Vibration resistance acc. to IEC 60068-2-6 | g | 2 |
| Degree of protection | | IP20 |
| Electromagnetic compatibility (EMC) Emitted interference • Conducted interference voltage IEC acc. to 60947-4-3 • Emitted, high-frequency interference voltage acc. to IEC 60947-4-3 | | Class A for industrial applications Class A for industrial applications |
| Noise immunity • Electrostatic discharge acc. to IEC 61000-4-2 (corresponds to degree of severity 3) • Induced RF fields acc. to IEC 61000-4-6 • Burst acc. to IEC 61000-4-4 • Surge acc. to IEC 61000-4-5 | kV MHz kV kV | Contact discharge 4; air discharge 8; behavior criterion 2 0.15 80; 140 dBµV; behavior criterion 1 2/5.0 kHz; behavior criterion 1 Conductor - ground 2; conductor - conductor 1; behavior criterion 2 |
| Connection, main contacts, screw con- nection Conductor cross-section Solid Finely stranded with end sleeve Solid or stranded AWG conductors Insulation stripping length Terminal screw • Tightening torque | mm ² mm ² AWG mm Nm Ib.in | 2 × (1.5 2.5); 2 × (2.5 6) 2 × (1.5 2.5); 2 × (2.5 6); 1 × 10 2 × (14 10) 10 M 4 2 2.5 18 22 |
| Connection, auxiliary/control contacts, screw connection Conductor cross-section Insulation stripping length Terminal screw • Tightening torque | mm ² mm Nm Ib.in | 1x (0.5 2.5); 2x (0.5 1.0); AWG 20 12 7 M 3 0.5 0.6 4.5 5.3 |

| Туре | | 3RF20 .0-1AA.2 | 3RF20 .0-1AA.4 | 3RF20 .0-1AA.6 |
|--|--------------|----------------------------|----------------|----------------|
| Main circuit | | | | |
| Rated operational voltage U _e • Tolerance • Rated frequency | V % Hz | 24 230 -15/+10 50/60 | 230 460 | 400 600 |
| Rated insulation voltage U _i | V | 600 | | |
| Blocking voltage | V | 800 | 1200 | 1600 |
| Rage of voltage rise | V/µs | 1000 | | |

45 mm semiconductor relays

| Order No. | THOM | | U | U C | | /CSA / <i>T</i> u = 50 °C | Power loss for I _{max} | Minimum load current | Leakage current |
|--------------|------|------|----|------|----|------------------------------|------------------------------------|----------------------|-----------------|
| | A | K/W | A | K/W | A | K/W | W | A | mA |
| Main circuit | | | | | | | | | |
| 3RF20 20-1AA | 20 | 2.0 | 20 | 2.0 | 20 | 1.7 | 28.6 | 0.5 | 10 |
| 3RF20 30-1AA | 30 | 1.1 | 30 | 1.1 | 30 | 0.88 | 44.2 | 0.5 | 10 |
| 3RF20 50-1AA | 50 | 0.68 | 50 | 0.68 | 50 | 0.53 | 66 | 0.5 | 10 |
| 3RF20 70-1AA | 70 | 0.4 | 50 | 0.95 | 50 | 0.8 | 94 | 0.5 | 10 |
| 3RF20 90-1AA | 88 | 0.33 | 50 | 1.25 | 50 | 1.02 | 118 | 0.5 | 10 |

1) $I_{\rm max}$ provides information about the performance of the semiconductor relay. The actual permitted operational current $I_{\rm e}$ can be smaller depending on the connection method and cooling conditions.

| Order No. | Rated impulse withstand capacity <i>I</i> tsm | <i>Pt</i> value |
|----------------------------------|---|------------------|
| | A | A ² s |
| Main circuit | | |
| 3RF20 20-1AA | 200 | 200 |
| 3RF20 30-1AA.2 | 300 | 450 |
| 3RF20 30-1AA.4 3RF20 30-1AA.6 | 300 400 | 450 800 |
| 3RF20 50-1AA | 600 | 1800 |
| 3RF20 70-1AA.2 | 1200 | 7200 |
| 3RF20 70-1AA.4 3RF20 70-1AA.6 | 1200 1150 | 7200 6600 |
| 3RF20 90-1AA | 1150 | 6600 |

| Туре | | 3RF20 .0-1AA0. | 3RF20 .0-1AA2. |
|---|----------|--|--|
| Control circuit | | | |
| Method of operation | | DC operation | AC operation |
| Rated control supply voltage Us | V | 24 acc. to EN 61131-2 | 110 230 |
| Max. rated control voltage | V | 30 | 253 |
| Rated control current at U _s | mA | 15 | 6 |
| Rated frequency of the control supply voltage | Hz | - | 50/60 |
| Response voltage for tripping current | V mA | 15 2 | 90 2 |
| Drop-out voltage | V | 5 | 40 |
| Operating times closing time opening time | ms ms | 1 additional max. one half-wave 1 additional max. one half-wave | 40 additional max. one half-wave 40 additional max. one half-wave |

45 mm semiconductor relays

Fused design with semiconductor protection (similar to type of coordination "2")¹⁾

The semiconductor protection for the SIRIUS SC control gear can be used with different protective devices. This allows protection by means of LV HRC fuses of operational class gL/gG or miniature circuit-breakers. Siemens recommends the use of special SITOR semiconductor fuses. The table below lists the maximum permissible fuses for each SIRIUS SC controlgear. If a fuse is used with a higher rated current than specified, semiconductor protection is no longer guaranteed. However, smaller fuses with a lower rated current for the load can be used without problems.

For protective devices with operational class gL/gG and for SITOR full range fuses 3NE1, the minimum cross-sections for the conductor to be connected must be taken into account.

| Order No. | All-range fuse LV design gR/SITOR 3NE1 | Semiconducto Cylindrical de 10 × 38 mm aR/SITOR 3NC1 0 | or protection fus sign 14 × 51 mm aR/SITOR 3NC1 4 | se 22 × 58 mm aR/SITOR 3NC2 2 | Cable and line LV design gL/gG/3NA | e protection fuse Cylindrical de 10 × 38 mm gL/gG 3NW | | 22 × 58 mm gL/gG 3NW | DIAZED quick 5SB |
|---|---|--|---|--|--|--|-------------------------------|-------------------------------|-------------------------|
| 3RF20 20-1AA.2 3RF20 20-1AA.4 | 3NE1 814-0 3NE1 813-0 | 3NC1 020 3NC1 016 | 3NC1 420 3NC1 420 | 3NC2 220 3NC2 220 | 3NA2 803 3NA2 801 | 3NW6 001-1 - | 3NW6 101-1 3NW6 101-1 | - | 5SB1 71 5SB1 41 |
| 3RF20 30-1AA.2 3RF20 30-1AA.4 3RF20 30-1AA.6 | 3NE1 815-0 3NE1 815-0 3NE1 815-0 | 3NC1 032 3NC1 025 3NC1 032 | 3NC1 432 3NC1 432 3NC1 432 | 3NC2 232 3NC2 232 3NC2 232 | 3NA2 803 3NA2 803 3NA2 803-6 | - - | 3NW6 103-1 3NW6 101-1 - | - - | 5SB3 11 5SB1 71 - |
| 3RF20 50-1AA.2 3RF20 50-1AA.4 3RF20 50-1AA.6 | 3NE1 817-0 3NE1 802-0 3NE1 803-0 | - - | 3NC1 450 3NC1 450 3NC1 450 | 3NC2 250 3NC2 250 3NC2 250 | 3NA2 810 3NA2 807 3NA2 807-6 | - - | 3NW6 107-1 - - | 3NW6 207-1 3NW6 205-1 - | 5SB3 21 5SB3 11 - |
| 3RF20 70-1AA.2 ²⁾ 3RF20 70-1AA.4 ²⁾ 3RF20 70-1AA.6 ²⁾ | 3NE1 820-0 3NE1 020-2 3NE1 020-2 | - - | - - | 3NC2 280 3NC2 280 3NC2 280 | 3NA2 817 3NA2 812 3NA2 812-6 | - - | - - | 3NW6 217-1 3NW6 212-1 - | 5SB3 31 5SB3 21 - |
| 3RF20 90-1AA.2 ²⁾ 3RF20 90-1AA.4 ²⁾ 3RF20 90-1AA.6 ²⁾ | 3NE1 021-2 3NE1 021-2 3NE1 020-2 | - - - | - - | 3NC2 200 3NC2 280 3NC2 280 | 3NA2 817 3NA2 812 3NA2 812-6 | - - | - - | 3NW6 217-1 3NW6 212-1 - | 5SB3 31 5SB3 21 - |

 Type of coordination "2" acc. to EN 60947-4-1: In the event of a short-circuit, the control gear in the load feeder must not endanger persons or the installation. They must be suitable for further operation. For fused configurations, the protective device must be replaced.

2) These versions can also be protected against short-circuit with miniature circuit-breakers as described on page 3/16.

| Selection and orderi | ng data | | | | | | | |
|--|---|------------------------------------|------------------------------------|--|------------------|--|----------------------------|---|
| | Type current ¹⁾ | Maximum achievabl 115 V | le power for type curre 230 V | ent and <i>U</i> _e = 400 V | DT | Order No. ²⁾ | PS* | Weight per PU approx. |
| | A | kW | kW | kW | | | | kg |
| Zero-point switching | , rated operational | voltage U _e = 24 V | to 230 V | | | | | |
| | 20 30 50 70 88 | 2.3 3.5 5.8 8.1 10.4 | 4.6 6.9 11.5 16.1 20.7 | - | AAAAA | 3RF20 20-1AA 2 3RF20 30-1AA 2 3RF20 50-1AA 2 3RF20 70-1AA 2 3RF20 90-1AA 2 | 1 unit 1 unit 1 unit | 0.062 0.062 0.062 0.062 0.062 |
| 3RF20 20-1AA02 Zero-point switching | , rated operational | voltage U _e = 230 \ | / to 460 V | | | | | |
| | 20 30 50 70 88 | - - - - | 4.6 6.9 11.5 16.1 20.7 | 8 12 20 28 36 | A A A A | 3RF20 20-1AA□4 3RF20 30-1AA□4 3RF20 50-1AA□4 3RF20 70-1AA□4 3RF20 90-1AA□4 | 1 unit 1 unit | 0.062 0.062 0.062 0.062 0.062 |
| Zero-point switching | , rated operational | voltage $U_{\rm e} = 400$ V | / to 600 V | | | | | |
| | 30 50 70 88 | - | - | 12 20 28 36 | B B B B | 3RF20 30-1AA□6 3RF20 50-1AA□6 3RF20 70-1AA□6 3RF20 90-1AA□6 | 1 unit 1 unit | 0.062 0.062 0.062 0.062 |
| | Order No. extension DC 24 V acc. to EN 6 AC 110 V 230 V | n for rated control sup 51131-2 | pply voltage <i>U</i> s | | | 0 | | |
| Other rated control su | pply voltages on re | equest. | | | | _ | | |

 The type current provides information about the performance of the semiconductor relay. The actual permitted operational current l_e can be smaller depending on the connection method and cooling conditions.

2) Please note that this version can only be used for a rated current of up to 50 A and a conductor cross-section of 10 $\rm mm^2.$

SIRIUS SC semiconductor contactors

Overview

The complete self-contained units consist of a semiconductor relay plus optimized heat sink, and are therefore ready to use. They offer defined rated currents to make selection as easy as possible. Depending on the version, current intensities of up to 88 A are achieved. Like all of our semiconductor switching devices, one of their particular advantages is their compact and space-saving design. With their insulated mounting foot they can easily be snapped onto a standard mounting rail, or they can be mounted on carrier plates with fixing screws. This insulation enables them to be used in circuits with protective extra-low voltage (PELV) or safety extra-low voltage (SELV) in building engineering. For other applications, such as for extended personal safety, the heat sink can be grounded through a screw connection

Version for resistive loads, "zero-point switching"

This standard version is often used for switching space heaters on and off.

Version for inductive loads, "instantaneous switching"

In this version the semiconductor contactor is specifically matched to inductive loads. Whether it is a matter of frequent actuation of the valves in a filling plant or starting and stopping small drives in packet distribution systems, operation is carried out safely and noiselessly.

Special "low noise" version

Thanks to a special control circuit, this special design can be used in public networks up to 16 A without any additional measures such as interference suppressor filters. As a result it conforms to limit value curve class B in accordance with EN 60947-4-3 in terms of emitted interference.

Special "short-circuit" version

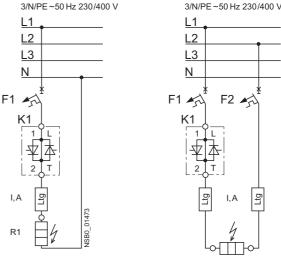
Skilful matching of the power semiconductor with the performance of the semiconductor contactor means that "short-circuit strength" can be achieved with a standard miniature circuitbreaker. In combination with a B-type MCB or a conventional fuse, the result is a short-circuit resistant feeder.

In order to achieve problem-free short-circuit protection by means of miniature circuit-breakers, however, certain boundary conditions must be observed. As the magnitude and duration of the short-circuit current are determined not only by the short-circuit breaking response of the miniature circuit-breaker but also the properties of the wiring system, such as the internal resistance of the input to the network and damping by switching devices and cables, particular attention must also be paid to these parameters. The necessary cable lengths are therefore shown for the main factor, the conductor resistance, in the table below

The following miniature circuit-breakers with a B characteristic and 10 kA breaking capacity protect the 3RF2320-.DA.. semiconductor contactors in the event of short-circuits on the load and the specified conductor cross-sections and lengths:

| Rated current of miniature circuit- breakers | Example of type | Max. conductor cross-section | Min. cable length from contactor to load |
|--|--------------------|------------------------------------|---|
| 6 A | 5SY4 106-6 | 1 mm ² | 5 m |
| 10 A | 5SY4 110-6 | 1.5 mm ² | 8 m |
| 16 A | 5SY4 116-6 | 1.5 mm ² | 12 m |
| 16 A | 5SY4 116-6 | 2.5 mm ² | 20 m |
| 20 A | 5SY4 120-6 | 2.5 mm ² | 20 m |

3/N/PE~50 Hz 230/400 V



The setup and installation above can also be used for the semiconductor relays with a $l^2 t$ value of at least 6600 A²s

Technical specifications

| Order No. | | 3RF23A | 3RF23B | 3RF23C | 3RF23D |
|---|-----------------------|---------------------------------|---|---|--------|
| General data | | | | | |
| Ambient temperature during operation, derating at 40 °C when stored | °C °C | -25 +60 -55 +80 | in a frame 1000 | | |
| Site altitude | m | 0 1000; derat | ing from 1000 | | |
| Shock resistance acc. to IEC 60068-2-27 | g/ms | 15/11 | | | |
| Vibration resistance acc. to IEC 60068-2-6 | g | 2 | | | |
| Degree of protection | | IP20 | | | |
| Electromagnetic compatibility (EMC) | | | | | |
| Emitted interference acc. to IEC 60947-4-3 Conducted interference voltage Emitted high-frequency interference voltage | | Class A for indu | strial applications | Class A for industrial applications; Class B for resi- dential/business/ commercial areas up to 16 A, AC51 Low Noise | |
| Noise immunity • Electrostatic discharge acc. to IEC 61000-4-2 (corresponds to degree of severity 3) • Induced RF fields acc. to IEC 61000-4-6 • Burst acc. to IEC 61000-4-4 • Surge acc. to IEC 61000-4-5 | kV MHz kV kV | 0.15 80; 140 2/5.0 kHz; beha | ge 4; air discharge dBµV; behavior crite vior criterion 1 und 2; conductor - | erion 1 | |

SIRIUS SC semiconductor contactors

| Order No. | | 3RF231 | 3RF232 | 3RF233 |
|--|--|---|----------------------------------|---|
| General data | | | | • |
| Connection technique | | Screw connection | Spring-loaded connection | Ring cable connection |
| Main contact connection Conductor cross-section Solid Finely stranded with end sleeve Finely stranded without end sleeves Solid or stranded AWG conductors Insulation stripping length Terminal screw Tightening torque Tightening torque OllN JIS | mm ² mm ² AWG mm Ib.in | 2 × (1.5 2.5), 2 × (2.5 6) 2 × (1.5 2.5), 2 × (2.5 6), 1 × 10 2 × (14 10) 10 M 4 2 2.5 18 22 - | | - - - - M 5 2 2.5 18 22 DIN 46234 -5-2.5, -5-6, -5-10, -5-16, -5-25 JIS C 2805 R 2-5, 5.5-5, 8-5, 14-5 |
| Auxiliary/control contact connections Conductor cross-section Insulation stripping length Terminal screw • Tightening torque | mm ² AWG mm Nm Ib.in | 1x (0.5 2.5); 2x (0.5 1.0) 20 12 7 M 3 0.5 0.6 4.5 5.3 | 0.5 1.5 20 12 10 - - | 1x (0.5 2.5); 2x (0.5 1.0) 20 12 7 M 3 0.5 0.6 4.5 5.3 |

| Туре | | 3RF232 | 3RF234 | 3RF236 |
|--|--------------|-------------------------------|---------|---------|
| Main circuit | | | | |
| Rated operational voltage U _e • Tolerance • Rated frequency | V % Hz | 24 230 -15/+10 50/60 Hz | 230 460 | 400 600 |
| Rated insulation voltage U _i | V | 600 | | |
| Blocking voltage | V | 800 | 1200 | 1600 |
| Rate of voltage rise | V/µs | 1000 | | |

| Order No. | Type current AC | -51 ¹⁾ | | Power loss at | Minimum load | Leakage | Rated impulse | <i>l²t</i> value |
|-------------------------------------|------------------|--------------------------|----------|------------------|--------------|----------------------|--|-----------------------------|
| | I _{max} | acc. to IEC 60947-4-3 | UL/CSA | / _{max} | current | current | withstand capacity I _{tsm} | |
| | at 40 °C | at 40 °C | at 50 °C | | | | | |
| | A | А | А | W | А | mA | А | A ² s |
| Main circuit | | | | | | | | |
| 3RF23 1A2 3RF23 1A4 3RF23 1A6 | 10.5 | 7.5 | 9.6 | 11 | 0.5 | 10 | 200 200 400 | 200 200 800 |
| 3RF23 2A2 3RF23 2C2 3RF23 2D2 | 20 | 13.2 | 17.6 | 20 | 0.5 | 10 25 10 | 600 600 1150 | 1800 1800 6600 |
| 3RF23 2A4 3RF23 2C4 3RF23 2D4 | | | | | | 10 25 10 10 | 600 600 1150 | 1800 1800 6600 |
| 3RF23 2A6 | | | | | | | 600 | 1800 |
| 3RF23 3A2 3RF23 3A4 3RF23 3A6 | 30 | 22 | 27 | 33 | 0.5 | 10 | 600 | 1800 |
| 3RF23 4A2 3RF23 4A4 3RF23 4A6 | 40 | 33 | 36 | 44 | 0.5 | 10 | 1200 1200 1150 | 7200 7200 6600 |
| 3RF23 5A2 3RF23 5A4 3RF23 5A6 | 50 | 36 | 45 | 54 | 0.5 | 10 | 1150 | 6600 |
| 3RF23 7A2 3RF23 7A4 3RF23 7A6 | 70 | 70 | 62 | 83 | 0.5 | 10 | 1150 | 6600 |
| 3RF23 9A2 3RF23 9A4 3RF23 9A6 | 88 | 88 | 80 | 117 | 0.5 | 10 | 1150 | 6600 |

 The type current provides information about the performance of the semiconductor contactor. The actual permitted operational current l_e can be smaller depending on the connection method and start-up conditions. Derating acc. to curves from page 3/30!

SIRIUS SC semiconductor contactors

| 0.1.11 | - | 40 5 (1) | | | | | | | | 0 |
|-------------------------------------|------------------|-----------------------|----------|-------|---------------------|---------------------|-------------------------|--------------------|-------------------------|-----------------------------|
| Order No. | Type current | | | | | Power loss | Minimum load current | Leakage current | Rated impulse withstand | <i>l²t</i> value |
| | I _{max} | acc. to IEC 60947- | UL/CSA | AC-15 | | at I _{max} | ioau current | Current | capacity Itsm | |
| | at 40 °C | 4-3 | at 50 °C | | Parameters | | | | | |
| | | at 40 °C | | | | | | | | |
| | А | A | A | А | | W | А | mA | A | A ² s |
| Main circuit | | | | | | | | | | |
| 3RF23 1B2 3RF23 1B4 | 10.5 | 7.5 | 9.6 | 6 | 1200 1/h 50 % ED | 11 | 0.5 | 10 | 200 200 | 200 200 |
| 3RF23 1B6 | | | | | | | | | 400 | 800 |
| 3RF23 2B2 3RF23 2B4 3RF23 2B6 | 20 | 13.2 | 17.6 | 12 | 1200 1/h 50 % ED | 20 | 0.5 | 10 | 600 | 1800 |
| 3RF23 3B2 3RF23 3B4 3RF23 3B6 | 30 | 22 | 27 | 15 | 1200 1/h 50 % ED | 33 | 0.5 | 10 | 600 | 1800 |
| 3RF23 4B2 3RF23 4B4 3RF23 4B6 | 40 | 33 | 36 | 20 | 1200 1/h 50 % ED | 44 | 0.5 | 10 | 1200 1200 1150 | 7200 7200 6600 |
| 3RF23 5B2 3RF23 5B4 3RF23 5B6 | 50 | 36 | 45 | 25 | 1200 1/h 50 % ED | 54 | 0.5 | 10 | 1150 | 6600 |
| 3RF23 7B2 3RF23 7B4 3RF23 7B6 | 70 | 70 | 62 | 27.5 | 1200 1/h 50 % ED | 83 | 0.5 | 10 | 1150 | 6600 |
| 3RF23 9B2 3RF23 9B4 3RF23 9B6 | 88 | 88 | 80 | 30 | 1200 1/h 50 % ED | 117 | 0.5 | 10 | 1150 | 6600 |

 The type current provides information about the performance of the semiconductor contactor. The actual permitted operational current *l_e* can be smaller depending on the connection method and start-up conditions. Derating acc. to curves from page 3/30!

| Туре | | 3RF230. | 3RF232. |
|---|----------|--|--|
| Control circuit | | | |
| Method of operation | | DC operation | AC operation |
| Rated control supply voltage Us | V | 24 to EN 61131-2 | 110 230 |
| Max. rated control voltage | V | 30 | 253 |
| Rated control current at U _s | mA | 15 | 6 |
| Rated frequency of the control supply voltage | Hz | | 50/60 |
| Response voltage for tripping current | V mA | 15 2 | 90 2 |
| Drop-out voltage | V | 5 | 40 |
| Operating times closing time opening time | ms ms | 1 additional max. one half-wave 1 additional max. one half-wave | 40 additional max. one half-wave 40 additional max. one half-wave |

SIRIUS SC semiconductor contactors

| Order No. | Accessories | | | |
|--|--|--|--|--|
| | Converters | Load monitors | | Power controllers |
| | | Basic | Extended | |
| | | | | |
| Type current = 10.5 A | | 3RF29 20-0FA08 | | |
| 3RF23 11A.02 3RF23 11A.04 3RF23 11A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 20-0GA13 3RF29 20-0GA16 3RF29 20-0GA16 | - |
| 3RF23 11A.22 3RF23 11A.24 3RF23 11A.26 | - | - | 3RF29 20-0GA33 3RF29 20-0GA36 3RF29 20-0GA36 | |
| 3RF23 11B.02 3RF23 11B.04 3RF23 11B.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 20-0GA13 3RF29 20-0GA16 3RF29 20-0GA16 | 3RF29 20-0HA13 3RF29 20-0HA16 3RF29 20-0HA16 |
| 3RF23 11B.22 3RF23 11B.24 3RF23 11B.26 | - - - | - - | 3RF29 20-0GA33 3RF29 20-0GA36 3RF29 20-0GA36 | 3RF29 20-0HA33 3RF29 20-0HA36 3RF29 20-0HA36 |
| 3RF23 12A.02 3RF23 12A.04 3RF23 12A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | - | | |
| 3RF23 12A.22 3RF23 12A.24 3RF23 12A.26 | - - - | - - | - | - - - |
| 3RF23 13A.02 3RF23 13A.04 3RF23 13A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | - - - | 3RF29 20-0GA13 3RF29 20-0GA16 3RF29 20-0GA16 | |
| 3RF23 13A.22 3RF23 13A.24 3RF23 13A.26 | - | - - - | 3RF29 20-0GA33 3RF29 20-0GA36 3RF29 20-0GA36 | |
| Type current = 20 A | | | | |
| 3RF23 21A.02 3RF23 21A.04 3RF23 21A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 20-0GA13 3RF29 20-0GA16 3RF29 20-0GA16 | - |
| 3RF23 21A.22 3RF23 21A.24 3RF23 21A.26 | - - - | | 3RF29 20-0GA33 3RF29 20-0GA36 3RF29 20-0GA36 | : : |
| 3RF23 21B.02 3RF23 21B.04 3RF23 21B.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 20-0GA13 3RF29 20-0GA16 3RF29 20-0GA16 | 3RF29 20-0HA13 3RF29 20-0HA16 3RF29 20-0HA16 |
| 3RF23 21B.22 3RF23 21B.24 3RF23 21B.26 | - - - | - - - | 3RF29 20-0GA33 3RF29 20-0GA36 3RF29 20-0GA36 | 3RF29 20-0HA33 3RF29 20-0HA36 3RF29 20-0HA36 |
| 3RF23 21C.02 3RF23 21C.04 3RF23 21C.22 | 3RF29 00-0EA18 3RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 20-0GA13 3RF29 20-0GA16 3RF29 20-0GA33 | - |
| 3RF23 21C.24 | | | 3RF29 20-0GA36 | |
| 3RF23 21D.02 3RF23 21D.04 | 3RF29 00-0EA18 3RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 20-0GA13 3RF29 20-0GA16 | - |
| 3RF23 21D.22 3RF23 21D.24 | - | - | 3RF29 20-0GA33 3RF29 20-0GA36 | |
| 3RF23 22A.02 3RF23 22A.04 3RF23 22A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | - | - - - | |
| 3RF23 22A.22 3RF23 22A.24 3RF23 22A.26 | - | - | - - - | |
| 3RF23 22C.02 3RF23 22C.04 | 3RF29 00-0EA18 3RF29 00-0EA18 | - | - | - |
| 3RF23 22C.22 3RF23 22C.24 | - | - | - | - |
| 3RF23 22D.22 3RF23 22D.24 | - | - | - | - |
| 3RF23 23A.02 3RF23 23A.04 3RF23 23A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | - - - | 3RF29 20-0GA13 3RF29 20-0GA16 3RF29 20-0GA16 | - - - |
| 3RF23 23A.22 3RF23 23A.24 3RF23 23A.26 | - | - - - | 3RF29 20-0GA33 3RF29 20-0GA36 3RF29 20-0GA36 | : |
| 3RF23 23D.02 3RF23 23D.04 | 3RF29 00-0EA18 3RF29 00-0EA18 | - | 3RF29 20-0GA13 3RF29 20-0GA16 | - |
| 3RF23 23D.22 3RF23 23D.24 | - | - | 3RF29 20-0GA33 3RF29 20-0GA36 | - |

SIRIUS SC semiconductor contactors

| Order No. | Accessories | | | |
|--|--|--|--|--|
| ordor No. | Converters | Load monitors | | Power controllers |
| | | Basic | Extended | |
| | | | | |
| Type current = 30 A | | | | |
| 3RF23 31A.02 3RF23 31A.04 | 3RF29 00-0EA18 3RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 50-0GA13 3RF29 50-0GA16 | - |
| 3RF23 31A.06 | 3RF29 00-0EA18 | 3RF29 20-0FA08 | 3RF29 50-0GA16 | - |
| 3RF23 31A.22 3RF23 31A.24 3RF23 31A.26 | - | - - - | 3RF29 50-0GA33 3RF29 50-0GA36 3RF29 50-0GA36 | - - - |
| 3RF23 31B.02 3RF23 31B.04 3RF23 31B.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | 3RF29 20-0FA08 3RF29 20-0FA08 3RF29 20-0FA08 | 3RF29 50-0GA13 3RF29 50-0GA16 3RF29 50-0GA16 | 3RF29 50-0HA13 3RF29 50-0HA16 3RF29 50-0HA16 |
| 3RF23 31B.22 3RF23 31B.24 3RF23 31B.26 | | - | 3RF29 50-0GA33 3RF29 50-0GA36 3RF29 50-0GA36 | 3RF29 50-0HA33 3RF29 50-0HA36 3RF29 50-0HA36 |
| 3RF23 33A.02 3RF23 33A.04 3RF23 33A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | | 3RF29 50-0GA13 3RF29 50-0GA16 3RF29 50-0GA16 | - - - |
| 3RF23 33A.22 3RF23 33A.24 3RF23 33A.26 | - | - - - | 3RF29 50-0GA33 3RF29 50-0GA36 3RF29 50-0GA36 | - |
| Type current = 40 A | | | | |
| 3RF23 41A.02 3RF23 41A.04 3RF23 41A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | - - - | 3RF29 50-0GA13 3RF29 50-0GA16 3RF29 50-0GA16 | - |
| 3RF23 41A.22 3RF23 41A.24 3RF23 41A.26 | - | - | 3RF29 50-0GA33 3RF29 50-0GA36 3RF29 50-0GA36 | - |
| 3RF23 41B.02 3RF23 41B.04 3RF23 41B.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | - | 3RF29 50-0GA13 3RF29 50-0GA16 3RF29 50-0GA16 | 3RF29 50-0HA13 3RF29 50-0HA16 3RF29 50-0HA16 |
| 3RF23 41B.22 3RF23 41B.24 3RF23 41B.26 | - - - | - - - | 3RF29 50-0GA33 3RF29 50-0GA36 3RF29 50-0GA36 | 3RF29 50-0HA33 3RF29 50-0HA36 3RF29 50-0HA36 |
| 3RF23 43A.02 3RF23 43A.04 3RF23 43A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | - - - | 3RF29 50-0GA13 3RF29 50-0GA16 3RF29 50-0GA16 | - - - |
| 3RF23 43A.22 3RF23 43A.24 3RF23 43A.26 | - - - | - - - | 3RF29 50-0GA33 3RF29 50-0GA36 3RF29 50-0GA36 | - - - |
| Type current = 50 A | | | | |
| 3RF23 51A.02 3RF23 51A.04 3RF23 51A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | | 3RF29 50-0GA13 3RF29 50-0GA16 3RF29 50-0GA16 | - - - |
| 3RF23 51A.22 3RF23 51A.24 3RF23 51A.26 | - - - | - - - | 3RF29 50-0GA33 3RF29 50-0GA36 3RF29 50-0GA36 | - - - |
| 3RF23 51B.02 3RF23 51B.04 3RF23 51B.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | - - - | 3RF29 50-0GA13 3RF29 50-0GA16 3RF29 50-0GA16 | 3RF29 50-0HA13 3RF29 50-0HA16 3RF29 50-0HA16 |
| 3RF23 51B.22 3RF23 51B.24 3RF23 51B.26 | - | - | 3RF29 50-0GA33 3RF29 50-0GA36 3RF29 50-0GA36 | 3RF29 50-0HA33 3RF29 50-0HA36 3RF29 50-0HA36 |
| 3RF23 53A.02 3RF23 53A.04 3RF23 53A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | - | 3RF29 50-0GA13 3RF29 50-0GA16 3RF29 50-0GA16 | - |
| 3RF23 53A.22 3RF23 53A.24 3RF23 53A.26 | - | - | 3RF29 50-0GA33 3RF29 50-0GA36 3RF29 50-0GA36 | - |
| Type current = 70 A | | | | |
| 3RF23 71B.02 3RF23 71B.04 3RF23 71B.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | - - - | 3RF29 90-0GA13 3RF29 90-0GA16 3RF29 90-0GA16 | 3RF29 90-0HA13 3RF29 90-0HA16 3RF29 90-0HA16 |
| 3RF23 71B.22 3RF23 71B.24 3RF23 71B.26 | - | - | 3RF29 90-0GA33 3RF29 90-0GA36 3RF29 90-0GA36 | 3RF29 90-0HA33 3RF29 90-0HA36 3RF29 90-0HA36 |
| 3RF23 73A.02 3RF23 73A.04 3RF23 73A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | - - - | 3RF29 90-0GA13 3RF29 90-0GA16 3RF29 90-0GA16 | - |
| 3RF23 73A.22 3RF23 73A.24 3RF23 73A.26 | - | - - - | 3RF29 90-0GA33 3RF29 90-0GA36 3RF29 90-0GA36 | - - - |
| | | | | |

SIRIUS SC semiconductor contactors

| Order No. | Accessories | | | |
|--|--|---------------|--|--|
| | Converters | Load monitors | | Power controllers |
| | | Basic | Extended | |
| | | Dasic | Extended | |
| Type current = 70 A | | | | |
| 3RF23 73B.02 3RF23 73B.04 3RF23 73B.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | - | 3RF29 90-0GA13 3RF29 90-0GA16 3RF29 90-0GA16 | 3RF29 90-0HA13 3RF29 90-0HA16 3RF29 90-0HA16 |
| 3RF23 73B.22 3RF23 73B.24 3RF23 73B.26 | - - - | - - - | 3RF29 90-0GA33 3RF29 90-0GA36 3RF29 90-0GA36 | 3RF29 90-0HA33 3RF29 90-0HA36 3RF29 90-0HA36 |
| Type current = 90 A | | | - | |
| 3RF23 91B.02 3RF23 91B.04 3RF23 91B.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | - | 3RF29 90-0GA13 3RF29 90-0GA16 3RF29 90-0GA16 | 3RF29 90-0HA13 3RF29 90-0HA16 3RF29 90-0HA16 |
| 3RF23 91B.22 3RF23 91B.24 3RF23 91B.26 | | - | 3RF29 90-0GA33 3RF29 90-0GA36 3RF29 90-0GA36 | 3RF29 90-0HA33 3RF29 90-0HA36 3RF29 90-0HA36 |
| 3RF23 93A.02 3RF23 93A.04 3RF23 93A.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | - | 3RF29 90-0GA13 3RF29 90-0GA16 3RF29 90-0GA16 | - |
| 3RF23 93A.22 3RF23 93A.24 3RF23 93A.26 | - | - - - | 3RF29 90-0GA33 3RF29 90-0GA36 3RF29 90-0GA36 | - - - |
| 3RF23 93B.02 3RF23 93B.04 3RF23 93B.06 | 3RF29 00-0EA18 3RF29 00-0EA18 3RF29 00-0EA18 | - | 3RF29 90-0GA13 3RF29 90-0GA16 3RF29 90-0GA16 | 3RF29 90-0HA13 3RF29 90-0HA16 3RF29 90-0HA16 |
| 3RF23 93B.22 3RF23 93B.24 3RF23 93B.26 | - | - - | 3RF29 90-0GA33 3RF29 90-0GA36 3RF29 90-0GA36 | 3RF29 90-0HA33 3RF29 90-0HA36 3RF29 90-0HA36 |

Fused design with semiconductor protection (similar to type of coordination "2")^1)

The semiconductor protection for the SIRIUS SC controlgear can be used with different protective devices. This allows protection by means of LV HRC fuses of operational class gL/gG or miniature circuit-breakers. Siemens recommends the use of special SITOR semiconductor fuses. The table below lists the maximum permissible fuses for each SIRIUS SC control gear.

If a fuse is used with a higher rated current than specified, semiconductor protection is no longer guaranteed. However, smaller fuses with a lower rated current for the load can be used without problems.

For protective devices with operational class gL/gG and for SITOR full range fuses 3NE1, the minimum cross-sections for the conductor to be connected must be taken into account.

| Order No. | All-range fuse LV HRC design gR/SITOR 3NE1 | Semiconducto Cylindrical de 10 × 38 mm aR/SITOR 3NC1 0 | or protection fus sign 14 × 51 mm aR/SITOR 3NC1 4 | e 22 × 58 mm aR/SITOR 3NC2 2 | Cable and line LV HRC design gL/gG 3NA | e protection fus Cylindrical de 10 × 38 mm gL/gG 3NW | | 22 × 58 mm gL/gG 3NW | DIAZED quick 5SB |
|----------------------------------|--|--|---|---------------------------------------|---|---|-------------------------------|-------------------------------|-------------------------|
| 3RF23 12 3RF23 14 3RF23 16 | 3NE1 813-0 3NE1 813-0 3NE1 813-0 | 3NC1 010 3NC1 010 3NC1 010 | 3NC1 410 3NC1 410 3NC1 410 | 3NC2 220 3NC2 220 3NC2 220 | 3NA2 803 3NA2 801 3NA2 803-6 | 3NW6 001-1 3NW6 001-1 - | 3NW6 101-1 3NW6 101-1 - | - - | 5SB1 41 5SB1 41 - |
| 3RF23 22 3RF23 24 3RF23 26 | 3NE1 814-0 3NE1 814-0 3NE1 814-0 | 3NC1 020 3NC1 020 3NC1 020 | 3NC1 420 3NC1 420 3NC1 420 | 3NC2 220 3NC2 220 3NC2 220 | 3NA2 807 3NA2 807 3NA2 807-6 | 3NW6 007-1 3NW6 005-1 - | 3NW6 107-1 3NW6 105-1 - | 3NW6 207-1 3NW6 205-1 - | 5SB1 71 5SB1 71 - |
| 3RF23 32 3RF23 34 3RF23 36 | 3NE1 803-0 3NE1 803-0 3NE1 803-0 | 3NC1 032 3NC1 032 3NC1 032 | 3NC1 432 3NC1 432 3NC1 432 | 3NC2 232 3NC2 232 3NC2 232 | 3NA2 810 3NA2 807 3NA2 807-6 | - - | 3NW6 107-1 3NW6 105-1 - | 3NW6 207-1 3NW6 205-1 - | 5SB3 11 5SB3 11 - |
| 3RF23 42 3RF23 44 3RF23 46 | 3NE1 802-0 3NE1 802-0 3NE1 802-0 | - - | 3NC1 440 3NC1 440 3NC1 440 | 3NC2 240 3NC2 240 3NC2 240 | 3NA2 817 3NA2 812 3NA2 812-6 | - - | 3NW6 117-1 3NW6 112-1 - | 3NW6 217-1 3NW6 212-1 - | 5SB3 21 5SB3 21 - |
| 3RF23 52 3RF23 54 3RF23 56 | 3NE1 817-0 3NE1 817-0 3NE1 817-0 | - - | 3NC1 450 3NC1 450 3NC1 450 | 3NC2 250 3NC2 250 3NC2 250 | 3NA2 817 3NA2 812 3NA2 812-6 | - - | 3NW6 117-1 - - | 3NW6 217-1 3NW6 210-1 - | 5SB3 21 5SB3 21 - |
| 3RF23 72 3RF23 74 3RF23 76 | 3NE1 820-0 3NE1 020-2 3NE1 020-2 | - | - | 3NC2 280 3NC2 280 3NC2 280 | 3NA2 817 3NA2 812 3NA2 812-6 | - | - | 3NW6 217-1 3NW6 210-1 - | 5SB3 31 5SB3 21 - |
| 3RF23 92 3RF23 94 3RF23 96 | 3NE1 021-2 3NE1 021-2 3NE1 020-2 | - - | - - | 3NC2 200 3NC2 280 3NC2 280 | 3NA2 817 3NA2 812 3NA2 812-6 | - | - - | 3NW6 217-1 3NW6 210-1 - | 5SB3 31 5SB3 21 - |

 Type of coordination "2" acc. to EN 60947-4-1: In the event of a short-circuit, the controlgear in the load feeder must not endanger persons or the installation. They must be suitable for further operation. For fused configurations, the protective device must be replaced. replaced.

SIRIUS SC semiconductor contactors

Selection and ordering data

| - Alera | |
|---------|-----|
| .0. | .G. |
| | |
| | 0 |









| 3RF23 | 10-1AA | 402 3R | -23 30- | 1AAC | 2 3RF23 40-1A | A02 | 3RF | 23 5 | D-3AA02 | 3RF23 7 | 0-3AA02 | | 3RF2 | 3 90-3A/ | 402 |
|--|------------------------------|------------------|----------------|-------------|--|--------------------|-----------------------------|--------|----------------------------------|---------|-----------------------------|-------------|--|----------------------------|-----------------------------|
| Type current 1) I _{max.} | able I _{max} a | and $U_{\rm e}$ | or | | Screw connection | PS* | Weight per PU approx. | DT | Spring-loaded connection | PS* | Weight per PU approx. | DT | Ring cable connection | PS* | Weight per PU approx. |
| А | kW | kW | kW | | Order No. | | kg | | Order No. | | kg | | Order No. | | kg |
| Zero-p | oint | switcl | ning, r | ated | operational volt | age U _e | = 24 V t | o 23 | D V | | | | | | |
| 10.5 20 | 1.2 2.3 | 2.4 4.6 | - | A A | 3RF23 10-1AA□2 3RF23 20-1AA□2 | | 0.136 0.204 | B B | 3RF23 10-2AA□2 3RF23 20-2AA□2 | | 0.136 0.204 | B B | 3RF23 10-3AA□2 3RF23 20-3AA□2 | 1 unit 1 unit | 0.136 0.204 |
| 30 40 50 | 3.5 4.6 6 | 6.9 9.2 12 | - | A A A | 3RF23 30-1AA□2 3RF23 40-1AA□2 3RF23 50-1AA□2 | 1 unit | 0.354 0.496 0.496 | | - | | | B B B | 3RF23 30-3AA□2 3RF23 40-3AA□2 3RF23 50-3AA□2 | 1 unit 1 unit 1 unit | 0.354 0.496 0.496 |
| 70 88 | 8 10 | 16 20 | - | | : | | | | : | | | B B | 3RF23 70-3AA□2 3RF23 90-3AA□2 | 1 unit 1 unit | 0.944 2.600 |
| Zero-p | oint | switcl | ning, r | ated | operational volt | age U _e | = 230 V | to 4 | 60 V | | | | | | |
| 10.5 20 | - | 2.4 4.6 | 4.2 8 | A A | 3RF23 10-1AA□4 3RF23 20-1AA□4 | | 0.136 0.204 | B B | 3RF23 10-2AA□4 3RF23 20-2AA□4 | | 0.136 0.204 | B B | 3RF23 10-3AA□4 3RF23 20-3AA□4 | 1 unit 1 unit | 0.136 0.204 |
| 30 40 50 | - | 6.9 9.2 12 | 12 16 20 | A A A | 3RF23 30-1AA□4 3RF23 40-1AA□4 3RF23 50-1AA□4 | 1 unit | 0.354 0.496 0.496 | | - | | | B B B | 3RF23 30-3AA□4 3RF23 40-3AA□4 3RF23 50-3AA□4 | 1 unit | 0.354 0.496 0.496 |
| 70 88 | - | 16 20 | 28 35 | | - | | | | - | | | B B | 3RF23 70-3AA□4 3RF23 90-3AA□4 | | 0.944 2.600 |
| Zero-p | oint | switcl | ning, r | ated | operational volt | age U _e | = 400 V | to 6 | 00 V | _ | | | | | |
| 10.5 20 | - | - | 4.2 8 | B B | 3RF23 10-1AA□6 3RF23 20-1AA□6 | | 0.136 0.204 | B B | 3RF23 10-2AA□6 3RF23 20-2AA□6 | | 0.136 0.204 | B B | 3RF23 10-3AA□6 3RF23 20-3AA□6 | 1 unit 1 unit | 0.136 0.204 |
| 30 40 50 | - | - | 12 16 20 | B B B | 3RF23 30-1AA□6 3RF23 40-1AA□6 3RF23 50-1AA□6 | 1 unit | 0.354 0.496 0.496 | | - | | | B B B | 3RF23 30-3AA□6 3RF23 40-3AA□6 3RF23 50-3AA□6 | 1 unit 1 unit 1 unit | 0.354 0.496 0.496 |
| 70 88 | - | - | 28 35 | | - | | | | - | | | B B | 3RF23 70-3AA□6 3RF23 90-3AA□6 | 1 unit 1 unit | 0.944 2.600 |
| Order N rated c | ontrol | supply | / voltag | | | | | | | | | | | | |
| DC 24 \ AC 110 | | | 61131-2 | 2 | 0 2 | | | | 0 2 | | | | 0 2 | | |

Other rated control supply voltages on request.

1) The type current provides information about the performance of the semiconductor contactor. The actual permitted operational current $l_{\rm e}$ can be smaller depending on the connection method and start-up conditions. Derating acc. to curves from page 3/30!

SIRIUS SC semiconductor contactors

| Type current) /max. | able p I _{max} a | na oe | or | DT | Screw connection | PS* | Weight per PU approx. | DT | Spring-loaded connection | PS* | Weight per PU approx. | DT | Ring cable connection | PS* | Weight per PU approx. |
|-------------------------------|------------------------------|-------------------|-------------------------|-------------------------|---|------------------|------------------------------------|-------|---|------------------------|-----------------------------|--------|----------------------------------|-------------|-----------------------------|
| ^ | | kW | kW | | Order No. | | ka | | Order No. | | ka | | Order No. | | ka |
| م Instan | kW taneo | | | g, ra | ated operational | voltag | kg e U_e = 2 4 | V to | | | kg | | Order No. | | kg |
| 10.5 | 1.2 | 2.4 | - | В | 3RF23 10-1BA□2 | 1 unit | 0.136 | | - | | | | - | | |
| 20 30 | 2.3 3.5 | 4.6 6.9 | - | B B | 3RF23 20-1BA□2 3RF23 30-1BA□2 | | 0.204 0.354 | | - | | | | - | | |
| 0 | 4.6 6 | 9.2 12 | - | B B | 3RF23 40-1BA□2 3RF23 50-1BA□2 | | 0.496 0.496 | | - | | | | - | | |
| 0 | 8 | 16 | - | В | 3RF23 70-1BA□2 | 1 unit | 0.944 | | - | | | В | 3RF23 70-3BA□2 | | 0.944 |
| 8 | 10 | 20 | - | В | 3RF23 90-1BA□2 | | 2.600 | | - | | | В | 3RF23 90-3BA□2 | 1 unit | 2.600 |
| nstan 0.5 | taneo - | us sw 2.4 | vitchin 4.2 | <mark>g, ra</mark> B | ated operational 3RF23 10-1BAD4 | · · · · · | e U _e = 23 0.136 | 80 V | to 460 V | | | | | | |
| 0.5 | - | 2.4 4.6 | 4.2 8 | В | 3RF23 20-1BA□4 | | 0.130 | | - | | | | - | | |
| 0 0 | - | 6.9 9.2 | 12 16 | B B | 3RF23 30-1BA□4 3RF23 40-1BA□4 | | 0.354 0.496 | | - | | | | - | | |
| 0 | - | 12 | 20 | В | 3RF23 50-1BA□4 | 1 unit | 0.496 | | - | | | - | - | | |
| 0 8 | - | 16 20 | 28 35 | B B | 3RF23 70-1BA□4 3RF23 90-1BA□4 | | 0.944 2.600 | | : | | | B B | 3RF23 70-3BA□4 3RF23 90-3BA□4 | | 0.944 2.600 |
| nstan | taneo | us sv | vitchin | g, ra | ated operational | voltag | e <i>U</i> e = 40 | 0 V 0 | to 600 V | - | | | | | |
| 0.5 0 | - | - | 4.2 8 | B B | 3RF23 10-1BA□6 3RF23 20-1BA□6 | | 0.136 0.204 | | - | | | | - | | |
| 0 | - | - | o 12 | B | 3RF23 20-1BA | | 0.204 | | - | | | | - | | |
| 0 0 | - | - | 16 20 | B B | 3RF23 40-1BA□6 3RF23 50-1BA□6 | 1 unit 1 unit | 0.496 0.496 | | - | | | | - | | |
| 0 | - | - | 28 | В | 3RF23 70-1BA□6 | 1 unit | 0.944 | | - | | | В | 3RF23 70-3BA□6 | | 0.944 |
| 8 | - | - | 35 | В | 3RF23 90-1BA□6 | | 2.600 | | - | | | В | 3RF23 90-3BA□6 | i unit | 2.600 |
| .ow no 0 | 2.3 | 4.6 | operat | B | al voltage U _e = 2 3RF23 20-1CA□2 | - | 230 V 0.204 | В | 3RF23 20-2CA□2 | 1 unit | 0.204 | | - | | |
| | | | operat | | al voltage <i>U_e</i> = 2 | | | _ | | | | | | | |
| 0 | - | 4.6 | 8 | В | 3RF23 20-1CA□4 | | 0.204 | В | 3RF23 20-2CA□4 | 1 unit | 0.204 | | - | | |
| Short- | circui | t resi | stant v | vith | B-automatic dev | /ice. ra | ted oper | atior | nal voltage <i>U_e = 2</i> | 24 V to | 230 V | | | | |
| 0 | 2.3 | 4.6 | - | В | 3RF23 20-1DA□2 | - | 0.204 | В | 3RF23 20-2DA22 | - | 0.204 | В | 3RF23 20-3DA□2 | 1 unit | 0.204 |
| Short- | circui | t resi | stant v | vith | B-automatic dev | /ice, ra | ted oper | atior | nal voltage <i>U_e = 2</i> | 230 V to | o 460 V | | | | |
| 0 | - | 4.6 | 8 | В | 3RF23 20-1DA□4 | 1 unit | 0.204 | В | 3RF23 20-2DA24 | 1 unit | 0.204 | В | 3RF23 20-3DA□4 | 1 unit | 0.204 |
| Order N | | | | ~ // | | | | | | | | | | | |
| C 24 V | acc. t | o EN 6 | voltag 1131-2 | eos | 0 | | | | o | | | | ο | | |
| C 110 | | | | | 2 | | | | 2 | | | | 2 | | |
| | | | | | oltages on reque mation about the pe | | on of the e | omi | | | | | | | |
| condi smalle | ictor co er depe | ontacto ending | or. The a on the o | actua conn | age 3/30! | nal curre | ent I _e can | be | | | | | | | |
| | | | Versio | 'n | | | | | | | | D | Order No. | PS* | Weight per PU approx |
| | | | Acce | esso | ories | | | | | | | | | | kg |
| | | | | | er for spring-loaded | d connec | tion syste | m | | | | А | 8WA2 880 | 1 unit | 0.034 |
| | | | Termi with ri | i nal d ng te | cover for 3RF21 sen | nicondu | ctor relays | and | 3RF23 semiconduct rminal cover can als | tor conta so be use | ctors ed for | A | 3RF29 00-3PA88 | 10 units | 0.010 |

3

SIRIUS SC semiconductor contactors

Further information

Notes on selection

These notes are intended for general orientation and will no doubt be sufficient for most applications. If the installation conditions differ significantly from the examples described here, you can contact our Technical Assistance team for further help.

 Telephone:
 +49
 9131
 7
 43833

 Fax:
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 9131
 7
 42899

 e-mail:
 nst.technical-assistance@siemens.com

For more information on the Internet go to www.siemens.com/lowvoltage/technical-assistance

Selecting semiconductor contactors

The semiconductor contactors are selected on the basis of details of the power system, the load and the ambient conditions. As the semiconductor contactors are already equipped with an optimally matched heat sink, the selection process is considerably simpler than that for semiconductor relays.

The following procedure is recommended:

- Determine the rated current of the load and the mains voltage
- Select a semiconductor contactor with the same or higher rated current than the load
- Check the correct contactor size with the aid of the rated current diagram, taking account of the design conditions

General data

Overview

Function modules for SIRIUS SC semiconductor switching devices

A great variety of applications demand an expanded range of functionality. With our function modules, these requirements can be met really easily. The modules are mounted simply by clicking them into place; straight away the necessary connections are made with the semiconductor relay or contactor. The plug-in connection to control the semiconductor switching devices can simply remain in use.

The following function modules are available:

- Converters
- Load monitors
- Power controllers

Technical specifications

| Туре | | 3RF29E | 3RF29F | 3RF29G | 3RF29H |
|---|-----------------------------|--|---------------------------------------|--|--------|
| General data | | | | | |
| Ambient temperature during operation, derating at 40 °C when stored | °C °C | -25 +60 -55 +80 | | | |
| Site altitude | m | 0 1000; derating fro | m 1000 | | |
| Shock resistance acc. to IEC 60068-2-27 | g/ms | 15/11 | | | |
| Vibration resistance acc. to IEC 60068-2-6 | g | 2 | | | |
| Degree of protection | | IP20 | | | |
| Electromagnetic compatibility (EMC) Emitted interference • Conducted interference voltage acc. to IEC 60947-4-3 • Emitted, high-frequency interference voltage acc. to IEC 60947-4-3 | | Class A for industrial a Class A for industrial a | | | |
| Noise immunity • Electrostatic discharge acc. to IEC 61000-4-2 (corresponds to degree of severity 3) • Induced RF fields acc. to IEC 61000-4-6 • Burst acc. to IEC 61000-4-4 • Surge acc. to IEC 61000-4-5 | kV MHz kV | Contact discharge 4; a 0.15 80; 140 dBµV; 2 kV/5.0 kHz; behavio Conductor - ground 2; | behavior criterion 1 r criterion 1 | vior criterion 2 or 1; behavior criterion 2 | 2 |
| Connection, auxiliary/control contacts, screw connection Conductor cross-section • Insulation stripping length Terminal screw • Tightening torque | mm ² mm Nm | 1x (0.5 2.5); 2x (0.5 7 M3 0.5 0.6 | 1) AWG 20 12 | | |
| Converter diameter of hole | mm | - | 7 | 17 | |
| 1) Note limitations for power controller function modu | le on page | 3/28. | | | |

| Туре | | 3RF29E8 | 3RF29F8 | 3RF29G3 | 3RF29G6 | 3RF29H3 | 3RF29H6 |
|--|--------------|---------------|---------|-------------------------------|---------|----------|---------|
| Main circuit | | | | | | | |
| Rated operational voltage U _e • Tolerance • Rated frequency | V % Hz | _1) - - | | 110 230 -15 / +10 50/60 | 400 600 | 110 230 | 400 600 |
| Rated insulation voltage U _i | V | - | | 600 | | | |
| Voltage detection Measuring range | V | - | | 93.5 253 | 340 660 | 93.5 253 | 340 660 |
| Mains voltage fluctuation compensation | % | - | | 20 | | | |

1) Versions do not depend on main circuit.

| Туре | | 3RF290. 3F | | | 3RF291. 3 | | | | 3RF293. | | | |
|--|---------|---------------|---------------|-----------|-----------|---------------|---------------|--------------|---------------|---------------|--|--|
| Control circuit | | | | | | | | | | | | |
| Method of operation | | DC operatio | n | | AC/DC | operation | | AC operation | | | | |
| Rated control supply voltage U _s Rated operating current | V mA | 24 15 | | | 24 15 | | | 110 15 | | | | |
| Max. rated control voltage Rated control current at maximum voltage | V mA | 30 15 | | | 30 15 | | | 121 15 | | | | |
| Rated frequency of the control supply voltage | Hz | - | | | 50/60 | | | 50/ | 60 | | | |
| Response voltage for tripping current | V mA | 15 2 | | | 15 2 | | | 90 2 | | | | |
| Drop-out voltage | V | 5 | | | 5 | | | - | | | | |
| Туре | | 3RF29 2 .F | 3RF29 2 .G | 3RI .H | F29 2 | 3RF29 5 .G | 3RF29 5 .H | i | 3RF29 9 .G | 3RF29 9 .H | | |
| Current detection | | | | | | | | | | | | |
| Rated operational current <i>I</i> e | А | 20 | | | | 50 | | | 90 | | | |
| Measuring range | А | 4 22 | | | 4 55 | | | 4 99 | | | | |
| Number of partial loads | | 6 | 12 | - | | 12 | - | | 12 | - | | |

Converters

Overview

Converter for SIRIUS SC semiconductor switching devices

This module is used to convert analog drive signals, such as those output from many temperature controllers, for example, into a pulse-width-modulated digital signal. The connected semiconductor contactors and relays can therefore regulate the output of a load as a percentage.

Area of application

The device is used for conversion from an analog input signal to an on/off ratio. The function module can only be used in conjunction with a 3RF21 semiconductor relay or a 3RF23 semiconductor contactor.

Design

Mounting

Simply snapping onto the 3RF21 semiconductor relays or 3RF23 semiconductor contactors establishes the connections to the semiconductor switching devices. The connector on the semiconductor switching devices from the control circuit can be used on the converter without rewiring.

Functions

The analog value from a temperature controller is present at the 0-10 V terminals. This controls the on-to-off period, as a function of voltage. The period duration is predefined at one second. Conversion of the analog voltage is linear in the voltage range from 0.1 to 9.9 V. At voltages below 0.1 V the connected switching device is not activated, while at voltages above 9.9 V the connected switching device is always activated.

Technical specifications

Control input for converter und load monitoring

| Туре | | 3RF29 00-0EA18 | 3RF290HA. |
|-----------------------------------|--------|----------------|---------------|
| Control input | | | |
| Analog input Permissible range | V V | 0 10 -1 11 | 0 10 -1 11 |
| Input resistance | kΩ | 100 | 8 |
| Period duration | S | 1 | 1 |

Selection and ordering data

| | Rated operational current <i>l</i> e | Rated operational voltage $U_{\rm e}$ | DT | Rated control supply voltage <i>U</i> s AC/DC 24 V | PS* | Weight per PU approx. |
|--|--------------------------------------|---------------------------------------|----|--|--------|-----------------------------|
| | A | V | | Order No. | | kg |
| Converter | | | | | | |
| A Marine and A Mar | - | - | A | 3RF29 00-0EA18 | 1 unit | 0.025 |

SIRIUS SC Semiconductor Switching Devices Function Modules

Load monitoring

Overview

Load monitoring for SIRIUS SC semiconductor switching devices

Many faults can be quickly detected by monitoring a load circuit connected to the semiconductor switching device, as made possible with this module. Examples include the failure of load elements (up to 6 in the basic version or up to 12 in the extended version), alloyed power semiconductors, a lack of voltage or a break in a load circuit. A fault is indicated by one or more LEDs and reported to the controller via a PLC-compatible output.

The operating principle is based on permanent monitoring of the current intensity. This figure is continuously compared with the reference value stored once during commissioning by the simple press of a button. In order to detect the failure of one of several loads, the current difference must be 1/6 (in the basic version) or 1/12 (in the extended version) of the reference value. In the event of a fault, a contact (NC) is actuated and one or more LEDs indicate the fault.

Area of application

The device is used for monitoring one or more loads (partial loads). The function module can only be used in conjunction with a 3RF21 semiconductor relay or a 3RF23 semiconductor contactor. The devices with spring-loaded connections in the load circuit are not suitable.

Design

Mounting

Simply snapping onto the 3RF21 semiconductor relays or 3RF23 semiconductor contactors establishes the connections to the semiconductor switching devices. Because of the special design, the straight-through transformer of the load monitoring module covers the lower main power connection. The cable to the load is simply pushed through and secured with the terminal screw.

Functions

The function module is activated when an "ON" signal is applied (IN terminal). The module constantly monitors the current level and compares this with the setpoint value.

Start-up

Pressing the "Teach" button switches the device on; the current through the semiconductor switching device is detected and is stored as the setpoint. During this process the two lower (red¹) LEDs flash alternately; simultaneous maintained light from the 3 (red¹) LEDs indicates the conclusion of the teaching process.

Selection and ordering data

The "Teach" button can also be used to switch on the connected semiconductor switching device briefly for test purposes. In this case the "ON" LED is switched on.

Partial load faults, "basic" load monitoring

If a deviation of at least 1/6 of the stored setpoint value is detected, a fault is signaled. The fault is indicated via a "Fault" LED and by activation of the fault signaling output.

| | ок | Fault | | | | | | | |
|-----------------|----|---|---------------------|--------------------------------|--|--|--|--|--|
| LEDs | | Partial load failure/ load short-circuit | Thyristor defect | Mains failure/ fuse rupture | | | | | |
| ON/OFF | ~ | v | - | v | | | | | |
| Current flowing | 4 | ~ | V | - | | | | | |
| Group fault | - | <i>v</i> | v | v | | | | | |

Function is available
 Function not available

Partial load faults, "extended" load monitoring

Depending on the setting of the "response time" potentiometer, a deviation of at least 1/12 of the stored setpoint value after a response time of between 100 ms and 3 s is signaled as a fault. The fault is indicated via a "Load" LED and by activation of the fault signaling output.

The potentiometer can also be used to determine the response behavior of the fault signaling output. When delay values are set in the left-hand half, the fault signal is stored. This can only be reset by switching on and off by means of the control supply voltage.

When settings are made on the right-hand side, the fault output is automatically reset after the deviation has been corrected.

Voltage compensation, "extended" load monitoring

In addition to the current, the load voltage is also detected. This makes it possible to compensate for influences on the current strength resulting from voltage fluctuations.

Thyristor fault

If a current greater than the residual current of the switching device is measured in the deenergized state, the device triggers a thyristor fault after the set time delay. This means that the fault output is activated and the "Fault" ("Thyristor"¹) LED lights up.

Supply fault

If no current is measured in the energized state, the device triggers a supply fault after the set time delay. This means that the fault output is activated and the "Fault" ("Supply"¹) LED lights up. 1) "Extended" load monitoring

| Rated opera- tional cur- rent <i>l</i> e | Rated opera- tional voltage U_{e} | DT | Rated control supply voltage <i>U</i> s AC 110 V | PS* | Weight per PU approx. | DT | Rated control supply voltage U _s AC/DC 24 V | PS* | Weight per PU approx. | DT | Rated control supply voltage <i>U</i> s DC 24 V | PS* | Weight per PU approx. |
|---|--|--------|--|------------------|-----------------------------|--------|--|------------------|-----------------------------|----|--|--------|-----------------------------|
| A | V | | Order No. | | kg | | Order No. | | kg | | Order No. | | kg |
| Basic loa | ad monitoring | | | | | | | | | | | | |
| 20 | - | | - | | | | - | | | А | 3RF29 20-0FA08 | 1 unit | 0.050 |
| Extende | d load monitor | ing | | | | | | | | | | | |
| 20 20 | 110 230 400 600 | A A | 3RF29 20-0GA33 3RF29 20-0GA36 | 1 unit 1 unit | 0.120 0.120 | A A | 3RF29 20-0GA13 3RF29 20-0GA16 | 1 unit 1 unit | 0.120 0.120 | | : | | |
| 50 50 | 110 230 400 600 | A A | 3RF29 50-0GA33 3RF29 50-0GA36 | 1 unit 1 unit | 0.120 0.120 | A A | 3RF29 50-0GA13 3RF29 50-0GA16 | 1 unit 1 unit | 0.120 0.120 | | - | | |
| 90 90 | 110 230 400 600 | A A | 3RF29 90-0GA33 3RF29 90-0GA36 | 1 unit 1 unit | 0.120 0.120 | A A | 3RF29 90-0GA13 3RF29 90-0GA16 | 1 unit 1 unit | 0.120 0.120 | | - | | |

3/27

Power controllers

Overview

Power controllers for SIRIUS SC semiconductor switching devices

This module provides similar functionality to a power control regulator.

The following functions are integrated:

Power control regulator with proportional-action control for adjusting the power of the connected load. Here, the setpoint is set with a rotary knob on the module as a percentage with reference to the 100% power stored as a setpoint. In this way the power is kept constant even in the event of voltage fluctuations or a change in load resistance.

Inrush current limitation: With the aid of an adjustable voltage ramp, the inrush current is limited by means of phase control. This is useful above all with loads such as lamps which have an inrush transient current.

Load circuit monitoring for detecting load failure, alloyed power semiconductors, lack of voltage or a break in the load circuit.

Area of application

The power controller adjusts the current in the connected load by means of a semiconductor switching device depending on a setpoint. This compensates for changes in the mains voltage or in the load resistance. The setpoint can be predefined externally as a 0 to 10 V signal or internally by means of a potentiometer. Depending on the setting of the potentiometer ($t_{\rm R}$), the adjustment is carried out according to the principle of full-wave control or generalized phase control.

Full-wave control

In this operating mode the output is adjusted to the required setpoint by changing the on-to-off period. The period duration is predefined at one second.

Generalized phase control

In this operating mode the output is adjusted to the required setpoint by changing the current flow angle. In order to observe the limit values of the conducted interference voltage for industrial power systems, a choke rated at at least 200 μ H must be included in the load circuit.

Design

Mounting

Easy snapping onto the 3RF21 semiconductor relays or 3RF23 semiconductor contactors establishes the connections to the semiconductor switching devices. Because of the special design, the straight-through transformer of the power controller module covers the lower main power connection. The cable to the load is simply pushed through and secured with the terminal screw.

Functions

Start-up

Pressing the "Teach" button switches the device on; the current through the semiconductor switching device and the mains voltage are detected and stored. The resultant output is taken as the 100% output for the setpoint selection. During this process the two lower red LEDs flash alternately. Simultaneous maintained light from the three red LEDs indicates the completion of the "Teach" process.

The "Teach" button can also be used to switch on the connected semiconductor switching device briefly for test purposes. In this case the "ON" LED is switched on.

Setpoint selection

The setting on the setpoint potentiometer (P) determines how the setpoint selection is to be made:

External setpoint selection

At 0 % the setpoint selection is set via an external 0 - 10 V analog signal (terminals IN / 0 - 10 V). The device is switched on and off via the power supply (terminals A1 / A2).

Internal setpoint selection

Above 0 % the setpoint is set using the potentiometer. To allow this, the potential at terminal A1 must additionally be applied at the IN terminal. After removal of the "ON" signal, the switching module is switched off.

Inrush current limitation

The ramp time (t_R) for a voltage ramp on switching on is set with the potentiometer for the purpose of inrush current limitation. If a time longer than 0 s is set, the device operates according to the phase-angle principle. If 0 s is set, there is no voltage ramp and the device operates according to the principle of full-wave control.

Load fault

If upon switching on with voltage applied the current flowing is not greater than the residual current of the switching device, the device triggers a load fault. The fault relay is activated and the "Load" LED lights up.

Thyristor fault

If a current greater than the residual current of the switching device is measured in the deenergized state, the device triggers a thyristor fault. The fault relay is activated and the "Thyristor" LED lights up.

Supply fault

If no current is measured in the energized state, the device triggers a supply fault. The fault relay is activated and the "Supply" LED lights up.

Selection and ordering data

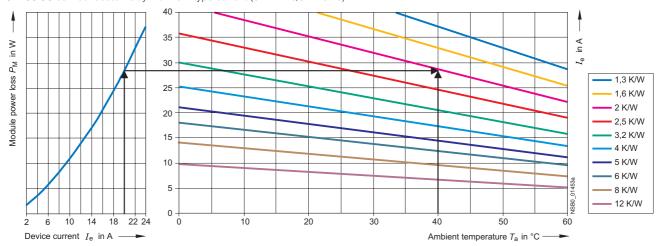
| Rated operational current Ie | Rated operational voltage U _e | DT | Rated control supply voltage U _s AC 110 V | PS* | Weight per PU approx. | DT | Rated control supply voltage U _s AC/DC 24 V | PS* | Weight per PU approx. |
|------------------------------|--|----|--|--------|-----------------------------|----|--|--------|-----------------------------|
| A | V | | Order No. | | kg | | Order No. | | kg |
| Power controllers | | | | | | | | | |
| 20 | 110 230 | A | 3RF29 20-0HA33 | 1 unit | 0.120 | A | 3RF29 20-0HA13 | 1 unit | 0.120 |
| 20 | 400 600 | A | 3RF29 20-0HA36 | 1 unit | 0.120 | A | 3RF29 20-0HA16 | 1 unit | 0.120 |
| 50 | 110 230 | A | 3RF29 50-0HA33 | 1 unit | 0.120 | A | 3RF29 50-0HA13 | 1 unit | 0.120 |
| 50 | 400 600 | A | 3RF29 50-0HA36 | 1 unit | 0.120 | A | 3RF29 50-0HA16 | 1 unit | 0.120 |
| 90 | 110 230 | A | 3RF29 90-0HA33 | 1 unit | 0.120 | A | 3RF29 90-0HA13 | 1 unit | 0.120 |
| 90 | 400 600 | A | 3RF29 90-0HA36 | 1 unit | 0.120 | A | 3RF29 90-0HA16 | 1 unit | 0.120 |

Project planning aids

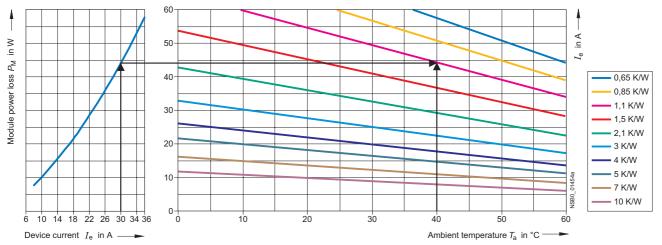
Characteristics

SIRIUS SC semiconductor relays

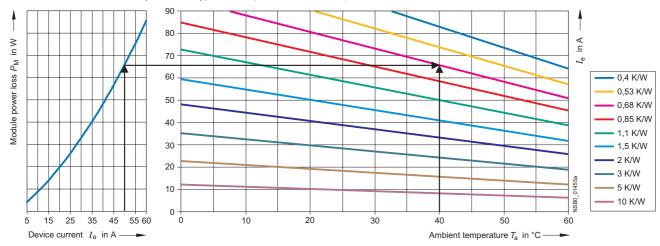
Dependence of the device current I_e on the ambient temperature T_a SIRIUS SC semiconductor relay with 20 A type current (3RF21 20/3RF20 20)¹⁾



SIRIUS SC semiconductor relay with 30 A type current (3RF21 30/3RF20 30)



SIRIUS SC semiconductor relay with 50 A type current (3RF21 50/3RF20 50)

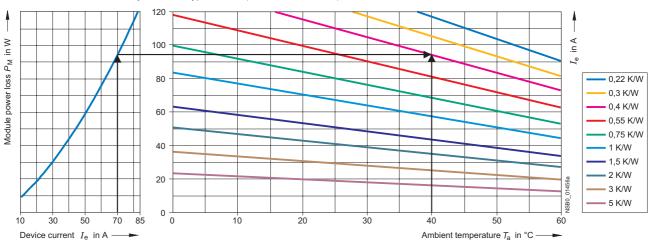


1) Arrangement example for $I_e = 20$ A and $T_a = 40$ C: The task is to find the thermal resistance $R_{\rm thha}$ and the heat-sink overtemperature $dT_{\rm ha}$. From the diagram on the left -> $P_{\rm M} = 28$ W, from the diagram on the right -> $R_{\rm thha} = 1.7$ K/W.

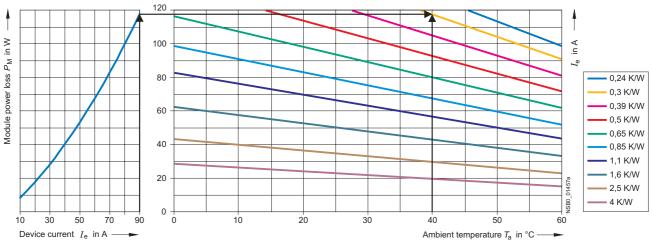
This results in: $dT_{ha} = R_{thha} \times P_M = 1.7 \text{ K/W} \times 28 \text{ W} = 47.6 \text{ K}$. At $dT_{ha} = 47.6 \text{ K}$ the heat sink must therefore have an $R_{thha} = 1.7 \text{ K/W}$.

Project planning aids

Dependence of the device current I_{e} on the ambient temperature T_{a} SIRIUS SC semiconductor relay with 70 A type current (3RF21 70/3RF20 70)



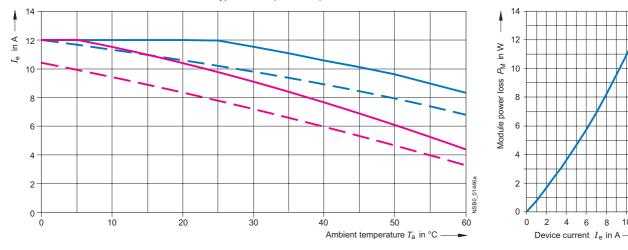
SIRIUS SC semiconductor relay with 88 A type current (3RF21 90/3RF20 90)



SIRIUS SC semiconductor contactors

Derating curves

SIRIUS SC semiconductor contactor with 10 A type current (3RF23 10)



10 12

8

3

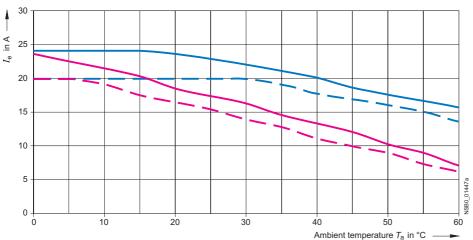
Module power loss P_M in W

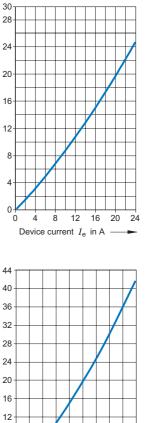
in V

Project planning aids

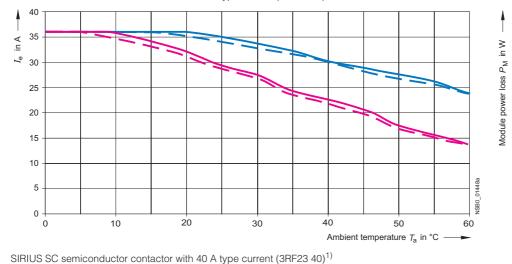
Derating curves

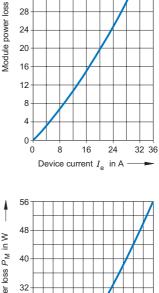


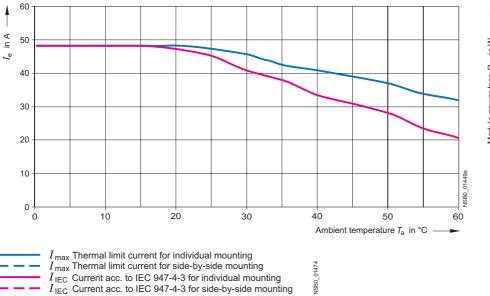


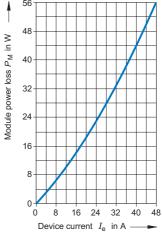










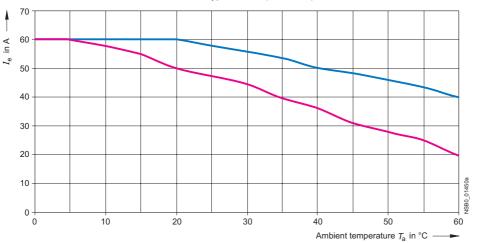


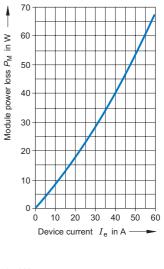
1) Identical current/temperature curves for individual and side-by-side mounting.

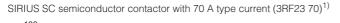
Project planning aids

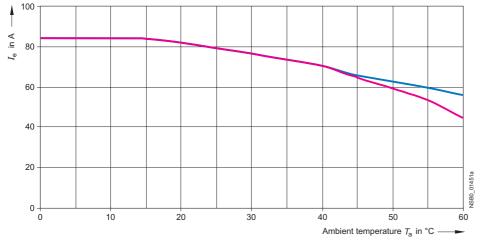
Derating curves

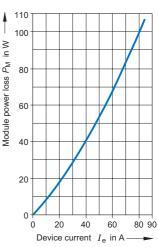
SIRIUS SC semiconductor contactor with 50 A type current (3RF23 50)¹⁾

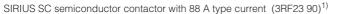


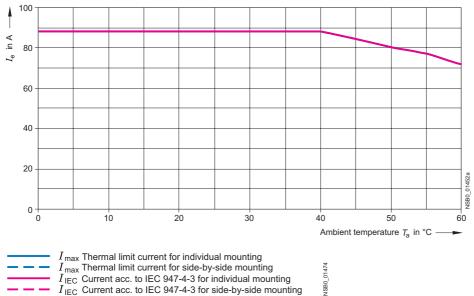


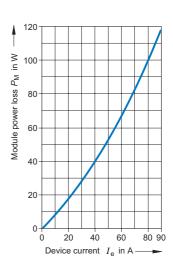












 $I_{\rm IEC}$ Current acc. to IEC 947-4-3 for side-by-side mounting

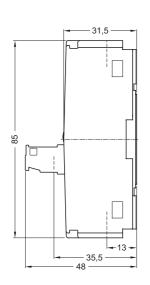
1) Identical current/temperature curves for individual and side-by-side mounting.

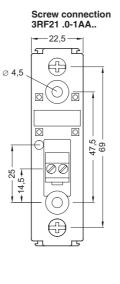
Project planning aids

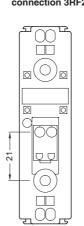
Dimension drawings

SIRIUS SC semiconductor relays

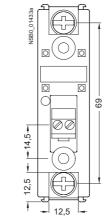
22.5 mm semiconductor relays



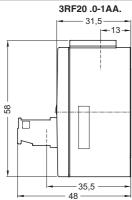


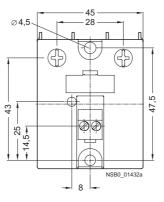


Spring-loaded Ring connection connection 3RF21 .0-2AA.. 3RF21 .0-3AA..



45 mm semiconductor relays





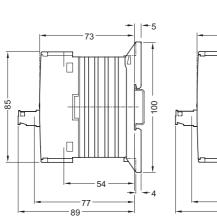
3RF23 20-.....

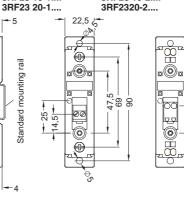
Project planning aids

3RF23 10-....

SIRIUS SC semiconductor contactors

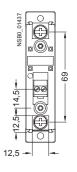
Semiconductor contactors with 10 A and 20 A type current





Screw connection 3RF23 10-1....

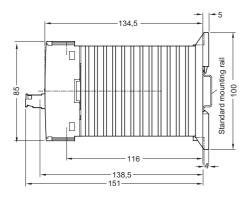
Spring-loaded connection 3RF23 10-2.... 3RF2320-2.... 3RF2320-2.... 3RF2320-3....



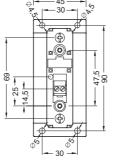
20,8

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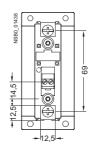
Semiconductor contactors with 30 A type current



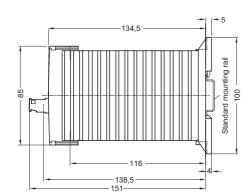




Ring connection 3RF23 30-3....



Semiconductor contactors with 40 A and 50 A type current





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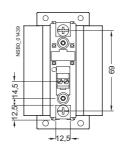
30 -67 ---

⁶⁰ T

+ 25 +

- 90 --





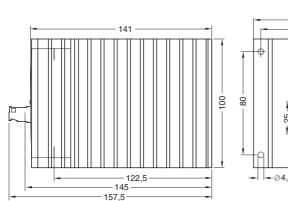
Project planning aids

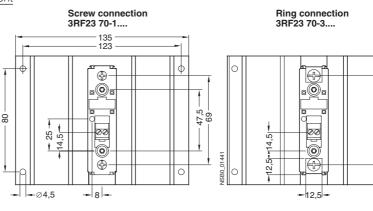
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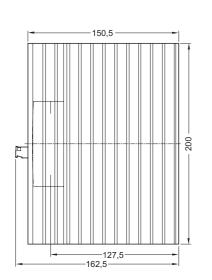
69

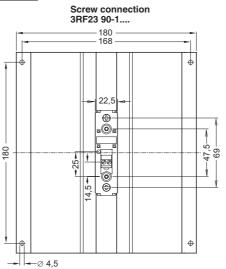




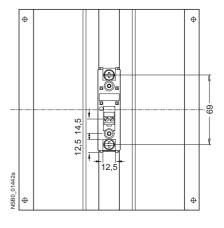


Semiconductor contactors with 88 A type current



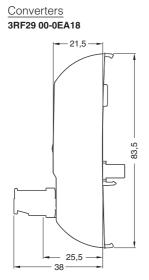


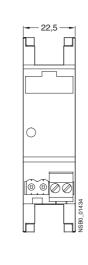


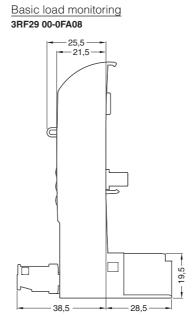


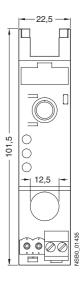
Project planning aids

Function modules for SIRIUS SC semiconductor switching devices

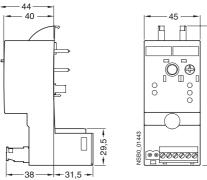


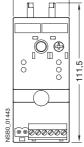




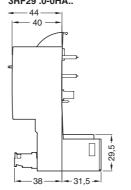


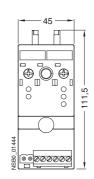
Extended load monitoring 3RF29 .0-0GA..





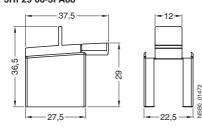
Power controllers 3RF29 .0-0HA..





Accessories for SIRIUS SC semiconductor switching devices

Terminal cover for SIRIUS semiconductor switching devices 3RF29 00-3PA88

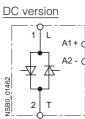


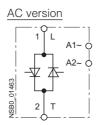
SIRIUS SC Semiconductor Switching Devices Semiconductor Relays and Contactors, Function Modules

Project planning aids

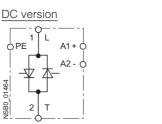
Circuit diagrams

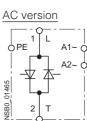
SIRIUS SC semiconductor relays



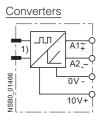


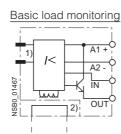
SIRIUS SC semiconductor contactors

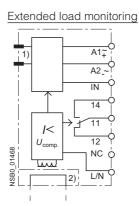




Function modules for SIRIUS SC semiconductor switching devices



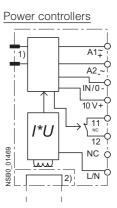




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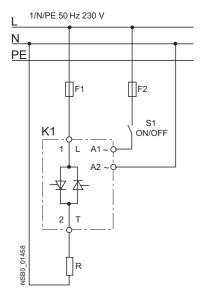


1) Internal connection.

2) Straight-through transformer.

SIRIUS SC semiconductor relays

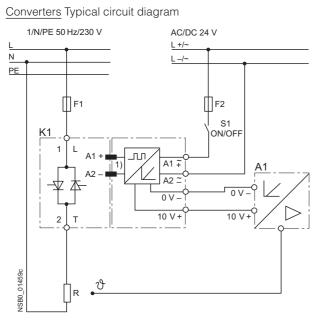
Typical circuit diagram



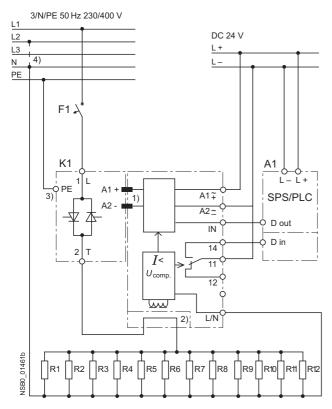
SIRIUS SC Semiconductor Switching Devices Semiconductor Relays and Contactors, Function Modules

Project planning aids

Function modules for SIRIUS SC semiconductor switching devices

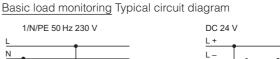


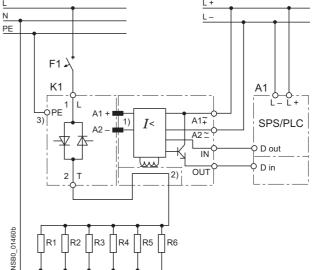
Extended load monitoring Typical circuit diagram



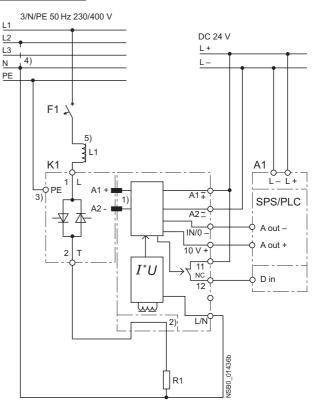
1) Internal connection.

- 2) Straight-through transformer.
- PE/ground connection for semiconductor contactors according to installation regulations.
- Connection of contact L/N to N conductor or a second phase according to the rated operational voltage of the function module.
- 5) In order to observe the limit values of the conducted interference voltage for generalized phase control, a choke rated at at least 200 μ H must be included in the load circuit.





Power controllers Typical circuit diagram



SIRIUS/SIKOSTART Soft Starters

General data

D

Overview

These properties apply to all soft starters:

- Soft starting and smooth ramp-down¹⁾
- Stepless starting
- Reduction of current peaks
- Avoidance of mains voltage fluctuations

- Reduced load on the power supply network
 Reduction of the mechanical load in the operating mechanism
 Considerable space savings and reduced wiring compared
- with conventional starters
- Maintenance-free switching
- Very easy handling

| | | 3RW30 03 | SIRIUS 3RW30/31 | SIKOSTART 3RW34 | SIKOSTART 3RW22 |
|---|----------|-------------------------|--------------------------|-------------------|--|
| Rated current at 40 °C | А | 3 | 6 100 | 57 1720 | 7 1200 |
| Rated operating voltage | V | 200 400 | 200 575 | 200 600 | 200 1000 |
| Motor rating at 400 V • Inline circuit • Inside-delta circuit | kW kW | 0.1 1.1 - | 1.1 55 - | 30 630 45 1000 | 3 710 - |
| Temperature range | °C | -25 +60 | -25 +60 | 0 +60 | 0 +55 |
| Starting voltage | % | 40 100 | 40 100 | 30 80 | 20 100 |
| Starting and ramp-down time | S | 0.1 20 | 0.1 20 | 0.5 60 | 0.3 180 (0 1000 with COM-SIKOSTART) |
| Number of parameter sets | | 1 | 1 (2 with 3RW31) | 1 | 1 3 (with COM-SIKOSTART) |
| Power semiconductors: thyristors | | in 2 phases | in 2 phases | in 3 phases | in 3 phases |
| Degree of protection | | IP20 | IP20 | IP00 | IP20/IP00 from 100 A |
| Built-in bypass contacts | | - | v | | |
| Optional inside-delta circuit | | - | | V | |
| Current limiting | | - | - | | v |
| Voltage limiting | | - | | | v |
| Pump running down | | - | - | | v |
| Energy saving | | - | - | | v |
| DC braking | | - | - | | v |
| Breakaway pulse | | - | - | | v |
| Electronic overload protection | | - | - | | v |
| Communication | | - | with AS-Interface module | - | PC interface, combinable with SIMOCODE-DP |
| Calibration software | | - | - | | ✔ (COM -SIKOSTART) |
| UL – CSA | | (✔) up to 230 V | v | v | (✔) up to 70 A |
| CE marking | | v | v | v | v |
| Approved for potentially explosive atmospheres | | - | V | - | V |
| Soft starting under heavy starting conditions | | - | - | ~ | ✓ |
| Configuring support | | Win-SIKOSTART, electron | ic selection slide | | |

Function is availableFunction not available

1) Smooth ramp-down not available for 3RW31.

For more information on the Internet go to www.siemens.de/sanftstarter

SIRIUS soft starters

Overview

SIRIUS 3RW30/31

Various versions of the 3RW30/31 SIRUS soft starters are available:

- Standard version for fixed frequency three-phase motors, sizes S00, S0, S2 and S3
- Version for fixed-speed three-phase motors in a 22.5 mm enclosure
- Special-purpose version 3RW31 for Dahlander motors only in size S0
- Version for soft starting single-phase motors of sizes S0, S2 and S3.

SIRIUS 3RW30/31 for three-phase motors

Soft starters rated up to 55 kW (at 400 V) for standard applications in three-phase networks. Extremely small sizes, low power losses and simple commissioning are just a few of the many advantages of this soft starter. The special feature of the 3RW31 series is that it allows independent definition of two separate acceleration ramps (Dahlander motors).

SIRIUS 3RW30 for single-phase motors

The additional version for standard applications in single-phase networks. Its voltage edge function reduces the motor's inrush current and effectively lowers the torque at the point of starting up, which protects the load and the supplying network.

Area of application

The SIRIUS solid-state soft starters are suitable for soft starting and stopping of three-phase asynchronous machines.

Due to two-phase control, the current is kept at minimum values in all three phases throughout the entire starting time. Due to continuous voltage influencing, current and torque peaks, which are unavoidable in the case of star-delta starters, for instance, do not occur.

Service range

Pumps, compressors, conveyors, and much more.

Functions

- Soft starting with voltage ramp; the starting voltage adjustment range $U_{\rm s}$ is 40 % to 100 % and the ramp time $t_{\rm R}$ can be set from 0 s to 20 s.
- Smooth ramp-down with voltage ramp; the running down time $t_{\rm off}$ can be set between 0 s to 20 s. Whereby the switch-off voltage $U_{\rm off}$ is dependent on the selected starting voltage $U_{\rm s}$.
- Setting with three potentiometers
- Simple mounting and commissioning
- Mains voltages at 50/60 Hz 200 V to 575 V
- \bullet Two control voltage versions are available: AC/DC 24 V and AC/DC 110 V to 230 V
- Wide temperature range from -25 °C to +60 °C
- Integrated bypass contacts to minimize dissipated power.
- Two built-in auxiliary contacts in sizes S0, S2 and S3 ensure user-friendly control and possible further processing within the system (for additional graphs, see page 3/52).

Technical specifications

| Туре | | 3RW30 03 | 3RW31.B0. | 3RW31.B1. |
|---|----|--------------------------|---------------------------|---------------------------------|
| Control electronics | | | | |
| Rated control supply voltage | V | AC/DC 24 230 (± 10 %) | AC/DC 24 (+10 %/-15 %) | AC/DC 110 230 (+10 %/-15 %) |
| Rated control supply current without fan/with fan | mA | 25 4 | approx. 50/approx. 180 | approx. 25 20/ approx. 85 80 |
| Rated frequency for AC | Hz | 50/60 ± 10 % | | |
| Starting time | S | 0 20 (variable) | | |
| Starting voltage | % | 40 100 (variable) | | |
| Ramp-down time | S | 0 20 (variable) | | |

| | 3RW30 03 | 3RW31.B.4 | 3RW31.B.5 | 3RW301AA12 | | |
|---|---|---|---|--|--|--|
| | | | | | | |
| V | AC/DC 200 400, 3-phase (± 10 %) | AC 200 460 3-phase (± 10 %) | AC 460 575 3-phase (± 10 %) | AC 115 240 1-phase (± 10 %) | | |
| Hz | 50/60 ± 10 % | | | | | |
| Reduction of I_e • up to 1000 m above sea level % • up to 2000 m above sea level % • up to 3000 m above sea level % • up to 4000 m above sea level ¹) % | 100 92 85 78 | | | | | |
| without auxiliary fan | The soft starters have been designed for operation on a vertical mountin surface $(+10^{\circ}/-10^{\circ})$. | | | | | |
| with auxiliary fan | - Any mounting position (except vertical, rotated by 18 | | | | | |
| | Hz Reduction of <i>l_e</i> • up to 1000 m above sea level % • up to 2000 m above sea level % • up to 3000 m above sea level % • up to 4000 m above sea level ¹) % without auxiliary fan | V AC/DC 200 400, 3-phase $(\pm 10 \%)$ Hz 50/60 $\pm 10 \%$ Reduction of l_e 100 up to 1000 m above sea level % 92 up to 3000 m above sea level % 85 up to 4000 m above sea level ¹) % 78 without auxiliary fan The soft starters ha surface (+10°/-10°) | V AC/DC 200 400, 3-phase $(\pm 10 \%)$ AC 200 460 3-phase $(\pm 10 \%)$ Hz 50/60 ± 10 % Reduction of I_e 100 up to 1000 m above sea level % 92 up to 3000 m above sea level % 85 up to 4000 m above sea level % 85 without auxiliary fan The soft starters have been designed for surface (+10°/-10°). | V AC/DC 200 400, 3-phase (± 10 %) AC 200 460 3-phase (± 10 %) AC 460 575 3-phase (± 10 %) Hz 50/60 ± 10 % (± 10 %) (± 10 %) Hz 50/60 ± 10 % 92 • up to 1000 m above sea level % • up to 3000 m above sea level % • up to 4000 m above sea level % • up to 4000 m above sea level % 85 • up to 4000 m above sea level % 85 • up to 4000 m above sea level % 85 • up to 4000 m above sea level % 85 • up to 4000 m above sea level % 85 • up to 4000 m above sea level % 85 • up to 4000 m above sea level % 85 • up to 4000 m above sea level % 85 • up to 4000 m above sea level % 85 • up to 4000 m above sea level % 85 • up to 4000 m above sea level % 85 • up to 4000 m above sea level % 85 • up to 4000 m above sea level % 85 • up to 4000 m above sea level % 92 | | |

1) At an altitude from 3000 m, the max. permissible operating voltage for all 3RW30 is reduced to 460 V.

SIRIUS soft starters

| Туре | | | 3RW30 03 | 3RW30 1. | 3RW30 2. | 3RW30 3. | 3RW30 4. | | |
|--|----------------------|--|---|------------------|---------------|---------------|---------------|--|--|
| Size | | | | S00 | S0 | S2 | S3 | | |
| Continuous operation (% of <i>l</i> _e) | | % | 100 | | | | | | |
| Minimum load ¹⁾ (% of <i>I</i> _e); at 40 °C | | 9 | 4 | | | | | | |
| Permissible ambient temperature | Operation Storage | °C ℃ | -25 +60 (derating from 40 °C, see load rating) -25 +80 | | | | | | |
| Switching capacity of the auxiliary contacts | | 230 V/AC-15 A 230 V/DC-13 A 24 V/DC-13 A | No auxiliary co | ntacts available | 3 0.1 1 | 3 0.1 1 | 3 0.1 1 | | |

1) The rated motor current (specified on the motor's name plate) should at least amount to the specified percentage of the SIRIUS soft starter's rated operational current $l_{\rm e}$.

| Туре | | | 3RW30 03 | 3RW30 14 | 3RW30 16 | 3RW3. 24 | 3RW3. 25 | 3RW3. 26 |
|---|---|---|---|---|----------------|-------------------------------|------------|----------|
| Load rating | | | | | | | | |
| Rated operating current Ie | | | | | | | | |
| Acc. to IEC | at 40/50/60 °C, AC-53b | А | - | 6/5/4 | 9/8/7 | 12.5/11/9 | 16/14/12 | 25/21/18 |
| for individual mounting • Acc. to UL/CSA | at 40/50/60 °C, AC-53b | А | - | 4.8/4.8/4 | 7.8/7.8/7 | 11/11/9 | 17.5/14/12 | 25/21/18 |
| for individual mounting Acc. to IEC/UL/CSA for individual mounting | at 40/50/60 °C, AC-53a | А | 3/2.6/2.2 | - | | | | |
| acc. to IEC/UL/CSA for side-by-side mounting | at 40/50/60 °C, AC-53a | А | 2.6/2.2/1.8 | - | | | | |
| Power loss | | | | | | | | |
| at continuous rated operating curr at utilization of max. operating free | | W W | 6.5 3 | 5 5 | 7 6 | 7 7 | 9 8 | 13 9 |
| Permissible starts per hour with | out using a fan | | | | | | | |
| for intermittent duty S4, $T_{\rm u}$ = 40 °C ON-period = 30 % ON-period = 70 % | c, individual mounting vertical | 1/h % / _e /s % / _e /s | 1500 - 300/0.2 | 60 250/2 - | 40 | 30 300/2 | | 12 |
| Permissible starts per hour whe | n using a fan | | | | | | | |
| for intermittent duty S4, $T_{\rm u}$ = 40 °C ON-period = 30 % | , individual mounting, | 1/h | Fans cannot be fitted5421 | | | | | 21 |
| Pause intervals after continuous | s duty | | | | | | | |
| with $I_{\rm e}$ before a new start | | S | 0 | | | | | 200 |
| Degree of protection | acc. to IEC 60529 | | IP20 (IP00 term | inal enclosur | e) | | | |
| Maximum conductor length betw | veen soft starter and motor | m | 100 ¹⁾ | | | | | |
| Conductor cross-sections | | | | | | | | |
| Screw-type terminals | Main conductors | | | | | | | |
| (1 or 2 conductor connections) for standard screw driver | • Solid | mm ² | 1 x (0.5 4); 2 x (0.5 2.5) | 2 x (0.5 1.5); 2 x (1 2.5); 2 x (0.75 2.5) 2 x (2.5 6) | | | | |
| size 2 and Pozidriv 2 | Finely stranded with end sleeve Stranded | mm² mm² | 1 x (0.5 2.5); 2 x (0.5 1.5) - | 2 x (0.5 2 - | 2.5) | 2 x (1 2.5 2 x (2.5 6 - | | |
| | AWG conductors, solid or stranded Terminal screws | AWG | 2 x (20 14) M3, PZ2 | 2 x (18 14 | 4) | 2 x (14 10) M4, PZ2 | | |
| | - Tightening torque | Nm Ib.in | 0.8 1.2 7.1 8.9 | 7 10.3 | | 2 2.2 18 22 | | |
| | Auxiliary conductors | | | | | | | |
| | • Solid | mm ² | 1 x (0.5 4); 2 x (0.5 2.5) | max. 2 x (0. | .75 4) | 5 2.5) to IE | C 60947; | |
| | Finely stranded with end sleeve AWG conductors, | mm ² | 1 x (0.5 2.5); 2 x (0.5 1.5) | 2 x (0.5 1 | .5); 2 x (0.75 | o 2.5) | | |
| | Solid or stranded Terminal screws | AWG | 2 x (20 14) M3, PZ2 | 2 x (18 14 | 4) | | | |
| | - Tightening torque | Nm Ib.in | 0.8 1.2 7 8.9 | 0.8 1 7.1 8.9 | | | | |
| Spring-loaded terminals | Main and auxiliary conductors | | | | | | | |
| | Solid Finely stranded with end sleeve AWG conductors, solid or stranded | mm ² mm ² AWG | 2 x (0.25 1.5) 2 x (0.25 1) 2 x (24 16) | - | | | | |
| | | 7.000 | 2 ~ (27 10) | | | | | |

1) If this value is exceeded, problems with line capacities may arise, which can result in false firing.

SIRIUS soft starters

| Туре | | | 3RW30 34 | 3RW30 35 | 3RW30 36 | 3RW30 44 | 3RW30 45 | 3RW30 46 | |
|--|--|------------------------------------|--|----------------------------------|----------|----------------------------|----------------|-----------|--|
| Power electronics | | | | | | | | | |
| Load rating | | | | | | | | | |
| Rated operating current Ie | | | | | | | | | |
| Acc. to IEC for individual mounting | at 40/50/60 °C, AC-53b | A | 32/27/23 | 38/32/27 | 45/38/32 | 63/54/46 | 75/64/54 | 100/85/72 | |
| Acc. to UL/CSA for individual mounting | at 40/50/60 °C, AC-53b | A | 27/27/23 | 34/32/27 | 42/38/32 | 62/54/46 | 68/64/54 | 99/85/72 | |
| Power loss | | | | | | | | | |
| at continuous rated operating curr at utilization of max. operating free | | W W | 10 11 | 13 11 | 17 10 | 13 18 | 16 29 | 26 26 | |
| Permissible starts per hour whe | en not using a fan | | | | | | | | |
| for intermittent duty S4, $T_{\rm u}$ = 40 °C, individual mounting vertical ON-period = 30 % | | | 20 300/3 | 15 | 5 | 20 300/4 | 30 | 15 | |
| Permissible starts per hour when using a fan | | | | | | | | | |
| for intermittent duty S4, $T_{\rm u}$ = 40 °C, individual mounting, ON-period = 30 % | | | 44 | 27 | 9 | 32 | 48 | 24 | |
| Pause intervals after continuous duty with l _e before a new start s | | | 0 | | 400 | 0 | | | |
| Protection | acc. to IEC 60529 | | IP20 (IP00 te | erminal enclo | sure) | IP20 ¹⁾ | | | |
| Maximum conductor length betw | veen soft starter and motor | m | 100 ²⁾ | | | | | | |
| Conductor cross-sections | | | | | | | | | |
| Screw-type terminals | Main conductors | | | | | | | | |
| (1 or 2 conductor connections) for standard screw driver size 2 and Pozidriv 2 | Solid Finely stranded with end sleeve | mm ² mm ² | 2 x (0.75 16) 2 x (0.75 16) | | | | | | |
| SIZE Z ANU POZIUNY Z | Stranded | mm ² | 1 x (0.75 25) 2 x (0.75 25) 1 x (0.75 35) 1 x (10 70) | | | | | | |
| | AWG conductors, solid or stranded Terminal screws | AWG | 2 x (18 3) M6, box terr | ; 1 x (18 2) | | 2 x (101/0) 1 x (10 2/0) | | | |
| | - Tightening torque | Nm Ib.in | 3 4.5 27 40 | 11111di, 1 ZZ | | M6 (Inbus) 4 6 35 53 | | | |
| | Auxiliary conductors | | | | | | | | |
| | Solid Finely stranded with end sleeve | mm ² mm ² | | .5); 2 x (0.75 .5); 2 x (0.75 | | l. to IEC 6094 | 7; max. 2 x (0 | .75 4) | |
| | AWG conductors, solid or stranded | AWG | 2 x (18 14 | 1) | | | | | |
| | Terminal screws Tightening torque | Nm Ib.in | M3 0.8 1 7.1 8.9 | | | | | | |

1) IP20 only with installed box terminal ('as-delivered'). Without box terminal IP00.

If this value is exceeded, problems with line capacities may arise, which can result in false firing.

Standard Parameters Electromagnetic compatibility acc. to EN 60947-4-2 EMC interference immunity IEC 61000-4-2 Degree of severity 3: 6/8 kV Electrostatic discharge (ESD) Frequency range: 80 ... 1000 MHz with 80 % at 1 kHz Degree of severity 3, 10 V/m IEC 60947-4-2 Electromagnetic RF fields Frequency range: 80 ... 1000 MHz with 80 % at 1 kHz 10 V at 0.15 ... 80 MHz 3 V at 10 kHz ... 80 MHz **Conducted RF interference** IEC 61000-4-6 IEC 60947-4-2 SN-IACS Burst IEC 61000-4-4 Degree of severity 3: 1/2 kV Surge IEC 61000-4-5 Degree of severity 3: 1/2 kV EMC emitted interference Class B limit at 30 ... 1000 MHz CISPR 11/09. 1990 EMC interference field strength CISPR 11/09. 1990 IEC 60 947-4-2 (0.15 ... 30 MHz): Device Class A (industrial) Radio interference voltage

3) No suppression filter is required for 3RW30 03.

SIRIUS soft starters

Is an RI suppression filter necessary?

| | 24 V AC/DC control voltage | e | 110 240 V AC/DC control voltage | | | |
|---|----------------------------|-----------------|--|-----------------------|--|--|
| | Main circuit | Control circuit | Main circuit | Control circuit | | |
| Degree of noise suppression A (industrial applications) | No | No | No | No | | |
| Degree of noise suppression B (applications for residential areas) | No | No | Yes ²⁾³⁾ (see table of recommended filters) | Yes ¹⁾²⁾³⁾ | | |

1) "No" only applies if the control voltage is taken from the main circuit down-stream of the RI suppression filter.

2) It may be preferable to use a device with 24 V AC/DC control voltage here; in that case the control voltage must be adapted with a transformer.

| Soft starter type | Rated current | Recommended fil | ters | | | | | | |
|-------------------|---------------|-------------------|----------------------|----------------------|-------------------------|----------------------|----------------------|--|--|
| | Soft starter | Voltage range 200 | 460 V | | Voltage range 460 575 V | | | | |
| | | Filter type | Rated current filter | Connection terminals | Filter type | Rated current filter | Connection terminals | | |
| | A | | A | mm ² | | A | mm ² | | |
| 3RW30 14 | 6 | B84143-G8-R110 | 8 | 4 | - | - | - | | |
| 3RW30 16 | 9 | B84143-G20-R110 | 20 | 4 | - | - | - | | |
| 3RW30 24 | 12.5 | B84143-G20-R110 | 20 | 4 | B8413-A25-R21 | 25 | 10 | | |
| 3RW30 25 | 16 | B84143-G20-R110 | 20 | 4 | B8413-A25-R21 | 25 | 10 | | |
| 3RW30 26 | 25 | B84143-G36-R110 | 36 | 6 | B8413-A25-R21 | 25 | 10 | | |
| 3RW30 34 | 32 | B84143-G36-R110 | 36 | 6 | B8413-A36-R21 | 36 | 10 | | |
| 3RW30 35 | 38 | B84143-G36-R110 | 36 | 6 | B8413-A36-R21 | 36 | 10 | | |
| 3RW30 36 | 45 | B84143-G50-R110 | 50 | 6 | B8413-A50-R21 | 50 | 10 | | |
| 3RW30 44 | 63 | B84143-G66-R110 | 66 | 25 | B8413-A80-R21 | 80 | 25 | | |
| 3RW30 45 | 75 | B84143-G120-R110 | 120 | 50 | B8413-A80-R21 | 80 | 25 | | |
| 3RW30 46 | 100 | B84143-G120-R110 | 120 | 50 | B8413-A120-R21 | 120 | 50 | | |

Contact address: The suppression filters mentioned above can be ordered from EPCOS AG (see Appendix -> External Partners).

SIRIUS soft starters

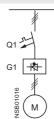
Fuse assignment

3



soft starter) is sufficient. If type 2 coordination is to be fulfilled, semiconductor fuses must be fitted in the motor feeder.



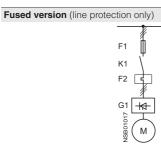


| Soft starter | Circuit-breaker ¹⁾ | Link module ²⁾ |
|----------------------|--|---------------------------|
| Туре | Туре | Туре |
| G1 | Q1 | |
| Type of coordination | n 1 ³⁾ : <i>I</i> _q = 50 kA at 400 V | |
| 3RW30 03 | 3RV10 11 | |
| 3RW30 14 | 3RV10 11 | 3RA19 11-1A |
| 3RW30 16 | 3RV10 11 | 3RA19 11-1A |
| 3RW30 24/3RW31 24 | 3RV10 21 | 3RA19 21-1A |
| 3RW30 25/3RW31 25 | 3RV10 21 | 3RA19 21-1A |
| 3RW30 26/3RW31 26 | 3RV10 21 | 3RA19 21-1A |
| 3RW30 34 | 3RV1031 | 3RA19 31-1A |
| 3RW30 35 | 3RV1031 | 3RA19 31-1A |
| 3RW30 36 | 3RV1031 | 3RA19 31-1A |
| 3RW30 44 | 3RV10 41 | 3RA19 41-1A |
| 3RW30 45 | 3RV10 41 | 3RA19 41-1A |
| 3RW30 46 | 3RV10 41 | 3RA19 41-1A |

1) The rated motor current defines the selection of units.

The types of coordination are explained in more detail under Load Feeders
 -> Fuseless Load Feeders.

2) Pay attention to quantity units.



| Soft starter | Line protection | | | Overload relay | | Contactor |
|---|--|--|---|--|--|--|
| Туре | Туре | Rated current | Size | Thermal type | Solid-state type | Туре |
| 51 | 7 1 | | | | .71. | 71. |
| G1 | F1 | | | F2 | | K1 |
| | | A | | | | |
| Type of coordination 1 ¹ | ⁾ : <i>I</i> _q = 50 kA at 400 V | | | | | |
| 3RW30 03 3RW30 14 3RW30 16 3RW30 24/3RW31 24 3RW30 25/3RW31 25 3RW30 26/3RW31 26 3RW30 34 3RW30 34 3RW30 35 3RW30 36 3RW30 45 | 3NA3 805 ²⁾ 3NA3 807 3NA3 807 3NA3 807 3NA3 810 3NA3 814 3NA3 822 3NA3 822 3NA3 822 3NA3 822 3NA3 824 3NA3 830 3NA3 132 | 20 20 20 25 35 63 63 63 80 100 125 | 000 000 000 000 000 000 000 000 000 00 | 3RU11 16 3RU11 16 ³⁾ 3RU11 26 ⁴⁾ 3RU11 26 ⁴⁾ 3RU11 26 ⁴⁾ 3RU11 26 ⁴⁾ 3RU11 36 ⁴⁾ 3RU11 36 ⁴⁾ 3RU11 36 ⁴⁾ 3RU11 36 ⁴⁾ 3RU11 46 ⁴⁾ | 3RB10 16 3RB10 16 ³⁾ 3RB10 26 ⁴⁾ 3RB10 26 ⁴⁾ 3RB10 26 ⁴⁾ 3RB10 26 ⁴⁾ 3RB10 36 3RB10 36 3RB10 36 3RB10 46 | 3RT10 15 3RT10 15 3RT10 16 3RT10 24 3RT10 25 3RT10 26 3RT10 34 3RT10 35 3RT10 35 3RT10 36 3RT10 44 3RT10 45 |
| 3RW30 45 3RW30 46 | 3NA3 132 3NA3 140 | 200 | 1 | 3RU11 46 ⁴⁾ | 3RB10 46 | 3RT10 45 3RT10 46 |

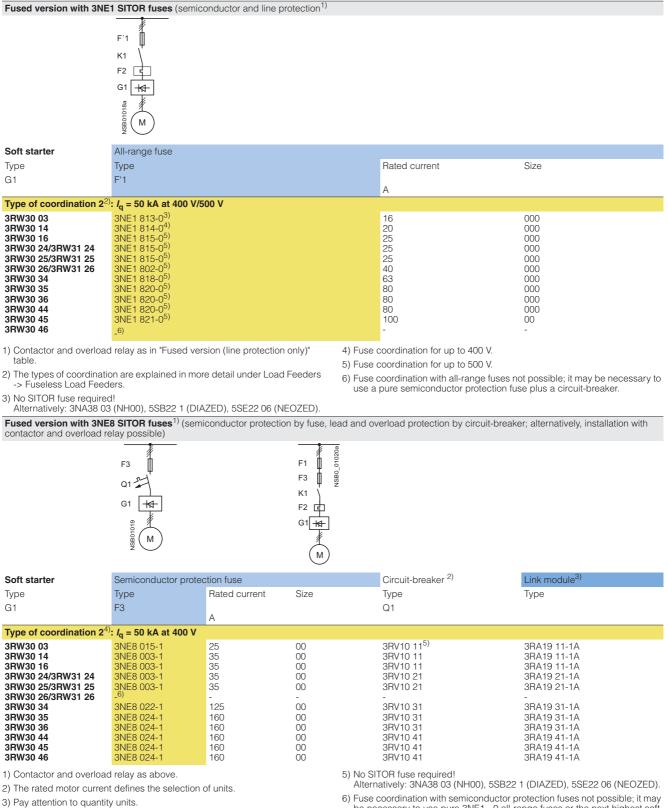
1) The types of coordination are explained in more detail under Load Feeders -> Fuseless Load Feeders.

2) 3NA38 05-1 (NH00), 5SB26 1 (DIAZED), 5SE22 01-06 (NEOZED).

3) $I_{\rm q} = 50$ kA up to max. of 400 V.

4) $I_{\rm q} = 50$ kA up to max. of 500 V.

SIRIUS soft starters



4) The types of coordination are explained in more detail under Load Feeders -> Fuseless Load Feeders

6) Fuse coordination with semiconductor protection fuses not possible; it may be necessary to use pure 3NE1..-0 all-range fuses or the next highest soft starter

SIRIUS soft starters

| Selection | and ord | ering | uata | | | | | | | | | | | | 4 | |
|--|---|--------------------------|---------------------------------|---|---------------------|---|---------------------------|---------------------------------------|------------------------|-----------|-------------|------------------|--------|--|------------------|-----------------------------|
| | | | | | I U | | | | | | - - A | | | | RW30 35- | |
| 3RW30 03-20 | | | | | 0 25-1A | | | | | 0 35-1A | B14 | _ | | | | |
| Rated oper- ating volt- age U _e | At ambie Rated operat- ing cur- rent <i>I</i> e | Rated induct opera | output tion mot ting volt | of three- ors for ra age <i>U</i> e | ated | At ambie Rated operat- ing cur- rent <i>I</i> e | Rated tion m voltag | output lotors foi le <i>U</i> e | of three- r rated c | peratin | g | Size | DT | Order No. | PS* | Weight per PU approx. |
| V | А | 115 V kW | 230 V kW | 400 V kW | 500 V kW | A | | 200 V | | | 575 V | | | | | ka |
| v Soft starte | | | | | | | hp peratin | hp na frea | hp uency | hp | hp | | | | | kg |
| 200 400 | 3 | - | 0.55 | 1.1 | - | 2.6 | - | 0.5 | 0.5 | - | - | | | 3RW30 03-□CB54 | 1 unit | 0.200 |
| | Order N | o. exter | nsion fo | r conne | ction m | nethod ¹⁾ | | | | | | | | | | |
| Coff should | with scr with spr | ing-load | led term | inals | | | | | | | | 22.5 m 22.5 m | | 1 2 | | |
| Soft starte 200 460 | 6 | iree-pr | 1.5 | 3 | | 4.8 | | 1 | 1 | 3 | _ | S00 | | 3RW30 14-1CB□4 | 1 unit | 0.302 |
| 200 400 | 9 | - | 2.2 | 4 | - | 7.8 | - | 2 | 2 | 5 | - | S00 | | 3RW30 16-1CB | 1 unit | 0.302 |
| | 12.5 16 | - | 3 4 | 5.5 7.5 | - | 11 14 | - | 3 3 | 3 3 | 7.5 10 | - | S0 S0 | | 3RW30 24-1AB□4 3RW30 25-1AB□4 | 1 unit 1 unit | 0.490 0.481 |
| | 25 | - | 5.5 | 11 | - | 21 | - | 5 | 5 | 15 | - | S0 | | 3RW30 26-1AB | 1 unit | 0.489 |
| | 32 38 | - | 7.5 11 | 15 18.5 | - | 27 32 | - | 7.5 10 | 7.5 10 | 20 25 | - | S2 S2 | | 3RW30 34-1AB□4 3RW30 35-1AB□4 | 1 unit 1 unit | 0.794 0.779 |
| | 38 45 | - | 11 | 22 | - | 32 38 | - | 10 | 15 | 30 | - | 52 S2 | | 3RW30 35-1AB | 1 unit | 0.791 |
| | 63 | - | 18.5 | 30 | - | 54 | - | 15 | 20 | 40 | - | S3 | | 3RW30 44-1AB□4 | 1 unit | 1.660 |
| | 75 100 | - | 22 30 | 37 55 | - | 64 85 | - | 20 25 | 25 30 | 50 60 | - | S3 S3 | | 3RW30 45-1AB□4 3RW30 46-1AB□4 | 1 unit 1 unit | 1.800 1.810 |
| 460 575 | 12.5 | - | - | - | 7.5 | 11 | - | - | - | 7.5 | 10 | S0 | | 3RW30 24-1AB | 1 unit | 0.490 |
| | 16 25 | - | - | - | 11 15 | 14 21 | - | - | - | 10 15 | 10 20 | S0 S0 | | 3RW30 25-1AB□5 3RW30 26-1AB□5 | 1 unit 1 unit | 0.489 0.489 |
| | 32 | - | - | - | 18.5 | 27 | - | - | - | 20 | 25 | S2 | | 3RW30 34-1AB | 1 unit | 0.791 |
| | 38 45 | - | - | - | 22 30 | 32 38 | - | - | - | 25 30 | 30 40 | S2 S2 | | 3RW30 35-1AB□5 3RW30 36-1AB□5 | 1 unit 1 unit | 0.793 0.792 |
| | 63 | - | - | - | 37 | 54 | - | - | - | 40 | 50 | S3 | | 3RW30 44-1AB | 1 unit | 1.660 |
| | 75 100 | - | - | - | 55 70 | 64 85 | - | - | - | 50 60 | 60 75 | S3 S3 | 2) | 3RW30 45-1AB□5 3RW30 46-1AB□5 | 1 unit 1 unit | 1.810 1.800 |
| | | | nsion fo | r rated | control | supply ve | oltage U | l _s | | | | | | | | |
| | AC/DC 2 AC/DC | | 30 V | | | | | | | | | | | 0 | | |
| Soft starte (double po | rs with | two-ra | | ntrol fo | r three | -phase i | nducti | on mo | tors wi | ith two | speed | S | | | | |
| | | | upply v | oltage | U _s AC 1 | 10 230 | V | | | | | | | • | | |
| 200 460 | 12.5 | - | 3 | 5.5 | - | 11 | - | 3 | 3 | 7.5 | - | S0 | A | 3RW31 24-1CB14 | 1 unit | 0.468 |
| | 16 25 | - | 4 5.5 | 7.5 11 | - | 14 21 | - | 3 5 | 3 5 | 10 15 | - | S0 S0 | A A | 3RW31 25-1CB14 3RW31 26-1CB14 | 1 unit 1 unit | 0.475 0.464 |
| 460 575 | 12.5 | - | - | - | 7.5 | 11 | - | - | - | 7.5 | 10 | S0 | A | 3RW31 24-1CB15 | 1 unit | 0.467 |
| | 16 25 | - | - | - | 7.5 15 | 14 21 | - | - | - | 10 15 | 10 20 | S0 S0 | C A | 3RW31 25-1CB15 3RW31 26-1CB15 | 1 unit 1 unit | 0.476 0.475 |
| Soft starte | rs for si | ngle-p | hase n | notors | | | | | | | | | | | | |
| 115 240 | 25 38 | 2.2 3 | 4 5.5 | - | - | 21 32 | 1.5 | 3 5 | 3 5 | - | - | S0 S2 | A | 3RW30 26-1AA12 3RW30 35-1AA12 | 1 unit | 0.439 0.729 |
| | 38 75 | 3 5.5 | 5.5 11 | - | - | 32 64 | 2 5 | 5 10 | 5 10 | - | - | 52 S3 | A | 3RW30 35-1AA12 3RW30 45-1AA12 | 1 unit 1 unit | 1.390 |
| 1) The units v 2) 3RW30 46- | | | | | | | d-2004. | | | | | | | soft starters are de $0 \times J_{Motor}$. In the ev | | |

2) 3RW30 46-1AB05 soft starters (AC/DC 24 V version): Delivery time on request.

Selection of the soft starter depends on the motor's rated current.

The SIRIUS 3HW3 solid-state soft starters are designed for easy starting conditions. $J_{\text{Load}} < 10 \times J_{\text{Motor}}$. In the event of deviating conditions or increased switching frequency, it may be necessary to choose a larger unit. Siemens recommends the use of the selection and simulation program Win-SIKOSTART. See Technical specifications for information about rated currents for ambient temperatures >40 °C.

SIRIUS soft starters

Accessories

| | For soft starters Type | Size | Version | DT | Order No. | PS* | Weight per PU approx. kg |
|-----------------------|--------------------------------------|-----------------|---|----|--------------------------------|------------------|-----------------------------------|
| Fans ¹⁾ | 3RW3. 2. 3RW30 3. and 3RW30 4. | S0 S2 S3 | To increase switching frequency and for unit mounting in positions different from the nor- mal position. | | 3RW39 26-8A 3RW39 36-8A | 1 unit 1 unit | 0.008 0.030 |
| 3RW39 26-8A | | | The fan is snapped into the enclosure from below. During operation, (control signal input "IN" at potential A1), the fan is running. After a stop, the fan continues to run for about another 60 minutes. | | | | |
| 3RW39 36-8A Covers | | | | | | | |
| | Terminal cov | er for box terr | ninals | | | | |
| 3BT19 36-4EA2 | 3RW30 3. 3RW30 4. | S2 S3 | Additional shock-hazard protection for fitting to box terminals (2 units required per contactor) | • | 3RT19 36-4EA2 3RT19 46-4EA2 | 1 unit 1 unit | 0.020 0.017 |
| 511119 50-4EAZ | Terminal cov | er for cable lu | g and busbar connection | | | | |
| 3BT19 46-4EA1 | 3RW30 4. | S3 | For complying with the phase clearances and as shock-hazard protection in the case of a distant box terminal (2 units required per con- tactor) | | 3RT19 46-4EA1 | 1 unit | 0.037 |
| JIII 13 40-4LAI | | | | | | | |

| | Version | Functionality Functions | Application | DT | Order No. | PS* | Weight per PU approx. |
|------------------------------|---------------------------------|--|--|----|-----------|-------------|-----------------------------|
| | | | | | | | kg |
| Covering cap and plug-in lug | (only for 3RW | 30 03) | | | | | |
| | Sealable cap | for securing against unauthorized maladjustment of setting knobs | for units with 1 or 2 changeover contacts | • | 3RP19 02 | 5 units | 0.019 |
| | Push-in lug for screw fixing | | for units with 1 or 2 changeover contacts | • | 3RP19 03 | 10 units | 0.018 |

SIRIUS soft starters

| | For soft starters | Size | Version | DT | Order No. | PS* | Weight per PU approx. |
|--------------|--|-----------------------------------|--|----|--|--------------------------------------|----------------------------------|
| | Туре | | | | | | kg |
| Link modules | | | | | | _ | |
| 3RA19 11-1A | Individually 3RW30 1 3RW30 2 3RW30 3 3RW30 4 Multi-pack | packaged S00 S0 S2 S3 | Electrical and mechanical link between circuit-breaker and soft starter. | | 3RA19 11-1AA00 3RA19 21-1AA00 3RA19 31-1AA00 3RA19 41-1AA00 | 1 unit 1 unit 1 unit 1 unit | 0.027 0.037 0.042 0.090 |
| | 3RW30 1 | S00 | | | 3RA19 11-1A | 10 units | 0.193 |
| 3RA19 21-1A | 3RW30 2 | S0 | | | 3RA19 21-1A | 10 units | 0.276 |
| | 3RW30 3 3RW30 4 | S2 S3 | | | 3RA19 31-1A 3RA19 41-1A | 5 units 5 units | 0.163 0.366 |

3RA19 31-1A

Note: The covers and connection modules listed here are also used for (2014 http://www.brooker.u.387.contactor). load feeders (3RV circuit-breaker + 3RT contactor).

For further technical specifications see Controlgear -> Contactors and contactor assemblies. For fuseless load feeders with size S00 soft starter, the link module has an integrated conductor routing.

| | Designation | Labeling area/color | DT | Order No. | PS* | Weight per PU approx. |
|-----------------------|--|----------------------------|----|----------------|---------------|-----------------------------|
| | | W x H mm x mm | | | | kg |
| Blank labeling plates | | | | | | |
| | Item code labels for "SIRIUS ^{"1)} | 20 x 7 pastel turquoise | А | 3RT19 00-1SB20 | 340 units | 0.067 |
| | "SIRIUS" labels for sticking | 19 x 6 pastel turquoise | D | 3RT19 00-1SB60 | 4700 units | 0.003 |
| | | 19 x 6 zinc yellow | С | 3RT19 00-1SD60 | 4700 units | 0.003 |

Item code labels 1 frame = 20 labels

1) Computer labeling system for individual labeling of device labeling plates available from: murrplastik Systemtechnik GmbH (see Appendix -> External Partners).

SIRIUS soft starters

| | For soft starters | Version | | DT | Order No. | PS* | Weight per PU approx. |
|--|--------------------|--|---|--------|--|--------------------------------------|----------------------------------|
| AS-Interface load feeder | Type | | | | | | kg |
| | modules | AS-Interface load feeder modules for mounting onto standard mounting Sizes S00 and S0 For mounting onto 40 mm or 60 mm bi SIRIUS standard rail adapters, the ma required (see 3RK1 901-3GA00) The AS-Interface connectors for the c power cable (yellow and black) must rately (see 3RK1 901-0.A00) 2 inputs/1 output/DC 24 V ¹¹ 4 inputs/2 outputs/DC 24 V ¹¹ 2 inputs/1 relay outputs AC 120/230 V ² 3 inputs/2 relay outputs AC 120/230 V ² | usbar systems and atching support is lata and auxiliary be ordered sepa- | | 3RK1 400-1KG01-0AA1 3RK1 400-1MG01-0AA1 3RK1 402-3KG02-0AA1 3RK1 402-3LG02-0AA1 | 1 unit 1 unit 1 unit 1 unit | 0.097 0.100 0.124 0.134 |
| 3RK14 00-1KG01-0AA1 3RK14 00-1MG01-0AA1 | | | | | | | |
| | | Manual for AS-Interface load feeder module | | | | | |
| | | German, English Italian, French | | ► A | 3RK1 701-2GB00-0AA0 3RK1 701-2HB00-0AA0 | 1 unit 1 unit | 0.197 0.196 |
| | | Support for AS-Interface load feeder module | | | | | |
| | | for mounting onto 3RA19 22-1A SIRIUS standard mounting rail adapter | 45 mm | Х | 3RK1 901-3GA00 | 1 unit | 0.048 |
| Support with mounted power | | Power connector set 5-pin, 2.5 mm ² (1 package = 5 connectors and 5 couplers) | | A | 3RK1 901-0EA00 | 5 units | 0.111 |
| connector coupling | | AS-Interface connector for data | | | | | |
| A PART | | and auxiliary supply cables with overlapping terminals for 2 x | yellow | | 3RK1 901-0NA00 | 5 units | 0.015 |
| 3RK19 01-0NA00 | | (0.5 to 0.75 mm ²) flexible lead with overlapping terminals for 2 x (0.5 to 0.75 mm ²) flexible lead | black | | 3RK1 901-0PA00 | 5 units | 0.015 |
| 3RK19 01-0PA00 Standard mounting rail a | dapter | | | | | | |
| | 3RW30 1. | Standard mounting rail adapter for mechanical mounting of circuit- breaker and contactor; can be snapped onto standard rail or for screw mounting, suitable for size S00 | | • | 3RA19 22-1A | 5 units | 0.474 |
| 3RA19 22 Surge suppressor - RC e | lement for PLC | control | | | | | |
| 3TX7 462-3. | | RC element For lateral snapping onto auxiliary switch or 35 mm standard mounting rail | AC 127 V 240 V | | 3TX7 462-3T | 1 unit | 0.080 |
| 1) Without connectors for data | and auxiliary powe | r (yellow and black). | | | | | |

2) With one connector each for data and auxiliary power (yellow and red).

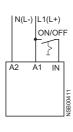
For busbar accessories, see Load feeders -> Busbar Adapter System.

SIRIUS soft starters

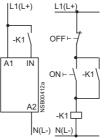
Circuit diagrams

Connection examples for actuation with switches or auxiliary contacts

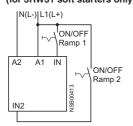
Control via switch



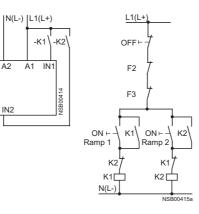
Control via contactor contacts (for control of size S00 with buttons)



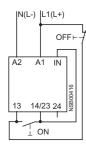
Control via contacts in versions for pole-changing motors (for 3RW31 soft starters only)



Control via contactor contacts in versions for pole-changing motors (for 3RW31 soft starters only)



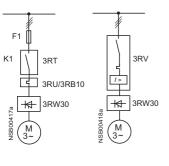
Connection example for control with pushbuttons (sizes S0, S2, and S3 only)

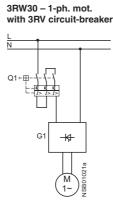


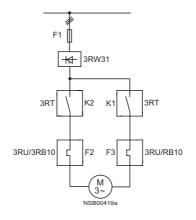
SIRIUS soft starters

Connection examples for main circuit ¹⁾

3RW30 – 3-ph. mot. 3RW30 – 3-ph. mot. with overload relay with circuit-breaker







3RW31

Connection example for AS-Interface load feeder with SIRIUS soft starter Main circuit Control circuit

L1 3/N/PE 50 Hz 230/400 V L2 L3 G1 PE 1 A1 Q1 A2 Adapter for rail mounting Q1⊢⊞ X4.1 X3.2 4 X3.1 X3.3 X4.2 6 IN 1 IN 2 M/N OUT 1 IN + G1 L1 L2 L3 UC= 110-230 V AS-i application module 3RK1400 - 1KG01 - 0AA1 3RK1402 - 3KG02 - 0AA1 A2 -\$ M/N L+/L 2 X1.1 X1.2 22a X Power supply U prim x V/ U sec. 24 V or 230 V AC Q1 = circuit-breaker G1 = SIRIUS soft starter 3RW30 1. X5 = power supply connector

1) As an alternative, the motor feeder can also be installed as a fuseless or as a fused version. For details of fuse and switching device coordination, see page 3/44 and 3/45. The wiring diagrams are provided only as examples.

SIRIUS soft starters

Further information

Configuration

The 3RW solid-state soft starters are designed for easy starting conditions. In the event of deviating conditions or increased switching frequency, it may be necessary to choose a larger device. For accurate dimensioning, use the Win-SIKOSTART selection and simulation program.

If necessary, an overload relay for heavy-starting must be selected where long starting times are involved. PTC thermistor detectors are recommended. This also applies to smooth rampdown. In this case an additional current load is effective compared with a free running down.

In the motor feeder between the SIRIUS 3RW3 soft starter and the motor, no capacitive elements are permitted (e.g. no compensation equipment).

All elements of the main circuit (such as fuses, switching devices and overload relays) should be dimensioned for direct starting, following the local short-circuit conditions. Fuses, switching devices and overload relays must be ordered separately. Please observe the maximum switching frequencies specified in the technical specifications.

Power electronics circuit diagram¹⁾

Control with a PLC

When a 3RW30 is operated with a Triac output or thyristor output, the residual current at the PLC output should be < 1 mA because otherwise the 3RW30 will interpret the resultant voltage drop at the input as an "On" command. As a corrective measure for PLC outputs with a higher residual current, an RC element with > 100 nF and 220 W can be connected in series between "IN1" and terminal "A2" of the 3RW30 (Order No.: 3TX7 462-3T see page 3/49).

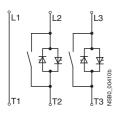
Selection and simulation program Win-SIKOSTART

With this software, you can simulate and select all Siemens soft starters, taking into account various parameters such as mains properties, motor and load data, and special application requirements.

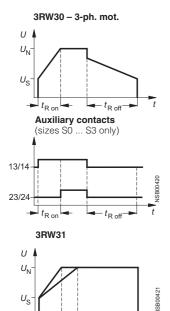
The software is a valuable tool, which makes complicated, lengthy manual calculations for determining the required soft starters superfluous.

You can order the CD-ROM under the following order number: Order No.: E20001-D1020-P302-X-7400.

For more information on the Internet go to www.siemens.de/sanftstarter



Status graphs



 $\rightarrow t_{R1} \bullet t_{R2}$

1) Circuit diagram applies to sizes S0 and S2; for size S00, phase L3 is bridged, for size S3, phase L2 is bridged.

SIKOSTART soft starters

Functions

- Soft starting with voltage ramp; the starting voltage adjustment range $U_{\rm S}$ is 30 % to 80 % and the ramp time $t_{\rm R}$ can be set from 0.5 s to 60 s.
- Smooth ramp-down with voltage ramp; the running down time $t_{\rm off}$ can be set between 0.5 s to 60 s. Whereby the switch-off voltage $U_{\rm off}$ is dependent on the selected starting voltage $U_{\rm s}$.
- Setting with three potentiometers
- Simple mounting and commissioning
- Mains voltages at 50/60 Hz 200 V to 600 V
- \bullet Three control voltage variants for DC 24 V, AC 115 V and AC 230 V
- Extended temperature range: 0 ... +60 °C

Overview

SIKOSTART 3RW34

Just as easily as with the SIRIUS soft starters, three-phase asynchronous motors with rated operating power of up to 1000 kW (at 400 V) can be controlled with SIKOSTART 3RW34. Soft starting and soft deceleration are standard functions of this device. Fast commissioning, small sizes and simple installation are the key benefits here.

The devices can be operated with two different contact sequences:

• Inline circuit

Inside-delta circuit

Area of application

The 3RW34 solid-state soft starters are suitable for soft starting and stopping of three-phase asynchronous motor.

Service range

Pumps, compressors, conveyors, and much more.

Technical specifications

| Туре | | | | 3RW340DC2. | 3RW340DC3. | 3RW340DC4. |
|--|----------------------------------|-------------------------|--------|--|----------------------|----------------------|
| Control electronics | | | | | | |
| Rated control supply voltage | | X1/X2 | V | 24 DC +10 %/-15 % | 115 V AC +10 %/-15 % | 230 V AC +10 %/-15 % |
| Rated frequency | | | Hz | - | Operating range 45 | 66 |
| Operating indications (continuous light) | | LED 1 LED 2 | | Ready Starting terminated | 7 | |
| Interference/status indication Flash mode 1 (flashing frequency 2 3 Hz) | | LED 1 LED 2 | | Missing phase Starting/running down | | |
| Fault indications Flash mode 2 (flashing frequency 2 3 Hz with 1 s pause) | | LED 1 LED 2 | | EEPROM parity fault Thyristor fault or no loa | d connected | |
| Control input | Input 1 | A1/A2 | | ON | | |
| Control outputs | Output 1 Output 2 Output 3 | 13/14 27/28 37/38 | | Status indication (NO) Starting end indication Group fault signal (par | | |
| Current-carrying capacity of the control outputs (solid-state) | 230 V/AC-15 24 V/DC-13 | | A A | 1.0 0.5 | | |

| Туре | | | 3RW340DC.4 | 3RW340DC.5 | | | |
|---|-----------------------|----------|--|----------------------|--|--|--|
| Power electronics | | | | | | | |
| Operating range for inline circuit Rated voltage | | | 200 460 (-15 %/+10%) | 400 600 (-15 %/+10%) | | | |
| Operating range for inside-delta circuit Rated voltage | | V | 200 400 (-15 %/+10%) | 400 600 (-15 %/+10%) | | | |
| Rated frequency | | | Operating range 45 66 | | | | |
| Continuous operation at 40° C (% of I _e) | | | 115 100 (for 3RW34 84 and 3RW34 86 | ;) | | | |
| Max. starting time for starting current (% of $\mathit{I}_{e})$ | | | To determine the best contactor for your application, Siemens recommends use of Win-SIKOSTART. (Order No. E2001-D1020-P302-X7400). This program is also contained on the CA01. | | | | |
| Minimum load ¹⁾ (% of l _e) | | % | 4 | | | | |
| Permissible ambient temperature | Operation Storage | °C °C | 0 +60 (derating from 40 °C, see 0 +70 | e load rating) | | | |
| Permissible installation altitude | | | up to 3 000 m above sea level over 1000 m above sea level linear reduction of $l_{\rm e}$, thus at 2000 m above sea level 0.87 x $l_{\rm e}$ and at 3000 m above sea level 0.77 x $l_{\rm e}$ | | | | |
| Mounting position | | | The soft starters have been designed for operation on a vertical mounting surface (+12°/-12°). | | | | |
| Maximum conductor length between so | oft starter and motor | m | 300 ²⁾ | | | | |
| Degree of protection | | | IP20 (connection terminals IP00) | | | | |

 The rated motor current (specified on the motor's name plate) should amount to at least 4 % of the SIKOSTART unit's rated current l_e.

 If this value is exceeded, problems with line capacities may arise, which can result in false firing.

SIKOSTART soft starters

| Туре | | | 3RW34 54 | 3RW34 55 | 3RW34 57 | 3RW34 58 | 3RW34 65 | 3RW34 66 |
|--|---|------------------------------------|--|----------------------------|-----------|------------|----------------------------|-------------|
| Load rating | | | | | | | | |
| Rated operating current $l_e^{1)}$ | at 40/50/60 °C, AC-53a | А | 57/42/35 | 70/57/42 | 110/81/57 | 135/110/81 | 162/135/110 | 195/162/135 |
| Power loss at rated operating current (40 °C) approx. W | | | 158 | 190 | 306 | 358 | 493 | 515 |
| Permissible starts per hourfor intermittent duty S4 $T_{\rm u}$ = 40 °CON-period = 30 % and 300 % x $I_{\rm e}$ for 10 s | | | 20 | | - | - | - | |
| Conductor cross-sections | | | | | | | | |
| Screw-type terminals | Main conductors | | | | | | | |
| (1 or 2 conductor connections) for standard screw driver size 2 and Pozidriv 2 | Stranded | mm ² | 95 | | | 120 | 150 | 240 |
| | Auxiliary conductors | | | | | | | |
| | Solid Finely stranded with end sleeve | mm ² mm ² | | | | | | 75 4) |
| | AWG conductors, solid or stranded Terminal screws Tightening torque | AWG Nm | i 2 x (18 14) M 3 0.8 1.2 (7 10.3 lb.in) | | | | | |
| Rated control supply currents Control inputs | | 24 V mA 30 V mA | approx. 45 approx. 13 | | | | | |
| Fans | | 24 V mA 30 V mA | | approx. 400 approx. 200 | | | approx. 200 approx. 140 | |

1) The rated operating current in the inline circuit is specified.

| Туре | | | 3RW34 67 | 3RW34 72 | 3RW34 83 | 3RW34 84 | 3RW34 86 |
|--|--|------------------------------------|----------------------------|----------------------------|----------------------------|-----------------|--------------|
| Load rating Rated operating current <i>I</i> e ¹⁾ | at 40/50/60 °C, AC-53a | А | 235/195/162 | 352/285/235 | 500/450/352 | 700/608/500 | 1050/865/726 |
| Power loss at rated operating current (40 °C) approx. W | | | 629 | 1023 | 1425 | 2020 | 2949 |
| Permissible starts per hourfor intermittent duty S4 $T_{\rm u}$ = 40 °CON-period = 30 % and 300 % x $l_{\rm e}$ for 10 s | | | 20 | | | | |
| Conductor cross-sections | | | | | | | |
| Screw-type terminals (1 or 2 conductor connections) for standard screw driver size 2 and Pozidriv 2 | Main conductors Stranded Auxiliary conductors Solid Solid | mm ² mm ² | | ; 2 x (0.75 2.5 | | 60947; max. 2 × | s (0.75 4) |
| | Finely stranded with end sleeve AWG conductors, solid or stranded Terminal screws Tightening torque | AWG Nm | M3 | | | | |
| | Connecting busbar ²⁾ | | - | , | 40 x 10 | | 50 × 20 |
| Rated control supply currents Control inputs | | 24 V mA 30 V mA | approx. 45 approx. 13 | | | | |
| Fans | | 24 V mA 30 V mA | approx. 200 approx. 140 | approx. 450 approx. 280 | approx. 700 approx. 420 | | |

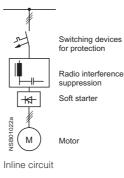
1) The rated operating current in the inline circuit is specified.

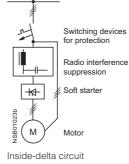
2) The busbars must not be connected directly to the soft starter. Flexible busbar connection pieces must be used for the connection.

SIKOSTART soft starters

| Radio interference suppression | | |
|--|----------------------------------|--|
| | Standard | Parameters |
| Noise immunity | | |
| Electrostatic discharge (ESD) | IEC 61000-4-2, EN 60947-4-2 | Pulse shape: 1/60 ns Test severity 6 kV or 8 kV 4 kV charging voltage in the event of contact discharge 8 kV charging voltage in the event of air discharge |
| Electromagnetic RF fields | IEC 61000-4-3, EN 60647-4-2 | Frequency range: 80 MHz 1000 MHz with 80 % at 1 kHz field strength 10 V/m |
| Conducted low-frequency interference (harmonics) | IEC 60 947-4-2 | Frequency range: 50 Hz 10 kHz |
| RF-voltages and RF-currents on conductors | IEC 61000-4-6, EN 60947-4-2 | Frequency range: 80 MHz1000 MHz with 80 % at 1 kHz 10 V at 0.15 MHz 80 MHz |
| Burst | IEC 61000-4-4 | Test severity: 2 kV or 1 kV |
| Surge | IEC 61000-4-5 | Test severity: 2 kV or 1 kV |
| Emitted interference | | |
| Radio interference field strength | CISPR 11/09.1990 EN 60947-4-2 | H field: 150 kHz 30 MHz E field: 30 MHz 1000 MHz limit value of Class B at 30 MHz 1000 MHz |
| Radio interference voltage | CISPR 11/09.1990 EN 60947-4-2 | Frequency range: 9 kHz 30 MHz (0.15 MHz 30 MHz): Unit Class A (industry) and unit Class B (public networks) |

Example connections





Is an RI suppression filter necessary?

| | 24 V DC control voltage | | 230 V AC control voltage | | |
|--|--|-----------------|--|-----------------|--|
| | Main circuit | Control circuit | Main circuit | Control circuit | |
| Degree of noise suppression A (industrial applications) | No | No | No | No | |
| Degree of noise suppression B (applications for residential areas) | Yes (see table of recommended filters) | No | Yes (see table of recommended filters) | No | |

| Soft starter type | Rated current | Recommended filters | | | | | | | | |
|--|--|--|---|--|--|---|--|--|--|--|
| | soft starter | Voltage range 200 460 V | | Voltage range 460 600 V | | | | | | |
| | A | Filter type | Rated current filter A | Connection terminals mm ² | Filter type | Rated current filter A | Connection terminals mm ² | | | |
| 3RW34 54 3RW34 55 3RW34 55 3RW34 58 3RW34 65 3RW34 66 3RW34 67 3RW34 67 3RW34 72 3RW34 83 3RW34 83 3RW34 84 | 57 70 110 135 162 195 235 352 500 700 1050 | B84143-G66-R110 B84143-G120-R110 B84143-G120-R110 B84143-G220-R110 B84143-G220-R110 B84143-G220-R110 B84143-G220-R110 B84143-B400-S20 B84143-B1000-S20 B84143-B1000-S20 | 66 66 120 220 220 220 220 400 600 1000 | $\begin{array}{c} 25\\ 25\\ 50\\ 95\\ 95\\ 95\\ 40\times 25\times 5^{1)}\\ 40\times 30\times 5^{1)}\\ 50\times 40\times 8^{1)}\\ 50\times 40\times 8^{1)} \end{array}$ | B84143-A80-R21 B84143-A80-R21 B84143-A120-R21 B84143-A150-R21 B84143-A150-R21 B84143-B250-S21 B84143-B250-S21 B84143-B400-S21 B84143-B1000-S21 B84143-B1000-S21 | 80 80 120 150 180 250 250 400 600 1000 | $\begin{array}{c} 25\\ 25\\ 50\\ 95\\ 40\times 25\times 51\\ 40\times 25\times 5^{1)}\\ 40\times 25\times 5^{1)}\\ 40\times 30\times 5^{1)}\\ 50\times 40\times 8^{1)}\\ 50\times 40\times 8^{1)} \end{array}$ | | | |

1) Busbar connection: L x W x H

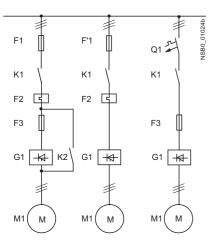
Contact address:

The suppression filters mentioned above can be ordered from EPCOS AG (see Appendix –> External Partners).

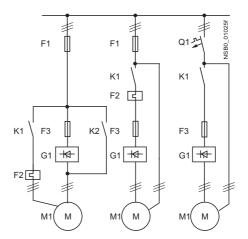
SIKOSTART soft starters

Circuit examples

Inline circuit



The all-range fuse F'1 (semiconductor and conductor protection) and semiconductor protection F3 must be selected with the aid of the fuse assignment table. Inside-delta circuit



Important: When the inside-delta circuit is used, the sequence of the terminals must be precisely observed.

| Soft starter type | Rated current | Fuse, lead fuse | Line contactor acc. to AC-3 ¹⁾ | Overload relay thermal | electronic | motor protection ²⁾ | Power electronics and bridging con- tactor acc. to AC-1 ¹⁾ |
|--|--|--|--|---|---|---|---|
| | A | F1 (type 1 coordina- tion) | К1 | F2 | F2 | Q1 | K2 |
| Recommended in inline circuit | motor feeders | | | | | | |
| 3RW34 54 3RW34 55 3RW34 57 3RW34 58 3RW34 65 3RW34 66 3RW34 67 3RW34 67 3RW34 72 3RW34 72 3RW34 83 3RW34 84 3RW34 86 | 57 70 110 135 162 195 235 352 500 700 1050 | 3NA3 022 3NA3 024 3NA3 032 3NA3 036 3NA3 140 3NA3 140 3NA3 144 3NA3 254 ³⁾ 3NA3 365 3NA3 475 3NA3 482 | 3RT10 36 3RT10 45 3RT10 54 3RT10 55 3RT10 56 3RT10 64 3RT10 65 3RT10 75 3TF68 3TF69 2 x 3TF68 (parallel) | 3RU11 46 3RU11 46 - - - - - - - - - - - | 3RB10 46 3RB10 56 3RB10 56 3RB10 56 3RB10 56 3RB10 56 3RB10 66 3RB10 66 3RB10 66 3RB10 66 3RB12 62 | 3RV10 41 3RV10 41 3VL27 16 AP 3VL27 16 AP 3VL37 20 AP 3VL37 25 AP 3VL37 25 AP 3VL47 40 AP 3VL57 50 AP 3WL11 08EB 3WL11 12EB | 3RT10 35 3RT10 44 3RT10 46 3RT14 46 3RT14 56 3RT14 56 3RT14 56 3RT14 56 3RT14 76 3RT14 76 2 x 3TF68 (parallel) |
| Recommended inside-delta circ | motor feeders in uit | | | | | | |
| 3RW34 54 3RW34 55 3RW34 55 3RW34 57 3RW34 65 3RW34 66 3RW34 67 3RW34 72 3RW34 72 3RW34 83 3RW34 84 3RW34 84 | 99 121 191 234 281 338 407 610 866 1212 1819 | 3NA3 032 3NA3 036 3NA3 142 3NA3 144 3NA3 252 3NA3 254 ³⁾ 3NA3 365 3NA3 472 3NA3 480 3NA3 682 - | 3RT10 44 3RT10 45 3RT10 54 3RT10 56 3RT10 56 3RT10 64 3RT10 65 3RT10 75 3RT68 3TF68 3TF69 2 x 3TF68 (parallel) | 3RU11 46 3RU11 46 3UA6. 01 3UA61 01 3UA62 01 3UA62 01 - - - | 3RB10 46 3RB10 46 3RB12 53 3RB12 53 3RB12 53 3RB12 53 3RB12 57 3RB12 57 3RB12 57 3RB12 57 3RB12 57 3RB12 62 - | 3VL27 16AP 3VL27 16AP 3VL37 25AP 3VL37 25AP 3VL47 31AP 3VL47 40AP 3VL57 63AP 3VL57 63AP 3WL12 10EB 3WL12 12EB 3WL12 20EB | 3RT10 35 3RT10 44 3RT10 46 3RT14 46 3RT14 56 3RT14 56 3RT14 56 3RT14 56 3RT14 76 3RT14 76 2 x 3TF68 (parallel) |

1) Optional.

For SENTRON 3VL/3WL order number extension, see Circuit-breakers

 Circuit-breakers up to 500 A -> Compact (MCCB) SENTRON VL -> For motor/generator protection ETU.

See notes on low-voltage fuse links under Switch-disconnectors and fuses -> Fuses and fuse systems -> Low-voltage fuses.

SIKOSTART soft starters

| Fuse assignment | | | | | | | | | | | |
|--|--|-----------------------|---|--|---|---|---|--|------------------|--|--|
| | Fuse design with 3NE1 SITOR fuses with full utilization ¹⁾ of the soft starter (semiconductor and lead protection) | | | | Fuse design with 3NE3 SITOR fuses with full utilization ¹⁾ of the soft starter, lowest possible protection, age-free (semiconductor protection) | | | Fuse design with 3NE3 SITOR fuses with full utilization ¹⁾ of the soft starter, highest possible protection, age-free (semiconductor protection) | | | |
| Soft starter | All-range fuse F | '1 | | | Semiconductor f | use F3 | | Semiconductor | fuse F3 | | |
| Туре | Туре | Rated current A | Size | Required conductor cross-section for each fuse mm ² | Туре | Rated current A | Size | Туре | Rated current | Size | |
| Type of coordination | 2 ³⁾ : <i>I</i> _q = 50 kA a | t 400 V | | | | | | | | | |
| 3RW34 55-0DC.4 3RW34 57-0DC.4 3RW34 58-0DC.4 ²⁾ 3RW34 65-0DC.4 3RW34 65-0DC.4 3RW34 66-0DC.4 3RW34 67-0DC.4 3RW34 83-0DC.4 3RW34 83-0DC.4 | 3NE1 021-0 3NE1 022-0 3NE1 225-0 3NE1 225-0 3NE1 230-0 3NE1 230-0 3NE1 332-0 3NE1 435-0 3NE1 438-0 2 x 3NE1 435-0 2 x 3NE1 437-1 | | 00 00 1 1 1 2 3 3 3 | $\begin{array}{c} 35\\ 50\\ 95\\ 120\\ 2\times70\\ 2\times95\\ 2\times95\\ 2\times150\\ 2\times(50\times5)^{4)}\\ 2\times(50\times5)^{4)}\\ 2\times(40\times5)^{4)}\\ 2\times(40\times5)^{4)} \end{array}$ | 3NE3 222 3NE3 224 3NE3 225 3NE3 227 3NE3 230-0B 3NE3 233 3NE3 233 3NE3 336 3NE3 340-8 2 x 3NE3 340-8 2 x 3NE3 340-8 | 125 160 200 250 315 350 450 630 900 2 × 630 2 × 900 | 1 1 1 1 1 2 2 2 2 | 3NE3 225 3NE3 231 3NE3 233 3NE3 333 3NE3 334-0B 3NE3 334-0B 3NE3 340-8 3NE3 340-8 2 x 3NE3 340-8 2 x 3NE3 340-8 | | 1 1 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 | |

1) E.g. 3x I_e for 60 s.

2) E.g. 3x I_e for 30 s.

3) The types of coordination are explained in more detail under Load Feeders

> Fuseless Load Feeders.

4) No direct connection to busbars.

| | utilization ^{†)} of the soft starter (semiconductor and lead protection) | | | | Fuse design with 3NE3 SITOR fuses with full utilization ¹⁾ of the soft starter, lowest possible protection, age-free (semiconductor protection) | | | Fuse design with 3NE3 SITOR fuses with full utilization ¹⁾ of the soft starter, highest possible protection, age-free (semiconductor protection) | | |
|--|--|------------------|---|---|---|---|---|--|---|--|
| Soft starter | All-range fuse F | '1 | | | Semiconductor f | fuse F3 | | Semiconductor fuse F3 | | |
| Туре | Туре | Rated current | Size | Required con- ductor cross- section for each fuse ₂ | Туре | Rated current | Size | Туре | Rated current | Size |
| | 0) | A | | mm² | | A | | | A | |
| Type of coordination | າ 2 ³⁾ : <i>I</i> q = 50 kA a | t 575 V | | | | | | | | |
| 3RW34 54-0DC.5 3RW34 55-0DC.5 3RW34 55-0DC.5 3RW34 58-0DC.5 ²⁾ 3RW34 65-0DC.5 3RW34 66-0DC.5 3RW34 67-0DC.5 3RW34 87-0DC.5 3RW34 83-0DC.5 3RW34 84-0DC.5 3RW34 86-0DC.5 ²⁾ | 3NE1 022-2 3NE1 022-0 3NE1 225-0 3NE1 225-0 3NE1 227-0 3NE1 230-0 3NE1 332-0 3NE1 435-2 3NE1 437-0 2 x 3NE1 435-0 2 x 3NE1 437-2 | | 00 00 1 1 2 3 3 3 3 3 3 | 50 50 95 120 2×70 2×95 2×150 $2 \times (40 \times 5)^{4)}$ $2 \times (40 \times 5)^{4)}$ | 3NE3 222 3NE3 224 3NE3 225 3NE3 227 3NE3 230-0B 3NE3 231 3NE3 233 3NE3 336 3NE3 340-8 2 x 3NE3 336 2 x 3NE3 340-8 | 125 160 200 250 315 350 450 630 900 2 × 630 2 × 900 | 1 1 1 1 1 2 2 2 2 | 3NE3 225 3NE3 230-0B 3NE3 233 3NE3 333 3NE3 334-0B 3NE3 340-8 3NE3 340-8 3NE3 340-8 2 × 3NE3 340-8 2 × 3NE3 340-8 | 200 315 415 500 630 900 900 2 × 900 2 × 900 | 1 1 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 |

1) E.g. 3x I_e for 60 s.

2) E.g. 3x I_e for 30 s.

3) The types of coordination are explained in more detail under Load Feeders

> Fuseless Load Feeders.

4) No direct connection to busbars.

Note: All selection data refer to inline circuits. For selections for the inside-delta-circuit, please contact techni-

cal support.

Further information is available on the Internet at: www.siemens.com/softstarter.

SIKOSTART soft starters



| Rated | At ambient ter | mperatur | e 40 °C | | At ambient ter | nbient temperature 50 °C D | | | | | Order No. | PS* | Weight |
|-------------------------------------|--|------------|-------------------------------------|------------|--|----------------------------|---------------------------|------------|-------------|--------|----------------------------------|------------------|-------------------|
| operating voltage U _e | Rated operat- ing current <i>I</i> e ¹⁾ | phase r | output of motors fo ng voltag | r rated | Rated operat- ing current /e ¹⁾ | | output of t d operatii | | | 5) | | | per PU approx. |
| | | 230 V | 400 V | 500 V | | 200 V | 230 V | 460 V | 575 V | | | | |
| V | A | kW | kW | kW | A | hp | hp | hp | hp | | | | kg |
| Inline circ | | | | | | | | | | | | | |
| 200 460 | 57 70 | 15 18.5 | 30 37 | - | 42 57 | 10 15 | 15 20 | 30 40 | - | A | 3RW34 54-0DC□4 3RW34 55-0DC□4 | 1 unit 1 unit | 8.460 10.000 |
| | 110 | 30 | 55 | - | 81 | 25 | 30 | 40 60 | - | A | 3RW34 57-0DC□4 | 1 unit | 9.900 |
| | 135 | 37 | 75 | - | 110 | 30 | 40 | 75 | - | А | 3RW34 58-0DC□4 | 1 unit | 9.870 |
| | 162 | 45 | 90 | - | 135 | 40 | 50 | 100 | - | A | 3RW34 65-0DC□4 | 1 unit | 19.000 |
| | 195 235 | 55 75 | 110 132 | - | 162 195 | 50 60 | 60 75 | 125 150 | - | A A | 3RW34 66-0DC□4 3RW34 67-0DC□4 | 1 unit 1 unit | 19.100 21.100 |
| | 352 | 110 | 200 | - | 285 | 100 | 100 | 200 | - | A | 3RW34 72-0DC□4 | 1 unit | 36.300 |
| | 500 | 160 | 250 | - | 450 | 150 | 150 | 350 | - | Α | 3RW34 83-0DC□4 | 1 unit | 59,600 |
| | 700 | 200 | 400 | - | 608 | 200 | 250 | 500 | - | А | 3RW34 84-0DC□4 | 1 unit | 59.600 |
| | 1050 | 315 | 560 | - | 865 | 300 | 350 | 750 | - | D | 3RW34 86-0DC□4 | 1 unit | 95.100 |
| 400 600 | 57 70 | - | 30 37 | 37 45 | 42 57 | - | - | 30 40 | 40 50 | C C | 3RW34 54-0DC□5 3RW34 55-0DC□5 | 1 unit 1 unit | 8.600 10.000 |
| | 110 | - | 55 | 75 | 81 | - | - | 60 | 75 | C | 3RW34 57-0DC□5 | 1 unit | 9.480 |
| | 135 | - | 75 | 90 | 110 | - | - | 75 | 100 | С | 3RW34 58-0DC□5 | 1 unit | 7.650 |
| | 162 195 | - | 90 110 | 110 132 | 135 162 | - | - | 100 125 | 125 150 | C C | 3RW34 65-0DC□5 3RW34 66-0DC□5 | 1 unit 1 unit | 15.000 15.000 |
| | 235 | - | 132 | 160 | 195 | - | - | 150 | 200 | č | 3RW34 67-0DC□5 | 1 unit | 21.100 |
| | 352 | - | 200 | 250 | 285 | - | - | 200 | 300 | С | 3RW34 72-0DC□5 | 1 unit | 37.000 |
| | 500 | - | 250 | 355 | 450 | - | - | 350 | 450 | С | 3RW34 83-0DC□5 | 1 unit | 59.600 |
| | 700 1050 | - | 400 560 | 500 710 | 608 865 | - | - | 500 750 | 700 1000 | C D | 3RW34 84-0DC□5 3RW34 86-0DC□5 | 1 unit | 59.600 95.100 |
| Inside-del | | - | 560 | 710 | 803 | - | - | 730 | 1000 | D | | 1 unit | 93.100 |
| 200 400 | 99 | 30 | 55 | | 73 | 20 | 25 | | _ | А | 3RW34 54-0DC□4 | 1 unit | 8.460 |
| 200 400 | 121 | 37 | 55 | - | 99 | 30 | 30 | - | - | | 3RW34 55-0DC□4 | 1 unit | 10.000 |
| | 191 | 55 75 | 110 132 | - | 140 191 | 40 60 | 50 | - | - | A | 3RW34 57-0DC□4 | 1 unit | 9.900 |
| | 234 281 | 90 | 160 | - | 234 | 75 | 60 75 | - | - | A | 3RW34 58-0DC□4 3RW34 65-0DC□4 | 1 unit | 9.870 |
| | 338 | 90 110 | 200 | - | 281 | 100 | 100 | - | - | A | 3RW34 66-0DC□4 | 1 unit 1 unit | 19.000 |
| | 407 | 132 | 250 | - | 338 | 100 | 125 | - | - | А | 3RW34 67-0DC□4 | 1 unit | 21.100 |
| | 610 | 200 | 355 | - | 494 | 150 | 200 | - | - | А | 3RW34 72-0DC□4 | 1 unit | 36.300 |
| | 866 | 250 | 500 | - | 779 | 250 | 300 | - | - | A | 3RW34 83-0DC□4 | 1 unit | 59.600 |
| | 1212 1819 | 400 560 | 710 1000 | - | 1053 1498 | 350 600 | 450 650 | - | - | A D | 3RW34 84-0DC□4 3RW34 86-0DC□4 | 1 unit 1 unit | 59.600 95.100 |
| 400 600 | 99 | - | 55 | 55 | 73 | - | - | 50 | 75 | С | 3RW34 54-0DC□5 | 1 unit | 8.600 |
| | 121 | - | 55 | 75 | 99 | - | - | 75 | 100 | Ċ | 3RW34 55-0DC□5 | 1 unit | 10.000 |
| | 191 234 | - | 110 132 | 132 160 | 140 191 | - | - | 100 150 | 150 200 | C C | 3RW34 57-0DC□5 3RW34 58-0DC□5 | 1 unit 1 unit | 9.480 7.650 |
| | 281 | - | 160 | 200 | 234 | - | - | 200 | 250 | C | 3RW34 65-0DC | 1 unit | 15.000 |
| | 338 | - | 200 | 250 | 281 | - | - | 200 | 300 | Ċ | 3RW34 66-0DC□5 | 1 unit | 15.000 |
| | 407 | - | 250 | 315 | 338 | - | - | 250 | 350 | С | 3RW34 67-0DC□5 | 1 unit | 21.100 |
| | 610 | - | 355 | 400 | 494 | - | - | 400 | 500 | С | 3RW34 72-0DC□5 | 1 unit | 37.000 |
| | 866 1212 | - | 500 710 | 630 800 | 779 1053 | - | - | 700 950 | 850 1200 | C C | 3RW34 83-0DC□5 3RW34 84-0DC□5 | 1 unit 1 unit | 59.600 59.600 |
| | 1819 | - | 1000 | 1200 | 1498 | - | - | 1300 | 1700 | D | 3RW34 86-0DC□5 | 1 unit | 95.100 |

Order No. extension for rated control supply voltage U_s

DC 24 V²⁾ AC 115 V³⁾⁴⁾ AC 230 V

1) In the selection table, the unit rated operating current refers to the motor's rated operating current in the inside-delta circuit.

The actual current of the unit is approx. 58 % of this value. 2) SIKOSTART 3RW34 86-0DC..: not available as DC 24 V design. 3) SIKOSTART 3RW34 57-0DC.. and 3RW34 86-0DC..:

4) The specified hp values apply to 50 Hz networks. In conjunction with 60 Hz networks, in the AC 115 V design, a higher motor hp is possible. Relevant values on request.

5) The delivery times apply to AC 230 V soft starters. Delivery times for the remaining designs on request.

2 3 4

Soft starter selection depends on the motor's rated current.

The 3RW34 solid-state starters are designed for normal starting. In the event of deviating conditions or increased switching frequency, it may be necessary to choose a larger unit. Siemens recommends the use of the selection and simulation program Win-SIKOSTART. See technical specifications for information about rated currents for ambient temperatures >40 °C.

SIKOSTART soft starters

| | For soft starters | Version | DT | Order No. | PS* | Weight per PU approx. kg |
|------------------------|--|---|----|--------------------|--------|-----------------------------------|
| Terminal covers | | | | | | |
| | 3RW34 54 3RW34 55 3RW34 57 3RW34 58 | Terminal cover (1 set = 6 units) M 6 terminal screws | | 3KX3 552-3DA01 | 1 set | 0.077 |
| 3KX3 552-3DA01 | | | | | | |
| Operating instructions | | | | | | |
| | | or SIKOSTART 3RW34 in | | | | |
| | - German - English - Italian - French - Spanish - Portuguese are available in Adobe / www.siemens.de/autom "3RW34 manuals" as se | Acrobat format free-of-charge on the Internet at ation/manuals. Enter "SIKOSTART manuals" or parch torm | В | 3ZX1012-0RW34-1AN1 | 1 unit | 0.010 |
| | Shw34 manuais as se | | | | | |
| Spare parts | | | | | | |
| | For soft starters | Maximum number required per device | DT | Order No. | PS* | Weight per PU approx. |
| | Туре | | | | | kg |
| Control unit | | | | | _ | |
| | 2014/24 0002 | - | | 200/20 50 60 000 | d unit | 0 5 05 |

| | 3RW340DC2. 3RW340DC3. 3RW340DC4. | 1 1 1 | A A | 3RW39 50-6DC28 3RW39 50-6DC38 3RW39 50-6DC48 | 1 unit 1 unit 1 unit | 0.565 0.324 0.348 |
|------|--|---------------------------------|-------------|--|--------------------------------------|----------------------------------|
| Fans | 3RW34 50DC2. 3RW34 50DC4. 3RW34 60DC2. 3RW34 60DC4. | 2 2 1 | X A X | 3RW39 50-8DC28 3RW39 50-8DC48 3RW39 60-8DC28 3RW39 60-8DC48 | 1 unit 1 unit 1 unit 1 unit | 0.261 0.648 0.600 0.685 |
| | 3RW34 72-0DC4. 3RW34 80DC4. 3RW34 82-0DC2. 3RW34 83-0DC2. 3RW34 84-0DC2. 3RW34 84-0DC2. | 2 3 2 3 3 3 3 | X X X | 3RW39 70-8DC28 3RW39 72-8DC28 3RW39 73-8DC28 | 1 unit 1 unit 1 unit | 0.616 0.558 0.600 |

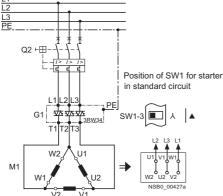
Accessories

SIKOSTART soft starters

Circuit diagrams

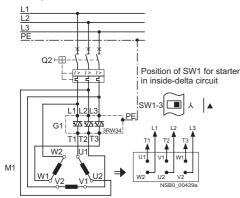
Connection examples for main and control circuits

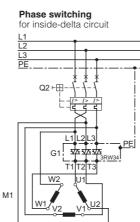
Main circuit Possibility 1: inline circuit



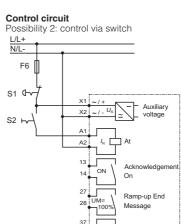


Possibility 2: inside-delta circuit





Control circuit Possibility 1: control via pushbutton L/L· N/L F6 Π S1 (Auxiliary X2 voltage I_N A2 13 Acknowledgen I ON On ON 14 S2 27 Ramp-up End ШΜ S3 OFF 28 Message .. 100 37 EEPROM 38 Acknowledgem Fault¹)



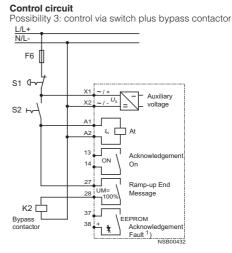
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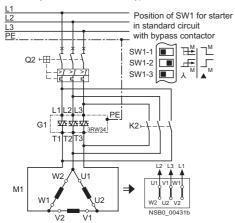
EEPROM

Acknow Fault¹) edge

NSB0043



Main circuit Possibility 3: inline circuit with bypass contactor



1) With SW1-4, the fault contact can be switched over between normally closed and normally open.

3/60 Siemens LV 10 · 2004

3

SIKOSTART soft starters

Further information

Configuration

The 3RW34 solid-state starters are designed for normal starting. In the event of deviating conditions or increased switching frequency, it may be necessary to choose a larger unit. For accurate dimensioning, use the Win-SIKOSTART selection and simulation program.

If necessary, an overload relay for heavy-starting must be selected where long starting times are involved. PTC thermistor detectors are recommended. This also applies to soft running down. In this case an additional current load is effective compared with a free ramp-down.

In the motor feeder between the SIKOSTART and the motor, no capacitive elements are permitted (e.g. no compensation equipment).

All elements of the main circuit (such as fuses, switching devices and overload relays) should be dimensioned for direct starting, following the local short-circuit conditions. Fuses, switching devices and overload relays must be ordered separately.

Circuit concept

The SIKOSTART 3RW34 can be operated in two different types of circuit.

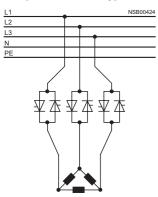
Inline circuit

The switching devices for isolating and protecting the motor are simply connected in series with the soft starter. The motor is connected to the soft starter with three leads.

Inside-delta circuit

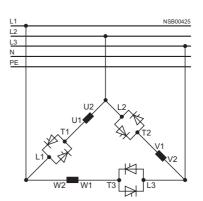
The wiring is similar to that of star-delta starters. The phases of the soft starter are connected in series with the individual motor windings. The soft starter then only has to carry the phase current, amounting to about 58 % of the rated current of the motor (conductor current).

Comparison of the types of circuit



Inline circuit:

Rated current $I_{\rm e}$ corresponds to the rated motor current $I_{\rm n},$ 3 conductors to motor



Inside-delta circuit:

Rated current $I_{\rm e}$ corresponds to approx. 58 % of the rated motor current $I_{\rm n}$.

6 conductors to motor (as star delta starters)

Which circuit?

Using the inline circuit involves the lowest wiring complexity, which is twice as high when using the inside-delta circuit. If the soft starter to motor connections are short, this contact sequence is preferable.

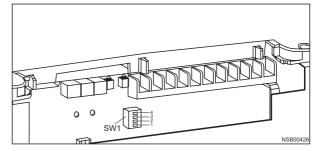
Thanks to the possibility of switching between the inline circuit and inside-delta circuit, the most favorable solution can always be chosen.

Settings

DIP switches (SW1):

This switch is located on the main logic module. It is used for setting the soft starter software to the relevant application.

- 1)SW1-1: causes an OFF delay on the soft starter. The OFF delay is required when using a parallel contactor (bridging contactor). It initially enables the contactor to be deenergized, after which the soft starter switches 1.0 s later. This prevents damage to the thyristors from voltage peaks which arise when the bridging contactor interrupts the motor current.
- 2)<u>SW1-2:</u> Sets an ON delay signal for the soft starter. This function makes it possible for a contactor disconnector first to be switched on in the currentless state, with the soft starter then being switched 1.0 s later. This has the effect of increasing the life of the contacts of the contactor disconnector.
- 3)<u>SW1-3:</u> Sets the soft starter software for operation with thyristors in the inline circuit or within the inside-delta circuit.
- 4)SW1-4: Sets the fault contact as an NO contact or NC contact. This contact can be used for controlling a fault contactor, a shunt release or a fault alarm.



SIKOSTART soft starters

Overview

SIKOSTART 3RW22

In addition to soft starting and soft ramp-down, the solid-state SIKOSTART 3RW22 soft starters provide numerous functions for higher-level requirements They cover a rating range of up to 710 kW (at 400 V).

Combinations of various starting, operating and ramp-down possibilities ensure an optimum adaptation to the applicationspecific requirements. Operation and commissioning can be carried out either conventionally with switches and potentiometers or conveniently using a commercial PC and an RS232 interface.

Applicable standards

- IEC 60947-4-2
- UL/CSA for 3RW22 21 to 3RW22 31

Area of application

The SIKOSTART 3RW22 solid-state soft starters are suitable for the controlled soft starting and ramp-down, for the braking and the energy-saving operation of three-phase induction motors.

Applications

- Pumps, compressors
- Fans, blowers
- Conveyors
- Breakers, mills
- Agitators
- Sanding machines
- Wire drawing/textile machines
- Presses
- Machine tools

Functions

- Soft starting with breakaway pulse, voltage ramp, voltage or current limiting as well as any combination of these, depending on load type
- Varied setting facilities for the starting parameters as starting voltage, ramp time etc.
- Start-up detection
- Energy saving mode
- Four running-down modes selectable: free ramp-down, pump stopping, soft stop, DC braking
- Electronic overload protection
- Protection against temperature rise
- Parameters can be set via a potentiometer and sliding-dolly switch or using the PC program COM SIKOSTART
- Interface for communication with the PC for more accurate setting of the parameters as well as for control and monitoring
- Simple adaptation to the motor feeder
- Simple mounting and commissioning
- Display of 5 operating states and 5 fault signals
- System voltages from 200 V to 1000 V, 50/60Hz
- Integrated power supply unit for three control supply voltages
- Applicable up to 55 °C
- Higher load ratings by selecting low ambient temperatures.

SIKOSTART soft starters

Technical specifications

| reclinical specifications | | | |
|--|---|--|---|
| Control electronics | | | |
| Rated control supply voltage (term | iinal 12 - 15) | V | 380 415, 200 240, 100 120 (+10 %/-15 %) |
| Rated frequency | | Hz | 50/60, operating range 45 66 |
| Rated control supply current | at 380 V 415 V at 200 V 240 V at 100 V 120 V | mA mA mA | approx. 40 approx. 75 approx. 100 |
| Short-circuit protection, control c | ircuit | | built-in fuse 250 mA slow, 6.3 mm x 32 mm |
| Operating times | ON-delay ON-delay ON-delay Recovery time | ms s s ms | ≤50 controlled separately when the control supply voltage is applied and voltage is present in the control circuit ≤ 1 contactor operation, ON/OFF by switching the control supply voltage ≤ 1.1 automatic mode ≤ 440 after DC braking |
| Power failure | | | |
| Bridging time | control supply voltage | ms | ≤ 80 |
| Response time | load current circuit | ms | ≤ 100 |
| Operating indications (continuous light) | LED 1 LED 2 LED 3 LED 4 LED 5 | | Ready starting or slowing down starting ended energy save mode active braking |
| Fault indications (flashing light) | LED 1 LED 2 LED 3 LED 4 LED 5 | | Mains fault (phase failure, missing voltage/load, control supply voltage too low) Thyristor defective (one or several thyristor(s) alloyed) Excess temperature or overload deactivation Unit malfunction Unit gets too hot; new starting is inhibited; however, unit continues to operate |
| Control inputs on versions with serial interface, the input assignments are dependent on the number of parameter sets selected via the COM-SIKOSTART PC communication program (up to 3 parameter sets can be selected) | Standard application: with one motor Input 1 Input 2 Input 3 Serial starting of several motors or of reversible pole motors Input 1 Input 2 Input 3 Rated operating current Rated voltage | mA | ON OFF Reset ON/OFF parameter set 1 ON/OFF parameter set 2 Reset or ON/OFF parameter set 3 approx. 10 according to DIN 19 240 DC 24 V from built-in power supply unit via DC +24 V terminal |
| Relay outputs | Output 1 Output 2 Output 2 Output 3 Rated operating current Short-circuit protection | A A A | Group fault signal (changeover contact) Starting terminated; motor connected to full mains voltage (NO contact) DC brakes active; for control of the braking contactor (NO contact) 3 AC-15/AC-14 at 240 V 0.1 DC-13 at 240 V 0.5 DC-13 at 24 V 4 A utilization category gL/gG; 6 A fast (fuse is not included in scope of supply) |
| Max. conductor cross-sections | Solid Finely stranded with end sleeve Tightening torque | mm ² mm ² Nm | 0.5 2.5 0.5 1.5 0.8 1.4 |

SIKOSTART soft starters

| Power electronics | | | |
|--|--|-------------------|---|
| Continuous operation (% of I_e) | | % | 115 |
| Max. starting time | | | |
| cold (40 °C or 55 °C)/warm | Starting current | | |
| | 600 % / _e 450 % / _e 300 % / _e 250 % / _e 200 % / _e | S S S S | 2/1 10/5 60/30 120/60 200/100 |
| Minimum load ¹⁾ (% of I _e) | | % | 20 |
| Permissible ambient temperature • in operation • when stored | | °C °C | 0 +40 or +55 (switchable) -25 +80 |
| Operating range | | | |
| | Rated operating voltage Frequency | V V V Hz | 200 (-15 %) 500 (+10 %) for 3RW220DB15, 200 (-15 %) 415 (+10 %) for 3RW220DB14, 500 (-15 %) 690 (+10 %) for 3RW220DB16, 1000 (-20 %; +25 %) for 3RW220DB18 45 66 |
| Degree of protection acc. to IEC 60947-1/IEC 60529 | RW22 21 RW22 31 RW22 34 RW22 50 | | IP20 IP00 |
| Overload protection | | | Thermal sensor on the heatsink, solid-state protection with thermal image |
| Permissible installation altitude | | | up to 3 000 m above sea level; over 1000 m above sea level linear reduction of $l_{\rm e}$, thus at 2 000 m above sea level 0.87 x $l_{\rm e}$ and at 3 000 m above sea level 0.77 x $l_{\rm e}$ |
| Fans | Rated control supply voltage Frequency | V Hz | 230 ±10% 45 66 |
| Maximum conductor length betwee | een soft starter and motor | m | 200 ²⁾ |
| | | | |

1) The rated motor current (specified on the motor's rating plate) should amount to at least 20 % of the SIKOSTART unit's rated current $l_{\rm e}.$

2) If this value is exceeded, problems with line capacities may arise, which can result in false firing.

| Power electronics | | | | - | - | _ |
|--|--|--|--|--|--|--|
| Type (200 500 V) | | | 3RW22 21-1AB15 | 3RW22 23-1AB15 | 3RW22 25-1AB15 | 3RW22 26-1AB15 |
| Load rating | | | | | | |
| Rated operating current <i>l</i> e Motor output (400 V) approx. | at 40/55 °C, AC-3 at 40/55 °C, AC-3 | A kW | 7/5.5 3/2.2 | 10.5/9 4/4 | 22/16 11/7.5 | 28/22 15/11 |
| Permissible starts per hour for intermittent duty S4, $T_u = 40 \text{ °C}$ ON-period = 30 % | 350 % x / _e for 5 s 300 % x / _e for 10 s 250 % x / _e for 15 s | 1/h 1/h 1/h | 80 50 50 | 90 60 50 | 30 20 20 | 20 10 10 |
| Power loss at rated operating curre | ent (40 °C) approx. | W | 30 | 40 | 70 | 80 |
| Max. conductor cross-sections | Solid Finely stranded without end sleeve Finely stranded with end sleeve Stranded | mm ² mm ² mm ² mm ² | 1 16 2.5 16 1 16 2.5 25 | 1 16 2.5 16 1 16 2.5 25 | 1 16 2.5 16 1 16 2.5 25 | 1 16 2.5 16 1 16 2.5 25 |
| Bridging contactor (if required, as a main contactor to / | for AC-1 AC-3) | | 3RT10 15 3RT10 16 | 3RT10 15 3RT10 17 | 3RT10 24 3RT10 26 | 3RT10 24 3RT10 34 |
| Recommended braking contactor | | | 3RT15 1. | 3RT15 26 | 3RT15 26 | 3RT15 26 |
| ······ | | | | | | |
| Type (200 500 V) | | | | 3RW22 28-1AB15 | | 3RW22 31-1AB15 |
| | | | | | | |
| Type (200 500 V) | at 40/55 °C, AC-3 at 40/55 °C, AC-3 | A kW | | | | |
| Type (200 500 V) Load rating Rated operating current <i>I</i> e | at 40/55 °C, AC-3 | | 3RW22 27-1AB15 35/32 | 3RW22 28-1AB15 45/37 | 3RW22 30-1AB15 50/45 | 3RW22 31-1AB15 70/63 |
| Type (200 500 V) Load rating Rated operating current I_e Motor output (400 V) Permissible starts per hour for intermittent duty S4, T_u = 40 °C | at 40/55 °C, AC-3 at 40/55 °C, AC-3 $350 \% \times I_{e}$ for 5 s $300 \% \times I_{e}$ for 10 s $250 \% \times I_{e}$ for 15 s | kW 1/h 1/h | 3RW22 27-1AB15 35/32 18.5/15 50 30 | 3RW22 28-1AB15 45/37 22/18.5 30 20 | 3RW22 30-1AB15 50/45 25/22 20 20 | 3RW22 31-1AB15 70/63 37/30 40 30 |
| Type (200 500 V) Load rating Rated operating current <i>I_e</i> Motor output (400 V) Permissible starts per hour for intermittent duty S4, <i>T_u</i> = 40 °C ON-period = 30 % | at 40/55 °C, AC-3 at 40/55 °C, AC-3 $350 \% \times I_e$ for 5 s $300 \% \times I_e$ for 10 s $250 \% \times I_e$ for 15 s ent (40 °C) approx. • Solid • Finely stranded without end sleeve | kW 1/h 1/h 1/h W Mm ² mm ² | 3RW22 27-1AB15 35/32 18.5/15 50 30 30 105 1/16 2.5 16 | 3RW22 28-1AB15 45/37 22/18.5 30 20 20 130 1/16 2.5 16 | 3RW22 30-1AB15 50/45 25/22 20 20 20 140 1/16 2.5 16 | 3RW22 31-1AB15 70/63 37/30 40 30 20 220 1/16 2.5 16 |
| Type (200 500 V) Load rating Rated operating current <i>l_e</i> Motor output (400 V) Permissible starts per hour for intermittent duty S4, <i>T_u</i> = 40 °C ON-period = 30 % Power loss at rated operating current | at 40/55 °C, AC-3 at 40/55 °C, AC-3 $350 \% x l_e$ for 5 s $300 \% x l_e$ for 10 s $250 \% x l_e$ for 15 s ent (40 °C) approx. • Solid • Finely stranded without end | kW 1/h 1/h 1/h W mm ² | 3RW22 27-1AB15 35/32 18.5/15 50 30 30 105 1/16 | 3RW22 28-1AB15 45/37 22/18.5 30 20 20 130 1/16 2.5 16 1/16 | 3RW22 30-1AB15 50/45 25/22 20 20 20 140 1/16 | 3RW22 31-1AB15 70/63 37/30 40 30 30 220 1/16 |
| Type (200 500 V) Load rating Rated operating current <i>I_e</i> Motor output (400 V) Permissible starts per hour for intermittent duty S4, <i>T_u</i> = 40 °C ON-period = 30 % Power loss at rated operating current | at 40/55 °C, AC-3 at 40/55 °C, AC-3 $350 \% \times I_e$ for 5 s $300 \% \times I_e$ for 10 s $250 \% \times I_e$ for 15 s ent (40 °C) approx. • Solid • Finely stranded without end sleeve • Finely stranded with end sleeve • Stranded for AC-1 | kW 1/h 1/h 1/h W W mm ² mm ² mm ² | 3RW22 27-1AB15 35/32 18.5/15 50 30 30 105 1/16 2.5 16 1/16 | 3RW22 28-1AB15 45/37 22/18.5 30 20 20 130 1/16 2.5 16 | 3RW22 30-1AB15 50/45 25/22 20 20 20 140 1/16 2.5 16 1/16 | 3RW22 31-1AB15 70/63 37/30 40 30 220 1/16 2.5 16 1/16 |

SIKOSTART soft starters

| Power electronics | | | | | | |
|---|--|-------------------|------------------------|------------------------|------------------------|------------------------|
| Type (200 500 V) | | | 3RW22 34-0DB15 | 3RW22 35-0DB15 | 3RW22 36-0DB15 | 3RW22 38-0DB15 |
| Load rating | | | | | | |
| Rated operating current <i>I</i> _e Motor output (400 V) | at 40/55 °C, AC-3 at 40/55 °C, AC-3 | A kW | 100/85 55/45 | 135/110 75/55 | 160/140 90/75 | 235/205 132/110 |
| Permissible starts per hour for intermittent duty S4, $T_{\rm u}$ = 40 °C, ON-period = 30 % | 350 % x / _e for 5 s 300 % x / _e for 10 s 250 % x / _e for 15 s | 1/h 1/h 1/h | 120 80 70 | 100 60 50 | 90 60 50 | 90 60 50 |
| Power loss at rated operating curre | ent (40 °C) approx. | W | 260 | 370 | 435 | 640 |
| Fans | Number Ratings | W | 1 18 | 1 18 | 1 18 | 1 18 |
| Max. conductor cross-sections | Stranded | mm ² | 95 | 120 | 150 | 240 |
| Bridging contactor (if required, as a main contactor to a | for AC-1 AC-3) | | 3RT10 45 3RT10 54 | 3RT14 46 3RT10 55 | 3RT14 56 3RT10 56 | 3RT14 56 3RT10 65 |
| Recommended braking contactor (opening + closing contactor) | combination | | 3RT10 34 + 3RT10 34 | 3RT10 35 + 3RT10 44 | 3RT10 44 + 3RT10 44 | 3RT10 44 + 3RT10 46 |

| Type (200 500 V) | | | 3RW22 40-0DB15 | 3RW22 41-0DB15 | 3RW22 42-0DB15 |
|--|--|-----------------------|------------------------|------------------------|------------------------|
| Load rating | | | | | |
| Rated operating current <i>I</i> _e Motor output (400 V) | at 40/55 °C, AC-3 at 40/55 °C, AC-3 | A kW | 300/250 160/132 | 355/300 200/160 | 430/355 250/200 |
| Permissible starts per hour for intermittent duty S4, $T_u = 40$ °C, ON-period = 30 % | 350 % x / _e for 5 s 300 % x / _e for 10 s 250 % x / _e for 15 s | 1/h 1/h 1/h | 20 10 10 | 40 20 20 | 180 100 70 |
| Power loss at rated operating curre | ent (40 °C) approx. | W | 810 | 970 | 1560 |
| Fans | Number Ratings | W | 2 36 | 2 36 | 3 54 |
| Max. conductor cross-sections | Stranded Connecting bar | mm ² mm | 240 - | 240 - | - 40 x 10 |
| Bridging contactor (if required, as a main contactor to A | for AC-1 AC-3) | | 3RT14 56 3RT10 66 | 3RT14 66 3RT10 75 | 3RT14 76 3RT14 76 |
| Recommended braking contactor (opening + closing contactor) | combination | | 3RT10 54 + 3RT10 55 | 3RT10 56 + 3RT10 65 | 3RT10 56 + 3RT10 65 |

| Type (200 500 V) | | | 3RW22 43-0DB15 | 3RW22 45-0DB15 | 3RW22 47-0DB15 | 3RW22 50-0DB15 |
|--|--|-------------------|------------------------|------------------------|------------------------|--------------------------------------|
| Load rating | | | | | | |
| Rated operating current <i>I</i> e Motor output (400 V) | at 40/55 °C, AC-3 at 40/55 °C, AC-3 | A kW | 560/450 315/250 | 700/500 400/315 | 865/700 500/400 | 1200/1000 710/560 |
| Permissible starts per hour for intermittent duty S4, $T_u = 40 \text{ °C}$, individual mounting, ON-period = 30 % | 350 % x / _e for 5 s 300 % x / _e for 10 s 250 % x / _e for 15 s | 1/h 1/h 1/h | 90 60 50 | 100 60 60 | 120 80 70 | 60 40 40 |
| Power loss at rated operating curre | ent (40 °C) approx. | W | 1950 | 2060 | 2440 | 3550 |
| Fans | Number Ratings | W | 3 135 | 3 135 | 3 78 | 3 78 |
| Max. conductor cross-sections 1) | Connecting bar | mm | 40 x 10 | | 50 x 20 | 60 x 20 |
| Bridging contactor (if required, also suitable for occasion $l_a \le 6 \times l_{\Theta}$) | for AC-1 onal direct start at | | 3RT14 76 3TF68 | 3TF68 3TF68 | 3TF69 3TF69 | 2 x 3TF68 2 x 3TF68 ²⁾ |
| Recommended braking contactor (opening + closing contactor) | | | 3RT10 65 + 3RT10 66 | 3RT10 65 + 3RT10 75 | 3RT10 75 + 3RT10 76 | 3RT14 76 + 3TF68 |

1) Due to thermal expansion of the bars, flexible links must be used for connecting the busbars.

2) Suitable as emergency contactor in occasional starts with $I_a \leq 6 \times I_e$.

SIKOSTART soft starters

| | | | | | _ | | - |
|--|--|-----------------------|--|--|--|----------------|--|
| Power electronics | | | | | | | |
| Type (500 690 V) | | | 3RW22 36-0DB16 | 3RW22 38-0D | B16 3RW22 40-0 | 0DB16 | 3RW22 42-0DB16 |
| Load rating | | | | | | | |
| Rated operating current I _e Motor output (690 V) | at 40/55 °C, AC-3 at 40/55 °C, AC-3 | A kW | 160/140 160/132 | 235/205 250/200 | 300/250 315/250 | | 450/355 450/355 |
| Permissible starts per hour Intermittent duty S4, $T_u = 40 \text{ °C}$ ON-period = 30 % | 350 % x I _e for 5 s 300 % x I _e for 10 s 250 % x I _e for 15 s | 1/h 1/h 1/h | 90 60 50 | 90 60 50 | 20 10 10 | | 180 100 70 |
| Short-circuit protection | SITOR Fuse links | А Туре | 500 3NE3 334-0B | 630 3NE3 336 | 2 x 500 2 x 3NE3 33 | 34-0B | 2 x 560 2 x 3NE3 335 |
| | Fuse switch disconnector Switch disconnector for fuses | Туре Туре | 3NP44 7 3NP54 (3NP44 76) 3KL61 3KM57 | 3NP44 7 3NP54 (3NP44 76) 3KL61 3KM57 | 2 x 3NP44 7 2 x 3NP54 (2 x 3NP44 2 x 3KL61 2 x 3KM57 | | 2 x 3NP44 7 2 x 3NP54 (2 x 3NP44 76) 2 x 3KL61 2 x 3KM57 |
| Power loss at rated operating curre | ent (40 °C) approx. | W | 490 | 700 | 810 | | 1550 |
| Fans | Number Ratings | W | 1 18 | 1 18 | 2 36 | | 3 54 |
| Max. conductor cross-sections ¹⁾ | Stranded Connecting bar | mm ² mm | 150 - | 240 - | 240 - | | - 40 x 10 |
| Bridging contactor | for AC-1 | | 3RT14 56 | 3RT10 56 | 3RT14 56 | | 3RT10 75 |
| Recommended braking contactor (opening + closing contactor) | combination | | 3RT10 36 + 3RT10 54 | 3RT10 44 + 3RT10 46 | 3RT10 54 + 3RT10 56 | | 3RT10 56 + 3RT10 65 |
| Due to thermal expansion of the b connecting the busbars. | ars, flexible links must be used f | or | | | | | |
| Type (500 690 V) | | | 3RW22 43-0DB16 | 3RW22 | 47-0DB16 | 3RW2 | 22 50-0DB16 |
| Load rating | | | | | | | |
| Rated operating current <i>I</i> _e Motor output (690 V) | at 40/55 °C, AC-3 at 40/55 °C, AC-3 | A kW | 560/450 560/450 | 865/700 850/710 | | 1200/ 1200/ | |
| Permissible starts per hour for intermittent duty S4, $T_u = 40$ °C, ON-period = 30 % | 350 % x / _e for 5 s 300 % x / _e for 10 s 250 % x / _e for 15 s | 1/h 1/h 1/h | 90 60 50 | 100 80 70 | | 60 40 40 | |
| Short-circuit protection | SITOR Fuse links Fuse switch disconnector | А Туре Туре | 2 x 560 2 x 3NE3 335 2 x 3NP44 7 | 3 x 800 3 x 3NE 3 x 3NF | 3 338-8 | | 00 NE3 338-8 NP44 7 |

| | Switch disconnector for fuses | Туре | 2 x 3NP54 2 x (3NP44 76) 2 x 3KL61 2 x 3KM57 | 3 x 3NP54 3 x (3NP44 76) 3 x 3KL61 3 x 3KM57 | 4 x 3NP54 4 x (3NP44 76) 4 x 3KL61 4 x 3KM57 |
|--|-------------------------------|------|---|---|---|
| Power loss at rated operating current (40 °C) approx. | | | 1950 | 2660 | 3560 |
| Fans | Number Ratings | W | 3 135 | 3 78 | 3 78 |
| Max. conductor cross-sections ¹⁾ | Connecting bar | mm | 40 x 10 | 60 x 20 | 60 x 20 |
| Bridging contactor | for AC-1 | | 3RT14 76 | 3TF69 | 2 x 3TF68 ²⁾ |
| Recommended braking contactor combination (opening + closing contactor) | | | 3RT10 65 + 3RT10 75 | 3RT10 75 + 3RT10 76 | 3RT14 76 + 3TF68 |

1) Due to thermal expansion of the bars, flexible links must be used for connecting the busbars.

2) Suitable as emergency contactor in occasional starts with $I_a \leq 6 \times I_e$.

| Type (1000 V) | | | 3RW22 36-0DB18 | 3RW22 40-0DB18 | 3RW22 42-0DB18 |
|--|--|-------------------|----------------------|--------------------|--------------------|
| Load rating | | | | | |
| Rated operating current <i>I</i> _e Motor output (1000 V) | at 40/55 °C, AC-3 at 40/55 °C, AC-3 | A kW | 160/140 200/160 | 300/250 400/315 | 450/355 630/450 |
| Permissible starts per hour for intermittent duty S4, $T_{\rm u}$ = 40 °C, ON-period = 30 % | 350 % x / _e for 5 s 300 % x / _e for 10 s 250 % x / _e for 15 s | 1/h 1/h 1/h | 60 40 40 | 120 80 70 | 110 70 70 |
| Short-circuit protection | SITOR Fuse links | А Туре | 3NE3230-0B | 3NE3335 | 2 x 3NE3233 |
| Power loss at rated operating curre | ent (40 °C) approx. | W | 550 | 1100 | 1190 |
| Fans | Number Ratings | W | 1 36 | 3 54 | 3 135 |
| Max. conductor cross-sections ¹⁾ | Connecting bar | mm | 150 | 40 x 10 | 40 x 10 |
| Bridging contactor | for AC-1 for AC-3 | | 3RT10 65 3RT10 75 | 3TF68 3TF68 | 3TF68 3TF68 |

1) Due to thermal expansion of the bars, flexible links must be used for connecting the busbars.

SIKOSTART soft starters

| Short-circuit prot | ection fo | or semico | onductors and le | ads with | SITOR all-ra | ange fuses, type 3NE1 | |
|--|---|---|--|---|--|---|---|
| SIKOSTART | Rated | Rated | | | | ART parameters e.g. starting current $3 \times I_{\rm r}$ | for 60 s |
| (7 _u = 40 °C) (200 500 V) | current I _N of motor at 400 V | output P _N of motor at 400 V | SITOR fuse (operational class gR) | Rated current | Conductor protection per fuse ¹⁾ for Cu cable | 3NP fuse switch disconnector | Switch disconnectors for fuses 3KL, 3KM |
| | А | kW | Quantity per phase/type | А | ≥mm ² | | _ |
| 3RW22 21-1AB15 3RW22 23-1AB15 ²⁾ 3RW22 25-1AB15 3RW22 25-1AB15 3RW22 27-1AB15 3RW22 27-1AB15 3RW22 30-1AB15 ²⁾ 3RW22 30-1AB15 ²⁾ 3RW22 30-0B15 3RW22 38-0DB15 3RW22 38-0DB15 3RW22 38-0DB15 3RW22 38-0DB15 3RW22 40-0DB15 3RW22 42-0DB1. ⁴⁾ 3RW22 43-0DB1. ² / ⁴⁾ 3RW22 45-0DB1. ⁴⁾ 3RW22 45-0DB1. ⁴⁾ | 6.8 11.4 21.4 28.5 35 41 55 80 97 134 160 194 228 280 345 430 610 690 850 1060 | 3 5.5 11 18.5 22 30 45 55 75 90 110 132 160 200 250 355 400 500 630 | 1 × 3NE1 814-0 1 × 3NE1 815-0 1 × 3NE1 815-0 1 × 3NE1 815-0 1 × 3NE1 818-0 1 × 3NE1 820-0 1 × 3NE1 820-0 1 × 3NE1 820-0 1 × 3NE1 225-0 1 × 3NE1 225-0 1 × 3NE1 225-0 1 × 3NE1 230-0 1 × 3NE1 333-0 1 × 3NE1 334-0 1 × 3NE1 334-0 1 × 3NE1 334-0 2 × 3NE1 334-0 2 × 3NE1 334-0 2 × 3NE1 334-0 2 × 3NE1 436-0 ³ 3 × 3NE1 436-0 ³ | 20 25 50 63 80 80 80 250 250 250 250 500 500 500 500 500 630 630 | $\begin{array}{c} 2.5 \\ 4 \\ 10 \\ 16 \\ 25 \\ 25 \\ 25 \\ 25 \\ 25 \\ 25 \\ 25 \\ 2$ | 3NP35, 3NP50, 3NP40 1, 3NP40 7 3NP35, 3NP50, 3NP40 1, 3NP40 7 3NP52, 3NP40 7 3NP52, 3NP42 7 3NP52, 3NP42 7 3NP52, 3NP43 7 3NP54, 3NP44 7, 3NP4 76 3NP54, 3NP44 7, 3NP4 76 3NP54, 3NP44 7, 3NP4 76 3NP54, 3NP44 70, 3NP4 76 2 × 3NP54, 2 × 3NP44 70, 2 × 3NP4 76 2 × 3NP54, 2 × 3NP44 70, 2 × 3NP4 76 3 × 3NP54, 3 × 3NP44 70, 2 × 3NP4 76 | 3KL50 30, 3KM50 30 3KL50 30, 3KM50 30 3KL50 30, 3KM50 30 3KL52 30, 3KM50 30 3KL52 30, 3KM52 30 3KL52 30, 3KM52 30 3KL52 30, 3KM52 30 3KL55 30, 3KM55 30 3KL57 30, 3KM57 30 3KL61 30, 3KM57 30 3KL61 30, 3KM57 30 3KL61 30, 3KM57 30 3KL61 30, 2 x 3KL61 30 2 x 3KL57 30, 2 x 3KL61 30 2 x 3KL61 30 2 x 3KL61 30 2 x 3KL61 30 2 x 3KL61 30 3 x 30 3 |

 The minimum conductor cross-section applies to 40 °C ambient temperature, 79 °C limit temperature. Single laying at a distance and with one fuse per phase. If there is more than one fuse per phase, a larger cross-section must be selected (see factors in parentheses). It may be necessary to lay different cross-sections in the event of deviating conditions (see DIN VDE 0298-4). 2) For these units, the service factor ($l_e \times 1.15$) was used! 3) These fuses do not provide semiconductor protection for voltages > 450 V.

 All-range fuses can only be used for the 415 V and 500 V types (-0DB14 and -0DB15). For the 600 V and 1000 V types (-0DB16 and -0DB18), conductor protection and semiconductor protection fuses must be used, otherwise the soft starter is not sufficiently protected.

| Short-circuit pro | tection fo | or semico | onductors and le | ads with | n SITOR all-ra | ange fuses, type 3NE1 | |
|---|--|---|--|---|--|---|---|
| SIKOSTART | Rated | Rated | Fuse for reduced I | oad: Start | ting current 3 x | I _n for 5 s and 2 starts/h | |
| (<i>T</i> _u = 40 °C) (200 500 V) | current I _N for the motor at 400 V | output P _N of motor at 400 V | SITOR fuse (operational class gR) | Rated current | Conductor protection per fuse ¹⁾ for Cu cable | 3NP fuse switch disconnector | Switch disconnectors for 3KL, 3KM fuses |
| | А | kW | Quantity per phase/type | A | ≥ mm ² | | |
| 3RW22 21-1AB15 3RW22 23-1AB15 ²¹ 3RW22 25-1AB15 3RW22 25-1AB15 3RW22 26-1AB15 3RW22 26-1AB155 3RW22 26-1AB155 3RW22 28-1AB15 3RW22 30-1AB15 ²¹ 3RW22 31-1AB15 ²¹ 3RW22 31-1AB15 ²¹ 3RW22 34-0DB15 3RW22 38-0DB15 3RW22 38-0DB15 3RW22 38-0DB15 3RW22 40-0DB15 3RW22 42-0DB1. ⁴¹ 3RW22 43-0DB1. ²¹⁴ | 6.8 11.4 15.4 21.4 28.5 35 41 55 67 80 97 134 160 194 228 280 345 430 | 3 5.5 7.5 11 15 18.5 22 30 37 45 55 75 90 110 132 160 200 250 355 | 1 x 3NE1 813-0 1 x 3NE1 814-0 1 x 3NE1 814-0 1 x 3NE1 815-0 1 x 3NE1 817-0 1 x 3NE1 821-0 1 x 3NE1 821-0 1 x 3NE1 821-0 1 x 3NE1 821-0 1 x 3NE1 225-0 1 x 3NE1 225-0 1 x 3NE1 227-0 1 x 3NE1 227-0 1 x 3NE1 227-0 1 x 3NE1 227-0 1 x 3NE1 231-0 1 x 3NE1 331-0 2 x 3NE1 331-0 | 16 20 25 35 50 63 63 63 100 100 125 160 200 250 315 350 350 | $\begin{array}{c} 1.5\\ 2.5\\ 4\\ 6\\ 10\\ 16\\ 16\\ 25\\ 35^{3}\\ 35^{3}\\ 50\\ 70\\ 95\\ 120\\ 2\times70\\ 2\times95\\ 2\times95\\ 2\times120\\ (2\times)2\times95\\ (2\times)2\times95\\ \end{array}$ | 3NP35, 3NP50, 3NP40 1, 3NP40 7 3NP35, 3NP50, 3NP40 1, 3NP40 7 3NP50, 3NP40 7 3NP50, 3NP40 7 3NP50, 3NP40 7 3NP50, 3NP40 7 3NP52, 3NP42 7 3NP52, 3NP42 7 3NP52, 3NP42 7 3NP53, 3NP43 7 3NP53, 3NP43 7 3NP54, 3NP44 7, 3NP4 76 2 x 3NP53, 2 x 3NP43 7 | 3KL50 30, 3KM50 30 3KL50 30, 3KM50 30 3KL50 30, 3KM50 30 3KL50 30, 3KM50 30 3KL50 30, 3KM50 30 3KL52 30, 3KM50 30 3KL52 30, 3KM52 30 3KL52 30, 3KM52 30 3KL52 30, 3KM52 30 3KL55 30, 3KM55 30 3KL55 30, 3KM55 30 3KL57 30, 3KM55 30 3KL57, 3KL61 30, 3KM57 30 3KL57, 3KL61 30, 3KM57 30 3KL57, 3KL61 30, 3KM57 30 3KL57, 2 × 3KL61 30 2 × 3KL57, 2 × 3KL61 30 2 × 3KL57, 30, 2 × 3KL57, 2 × 3KL57, 3 3 × 3KL57, 3 × 3KL57, 2 × 3KL57, 2 × 3KL57, 3 3 × 3KL57, 3 × 3KL57, 2 × 3KL57, 2 × 3KL57, 3 3 × 3KL57, 3 × 3KL57, 3 3 × |
| 3RW22 45-0DB1. ⁴⁾ 3RW22 47-0DB1. ⁴⁾ 3RW22 50-0DB1. ⁴⁾ | 690 850 1060 | 400 500 630 | 2 x 3NE1 332-0 2 x 3NE1 334-0 2 x 3NE1 436-0 | 400 500 630 | (2 x) 2 x 95 (2 x) 2 x 120 (2 x) 2 x 185 | 2 x 3NP53, 2 x 3NP43 7 2 x 3NP54, 2 x 3NP44 7, 2 x 3NP4 76 2 x 3NP54, 2 x 3NP44 70, 2 x 3NP4 76 | 2 x 3KL61 30 2 x 3KM57 30 2 x 3KL61 30, 2 x 3KM57 30 2 x 3KL61 30 |

1) The minimum conductor cross-section applies to 40 °C ambient temperature, 79 °C limit temperature. Single laying at a distance and with one fuse per phase. If there is more than one fuse per phase, these fuses must be connected in parallel and a larger cross-section must be selected (see factors in parentheses). It may be necessary to lay different cross-sections in the event of deviating conditions (see DIN VDE 0298-4).

2) For these units, the service factor ($I_e \times 1.15$) was used!

- To connect the unit to 35 mm² cables, they must be converted to 2 x 16 mm² using a terminal block.
- 4) All-range fuses can only be used for the 415 V and 500 V types (-0DB14 and -0DB15). For the 600 V and 1000 V types (-0DB16 and -0DB18), conductor protection and semiconductor protection fuses must be used otherwise the soft starter is not sufficiently protected.

SIKOSTART soft starters

Radio interference suppression

| The 3RW22 units fulfill the requirements for limit value Clas | sА |
|---|----|
| (industrial applications) as standard | |

(industrial applications) as standard. To achieve limit value Class B, a radio interference filter is required.

| | a radio interierence inter is required | J. | | | | | |
|---|--|----------|--|--|--|--|--|
| Climatic conditions | | | SN 29 070 Part 1, climate CLASS J2 | | | | |
| Mechanical conditions | Vibration resistance Shock resistance | | SN 29 010, severity 13 acc. to IEC 60068-2-27 | | | | |
| Noise immunity | | | | | | | |
| Electrostatic discharge acc. to IEC 60801-2 | Test severity Air discharge Contact discharge (direct and indirect) | kV kV | ± 8 ± 4 | | | | |
| Noise immunity Induced RF fields acc. to IEC 60801-6 | | V | 10 V; 0.15 MHz 230 MHz; 80 % AM modulated: 1 kHz | | | | |
| Burst acc. to IEC 60801-4 | Test severity | kV | IV 4 | | | | |
| Surge acc. to IEC 60801-5 | Load and supply voltage Control circuit | kV kV | 4/2 2/1 | | | | |
| Voltage dips acc. to IEC 60947-4-2 | Test | | A, B, C | | | | |
| Emitted interference | | | | | | | |
| Conducted interference voltage acc. to IEC 60947-4-2 | ge Limit CLASS Limit CLASS with single-stage filter | | A B | | | | |
| Noise field intensity acc. to IEC 60947-4-2 | Limit curve | | А | | | | |

To reach limit value class B, the following filters¹⁾ are required:

| Soft starter typ | e Rated operat- ing current | Voltage rang | ge 200 500 | v | Voltage rang | ge 200 415 | v | Voltage ran | Voltage range 500 690 V | | |
|------------------|--------------------------------|-----------------------|------------------------------|--|-----------------------|------------------------------|--|-----------------------|------------------------------|--|--|
| | Soft starter A | Filter type B84143 | Rated current filter A | Connection terminals mm ² | Filter type B84143 | Rated current filter A | Connection terminals mm ² | Filter type B84143 | Rated current filter A | Connectior terminals mm ² | |
| 000000 | 7 | 00.0110 | | | | A | | | A | | |
| 3RW22 21 | 1 | G8-R112 | 8 | 4 | | | | | | | |
| 3RW22 23 | 10.5 | G20-R112 | 20 | 4 | | | | | | | |
| 3RW22 25 | 22 | G36-R112 | 36 | 6 6 6 | | | | | | | |
| 3RW22 26 | 28 | G36-R112 | 36 | 6 | | | | | | | |
| 3RW22 27 | 35 | G36-R112 | 36 | | | | | | | | |
| 3RW22 28 | 45 | G50-R112 | 50 | 16 | | | | | | | |
| 3RW22 30 | 50 | G50-R112 | 50 | 16 | | | | | | | |
| 3RW22 31 | 70 | G66-R112 | 66 | 25 50 | | | | | | | |
| 3RW22 34 | 100 | G120-R112 | 120 | | | | | | | | |
| 3RW22 35 | 135 | G150-R112 | 150 | 50 | | | | | | | |
| 3RW22 36 | 160 | G150-R112 | 150 | 50 | | | | A180-R21 | 180 | 95 | |
| 3RW22 38 | 235 | G220-R112 | 220 | 95 | | | | B250-S21 | 250 | 40 x 25 x 5 | |
| 3RW22 40 | 300 | B320-S20 | 320 | 40 x 25 x 5 ¹ | | | | B320-S21 | 320 | 40 x 25 x 5 | |
| 3RW22 41 | 355 | B400-S20 | 400 | 40 x 25 x 5 ¹⁾ | | | | | | | |
| 3RW22 42 | 450 | B600-S20 | 600 | 40 x 30 x 5 ¹⁾ | | 600 | 40 x 25 x 5 ¹⁾ | | 600 | 40 x 25 x 5 | |
| 3RW22 43 | 560 | B600-S20 | 600 | 40 x 30 x 5 ¹⁾ | B600-S20 | 600 | 40 x 25 x 5 ¹⁾ | B600-S21 | 600 | 40 x 25 x \$ | |
| 3RW22 45 | 700 | B1000-S20 | 1000 | 50 x 40 x 8 ¹⁾ | B1000-S20 | 1000 | 40 x 25 x 5 ¹⁾ | | | | |
| 3RW22 47 | 865 | B1000-S20 | 1000 | 50 x 40 x 8 ¹⁾ | | 1000 | 40 x 25 x 5 ¹⁾ | | 1000 | 40 x 25 x | |
| 3RW22 50 | 1200 | B1600-S20 | 1600 | 50 x 40 x 8 ¹⁾ | | 1600 | 40 x 25 x 5 ¹⁾ | | 1600 | 40 x 25 x 5 | |

Contact address: The suppression filters mentioned above can be ordered from EPCOS AG (see Appendix -> External Partners).

2) Busbar connection: L x W x H.

SIKOSTART soft starters

| Туре | | | | 3RW22B1. | | | | | |
|------------------|---|---|----|---|---|--|--|--|--|
| Version | | | | With solid-state device protection | and RS 232 serial PC interface | | | | |
| Adjustabili | ty of functions in the various de | evice versions | | on the unit, with potentiometers | via a PC, with COM SIKOSTART | | | | |
| Start-up | Breakaway pulse | Amplitude | % | 20 100 x U _n | 21 100 x <i>U</i> _n | | | | |
| | | Duration | ms | 50 1000 | 100 1000 | | | | |
| | Start ramp | Starting voltage | % | 20 100 x <i>U</i> _n | | | | | |
| | | Duration | S | 0.3 180 | 0 1000 | | | | |
| Current limiting | | Amplitude | | 50 % 600 % x $I_{\rm e}$ ($I_{\rm e}$: rated operating current) | Numerical value in ampere, from 1 A to max. 6553 A or max. 6 × I_e (I_e : rated operating current) | | | | |
| | | Duration | | until starting is detected | | | | | |
| | Voltage limiting | Amplitude | % | - | 20 100 x <i>U</i> _n | | | | |
| | | Duration | S | - | 0 1000 | | | | |
| | Start-up detection | Function | | Automatic increase of the motor t reaching the rated speed through | terminal voltage to 100 % x $U_{\rm n}$ on n p.f. and current detection. | | | | |
| | | p.f. detection can be deactivated | | х | | | | | |
| | Emergency start (only start ramp active) | | | x | | | | | |
| Operation | Energy saving mode | | | х | | | | | |
| | Bridging contactor operation | | | Х | | | | | |
| | Continuous operation at max. 115 % <i>I</i> _e (full control of the thyr | istors) | | x | | | | | |
| Starting | Ramp-down | | | х | | | | | |
| | Smooth ramp-down | Starting voltage of the stop ramp | % | fixed 90 x <i>U</i> _n | 20 100 x <i>U</i> _n | | | | |
| | | Switch-off voltage of the stop ramp | % | 85 of the starting voltage of the start ramp | 20 100 x <i>U</i> _n | | | | |
| | | Ramp-down time | S | 1 20 | 0 1000 | | | | |
| | Pump ramp-down | Switch-off voltage of pump ramp-down | % | - | 20 90 x U _n | | | | |
| | | Ramp-down time | S | 5 90 | 5 200 | | | | |
| | DC braking | Braking torque | | Inversely proportional to the braking time, 20 % 85 % of the max. possible braking torque | 20 % 100 % of the max. possi- ble braking torque, regardless of braking time | | | | |
| | | Braking time | S | 3 18 | 1 18 | | | | |

 $U_{\rm n}$ = mains voltage

SIKOSTART soft starters

Selection and ordering data



| 10000 |
|--------|
| 1 · |
| is a D |
| 10.0 |
| |
| H4 |
| 1 |

3RW22 23 and 3RW22 25





3RW22 26 ... 3RW22 31 3RW22 34 ... 3RW22 41

| | | | 0110022 | 20 anu | 01100222 | .0 | | | | | | | | | |
|-------------------------------|---|-------------------|------------------------|-------------------|-------------|-------------|---|---|-------------------|-------------------|-------------|-------------|--|----------------------------|----------------------------|
| Rated operat- | | ent temp | erature 4 | 0 °C | | | At ambie | At ambient temperature 55 °C DT | | | | | Order No. | PS* | Weight |
| ing voltage U _e | Rated operat- ing cur- rent <i>I</i> e | | output of for ratec | | | | Rated operat- ing cur- rent <i>I</i> e | pperatinduction motors for rated operating curing voltage $U_{\rm e}$ | | | | | per PU approx. | | |
| | | 230 V | 400 V | 500 V | 690 V | 1000 V | | 200 V | 230 V | 460 V | 575 V | | | | |
| V | А | kW | kW | kW | kW | kW | А | hp | hp | hp | hp | | | | kg |
| Soft starters and serial F | | | | chrono | ous mot | tors witl | h electro | onic pro | otectior | I | | | | | |
| 200 500 | 7 | 1.5 | 3 | 4 | - | - | 5.5 | 1 | 1 | 3 | - | | 3RW22 21-1AB15 | 1 unit | 2.210 |
| | 10.5 22 | 2.2 5.5 | 4 11 | 5.5 15 | - | - | 9 16 | 2 3 | 2 5 | 5 10 | - | | 3RW22 23-1AB15 3RW22 25-1AB15 | 1 unit 1 unit | 3.560 3.710 |
| | 28 | 7.5 | 15 | 18.5 | - | - | 22 | 5 | 7.5 | 15 | - | | 3RW22 26-1AB15 | 1 unit | 4.910 |
| | 35 45 | 7.5 11 | 18.5 22 | 22 30 | - | - | 32 37 | 10 10 | 10 10 | 20 25 | - | | 3RW22 27-1AB15 3RW22 28-1AB15 | 1 unit 1 unit | 5.460 5.460 |
| | 50 70 | 15 18.5 | 22 37 | 30 45 | - | - | 45 63 | 10 20 | 15 20 | 30 40 | - | | 3RW22 30-1AB15 3RW22 31-1AB15 | 1 unit 1 unit | 8.500 8.920 |
| | 100 135 160 | 30 37 45 | 55 75 90 | 75 90 110 | | - - - | 85 110 140 | 25 30 40 | 30 40 50 | 60 75 100 | - - - | | 3RW22 34-0DB15 3RW22 35-0DB15 3RW22 36-0DB15 | 1 unit 1 unit 1 unit | 16.000 17.100 16.500 |
| | 235 300 355 | 75 90 110 | 132 160 200 | 160 200 250 | | - - - | 205 250 300 | 60 75 100 | 75 100 100 | 150 200 250 | - - - | | 3RW22 38-0DB15 3RW22 40-0DB15 3RW22 41-0DB15 | 1 unit 1 unit 1 unit | 20.600 20.600 20.700 |
| | 450 560 700 | 132 160 200 | 250 315 400 | 315 400 500 | - | | 355 450 560 | 100 150 200 | 125 150 200 | 300 350 450 | | A A A | 3RW22 42-0DB15 3RW22 43-0DB15 3RW22 45-0DB15 | 1 unit 1 unit 1 unit | 62.000 64.100 40.000 |
| | 865 | 250 | 500 | 630 | - | - | 700 | 250 | 250 | 600 | - | А | 3RW22 47-0DB15 | 1 unit | 103.000 |
| | 1200 | 400 | 710 | 900 | - | - | 1000 | 350 | 400 | 850 | - | А | 3RW22 50-0DB15 | 1 unit | 131.000 |
| 200 415 | 450 560 700 | 132 160 200 | 250 315 400 | - - - | - - - | - - - | 355 450 560 | 100 150 200 | 125 150 200 | - - | - - - | A A A | 3RW22 42-0DB14 3RW22 43-0DB14 3RW22 45-0DB14 | 1 unit 1 unit 1 unit | 57.400 58.600 52.000 |
| | 865 | 250 | 500 | - | - | - | 700 | 250 | 250 | - | - | А | 3RW22 47-0DB14 | 1 unit | 96.400 |
| | 1200 | 400 | 710 | - | - | - | 1000 | 350 | 400 | - | - | А | 3RW22 50-0DB14 | 1 unit | 70.000 |
| 500 690 | 160 | - | - | 110 | 160 | - | 140 | - | - | - | 125 | С | 3RW22 36-0DB16 | 1 unit | 17.500 |
| | 235 300 | - | - | 160 200 | 200 315 | - | 205 250 | - | - | - | 200 250 | C C | 3RW22 38-0DB16 3RW22 40-0DB16 | 1 unit 1 unit | 20.600 21.100 |
| | 450 560 | - | - | 315 400 | 450 560 | - | 355 450 | - | - | - | 350 450 | A C | 3RW22 42-0DB16 3RW22 43-0DB16 | 1 unit 1 unit | 57.300 16.200 |
| | 865 | - | - | 630 | 900 | - | 700 | - | - | - | 700 | С | 3RW22 47-0DB16 | 1 unit | 130.000 |
| | 1200 | - | - | 900 | 1200 | - | 1000 | - | - | - | 1000 | Х | 3RW22 50-0DB16 | 1 unit | 130.000 |
| 000 | 160 | - | - | - | - | 200 | 140 | - | - | - | - | С | 3RW22 36-0DB18 | 1 unit | 20.900 |
| | 300 | - | - | - | - | 400 | 250 | - | - | - | - | С | 3RW22 40-0DB18 | 1 unit | 63.600 |
| | 450 | - | - | - | - | 630 | 355 | - | - | - | - | С | 3RW22 42-0DB18 | 1 unit | 45.000 |

The 3RW22 solid-state soft starters are designed for normal operation (inertia load of the overall operating mechanism $J_{\text{load}} < 10 \times J_{\text{motor}}$; starting current 300 % for 30 s or similar load, e.g. large fans). For any other conditions of use, the devices should be selected using the Win-SIKOSTART selection and simulation program. See Technical specifications for information about rated currents for ambient temperatures >40 °C.

Soft starter selection depends on the motor's rated current.

.....

Ta Data Hara

3RW22 21

SIKOSTART soft starters

Accessories

| | DT | Order No. | PS* | Weight per PU approx. |
|---|-------------|---|----------------------------|-------------------------------|
| Planning, Commissioning & Installation manual | | | | kg |
| German English Spanish | X B B | E20001-P285-A484-V3 E20001-P285-A484-V2-7600 E20001-P285-A484-V2-7800 | 1 unit 1 unit 1 unit | on req. on req. on req. |
| COM SIKOSTART PC communication program ¹⁾ | | | | |
| User interface for PC communication via RS 232 serial interface in English, French, German, Italian and Spanish. Disk format 3 1/2" | | 3RW27 01-0AA00 | 1 unit | 0.078 |
| Cable | | | | |
| for PC communication (modified RS 232 cable) 5 m long | | 3RW29 20-1DA00 | 1 unit | 0.176 |
| Enclosure | | | | |
| for IP54 degree of protection for 3RW22 23 3RW22 31 | | 3RW29 20-0AB00 | 1 unit | 8.590 |
| Operating instructions | | | | |
| Operating manuals in English, French, German, Italian, Portuguese and Spanish (supplied with the unit as standard) can be downloaded free of charge as an Acrobat Reader file from the Internet at www.siemens.com/automation/manuals . Enter "SIKOSTART manuals" as a search term or "3RW22 manuals" as the search term. | В | 3ZX1012-0RW22-1AN1 | 1 unit | 0.263 |

1) The program can also be downloaded free of charge from the Internet at www.siemens.de/sanftstarter.

Simply enter the search term "COM SIKOSTART" at this address.

Spare parts

| For solid-state soft starters | Maximum number required per device | DT | Order No. | PS* | Weight per PU approx. |
|---|------------------------------------|-----------------------|--|--|--|
| | | | | | kg |
| Control unit with solid-state device protection and RS 232 seria 3RW220DB14, 3RW220DB15 | l interface | | 3RW29 20-1BC05 | 1 unit | 1,190 |
| 3RW22ODB16 3RW22ODB16 | 1 1 | A A | 3RW29 20-1BC06 3RW29 20-1BC08 | 1 unit 1 unit | 1.210 |
| Thyristor assembly | | | | | |
| 3RW22 42-0DB14, 3RW22 43-0DB14 3RW22 45-0DB14 3RW22 47-0DB14 3RW22 50-0DB14 | 3 3 3 3 | A A D D | 3RW29 20-6KC00 3RW29 20-6KD00 3RW29 20-6KE00 3RW29 20-6KH00 | 1 unit 1 unit 1 unit 1 unit | 8.500 7.140 9.870 26.700 |
| 3RW22 42-0DB15, 3RW22 43-0DB15 3RW22 45-0DB15 3RW22 47-0DB15 3RW22 50-0DB15 | 3 3 3 3 | A A A | 3RW29 20-6LC00 3RW29 20-6LD00 3RW29 20-6LE00 3RW29 20-6LH00 | 1 unit 1 unit 1 unit 1 unit | 4.780 5.630 17.500 25.500 |
| 3RW22 42-0DB16, 3RW22 43-0DB16 3RW22 47-0DB16 | 3 3 | A D | 3RW29 20-6MC00 3RW29 20-6ME00 | 1 unit 1 unit | 9.330 30.000 |
| Current transformers | | | | | |
| 3RW22 34-0DB1., 3RW22 35-0DB1., 3RW22 36-0DB1., 3RW22 37-0DB1. 3RW22 38-0DB1., 3RW22 40-0DB1. 3RW22 41-0DB1. 3RW22 42-0DB1., 3RW22 43-0DB1. 3RW22 45-0DB1. 3RW22 47-0DB1., 3RW22 50-0DB1. | 1 1 1 1 | A A A A A | 3RW29 20-2AD00 3RW29 20-2AE00 3RW29 20-2AK00 3RW29 20-2AH00 3RW29 20-2AL00 3RW29 20-2AJ00 | 1 unit 1 unit 1 unit 1 unit 1 unit 1 unit | 0.336 0.273 0.282 0.515 0.440 0.945 |
| Fans | | | | | |
| 3RW22 34-0DB1., 3RW22 35-0DB1., 3RW22 36-0DB1. ¹⁾ , 3RW22 37-0DB1., 3RW22 38-0DB1. 3RW22 36-0DB18, 3RW22 40-0DB1. ¹⁾ , 3RW22 41-0DB1 3RW22 42-0DB1. ¹⁾ , 3RW22 40-0DB18 | 1 2 3 | A A A | 3RW29 20-3AC00 3RW29 20-3AC00 3RW29 20-3AF00 | 1 unit 1 unit 1 unit | 0.619 0.619 0.718 |
| 3RW22 43-0DB1., 3RW22 42-0DB18, 3RW22 45-0DB1. 3RW22 47-0DB1., 3RW22 50-0DB1. | 3 3 | A | 3RW29 20-3AD00 3RW29 20-3AE00 | 1 unit 1 unit | 1.250 0.985 |
| Surge suppressor circuit | | | | | |
| 3RW22 34-0DB1., 3RW22 35-0DB1., 3RW22 36-0DB1. 3RW22 37-0DB1., 3RW22 38-0DB1., 3RW22 40-0DB1., 3RW22 41-0DB1. 3RW22 42-0DB1., 3RW22 43-0DB1., 3RW22 47-0DB1., 3RW22 50-0DB1. | 1 1 2 | A A A | 3RW29 20-4AC00 3RW29 20-4AD00 3RW29 20-4AD00 | 1 unit 1 unit 1 unit | 0.219 0.285 0.285 |
| Temperature sensors | | | | | |
| 3RW22 21-1AB1. to 3RW22 31-1AB1. 3RW22 34-0DB1. to 3RW22 50-0DB1. | 1 1 | A A | 3RW29 00-3AA00 3RW29 00-3BA00 | 1 unit 1 unit | 0.007 0.008 |
| Covers | | | | | |
| 3RW22 34-0DB1. to 3RW22 41-0DB1. ¹⁾ 3RW22 42-0DB1. to 3RW22 45-0DB1., 3RW22 40-0DB18 3RW22 47-0DB14, 3RW22 47-0DB15 3RW22 47-0DB16, 3RW22 50-0DB1. | 1 1 1 1 | A A D | 3RW29 20-0BA00 3RW29 20-0BB00 3RW29 20-0BC00 3RW29 20-0BD00 | 1 unit 1 unit 1 unit 1 unit | 0.392 2.120 1.700 3.300 |

1) Does not apply to 3RW22 ..-0DB18

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SIKOSTART soft starters

Further information

Configuration

The 3RW22 solid-state starters are designed for normal starting. In case of heavy starting or increased starting frequency, a larger unit must be selected.

If necessary, an overload relay for heavy-starting must be selected where long starting times are involved. PTC thermistor detectors are recommended. This also applies for the ramp-down modes soft ramp-down, pump ramp-down and DC braking, because during the ramp-down time in these modes, an additional current loading applies in contrast to free ramp-down.

In the motor feeder between the SIKOSTART and the motor, no capacitive elements are permitted (e.g. compensation equipment).

All elements of the main circuit (such as fuses, switching devices and overload relays) should be dimensioned for direct starting, following the local short-circuit conditions. Fuses, switching devices and overload relays must be ordered separately.

The harmonic component load for starting currents must be taken into consideration for the selection of circuit-breakers (selection of release).

Use with EEx-protected motors

The units are suitable for starting EEx-protected motors with types of protection "d", "p" and "n", insofar as the relevant mode does not give rise to any expected noteworthy influence of starting behavior on heat development.

Explanation:

- Type of protection
- "d" = flameproof enclosure
- "p" = overpressure enclosure
- "n" = designed for Zone 2

SIEMENS has received a confirmation from the German national standards laboratory (PTB) in Brunswick that, in relation to motors with the type of protection "d", there are no objections to including starting with SIKOSTART within the scope of the conditions upon which the general conformity certificates are based, and that there is no need to expressly mention this.

Express mention of this in the conformity certificate of the motors will also not be necessary in the future.

The devices are suitable for starting EEx-protected motors with types of protection "e" provided heavy starting is not involved. The ramp time on the unit must be set to a value that is at most equal to the T_E time of the machine. A test report with the PTB No. 3.53-542/96 is available.

Manual for SIKOSTART 3RW22

Besides containing all important information on planning, commissioning and servicing, the manual also contains suggested circuits and the technical data for all devices.

Electronic overload protection, serial RS 232 PC interface and COM SIKOSTART PC communication program

In addition to the electronic device protection, the 3RW22 electronic motor controllers feature a PC communication interface.

Together with the PC program COM SIKOSTART, it enables simple parameter definition, control and observation of SIKOSTART 3RW22 via a PC or a notebook.

Once entered, a parameter set can be stored in the PC and then retrieved when defining the parameters of a unit with the same kind of drive.

Parameters can be entered more precisely and independently of one another than when using the potentiometers.

It is also possible to store two or three parameter sets in the SIKOSTART 3RW22. Thus, the units are excellently suitable for use with Dahlander and reversible-pole motors, wind energy systems and for serial starting of motors with different outputs or loads.

Win-SIKOSTART selection and simulation program

With this software, you can simulate and select all Siemens soft starters, taking into account various parameters such as mains properties, motor and load data, and special application requirements.

The software is a valuable tool, which makes complicated, lengthy manual calculations for determining the required soft starters superfluous.

You can order the CD-ROM under the following order number: Order No.: E20001-D1020-P302-X-7400.

SIKOSTART training course (D91/D92)

Siemens offers a 2-day training course on the SIKOSTART solidstate motor controllers to keep customers and own personnel up-to-date on configuring, commissioning and servicing issues.

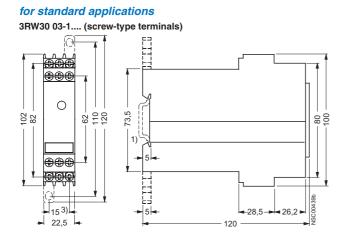
Please direct enquiries and applications to:

Training Center I&S IS E&C TC Werner-von-Siemens-Str. 65 D-91052 Erlangen Telephone:++49 (9131) 72 92 62 Telefax: ++49 (9131) 72 81 72 sibrain@erlg.siemens.de www.siemens.com/sibrain

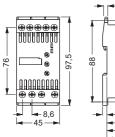
SIRIUS/SIKOSTART Soft Starters For Standard and Advanced Applications

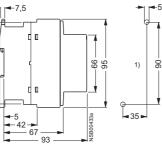
Project planning aids

Dimension drawings

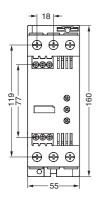


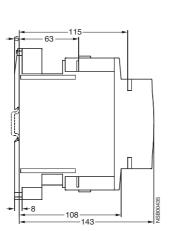
3RW30 1.





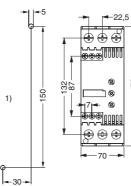
3RW30 3.



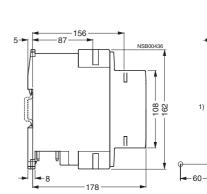


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3RW30 4.

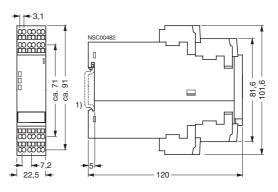


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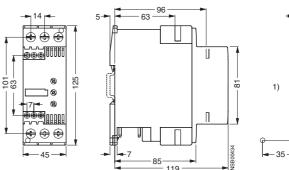


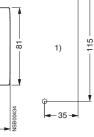
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3RW30 03-2.... (spring-type terminals)



3RW30 2. and 3RW31 2.





▶

₹5

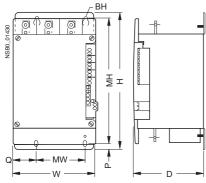
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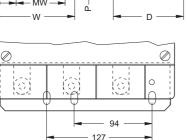
1) Drilling template

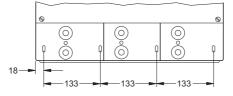
SIRIUS/SIKOSTART Soft Starters For Standard and Advanced Applications

Project planning aids

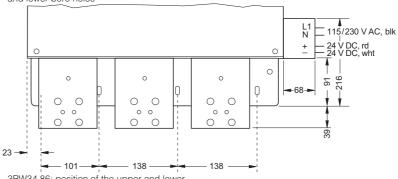
3RW34







3RW34 83/3RW34 84: position of the upper and lower bore holes



³RW34 86: position of the upper and lower bore holes and of the power supply

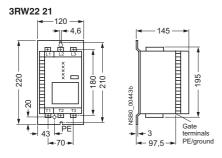
| Туре | / _e ¹⁾ [Ampere] | Width (W) | Height (H) | Depth (D) | Mounting width (MW) | Width offset (Q) | Mounting height (MH) | Height offset (P) | Bore holes (BH) |
|-----------------------------------|--|-------------------|-------------------|-------------------|------------------------|---------------------|-------------------------|----------------------|-------------------------|
| 3RW34 5. 3RW34 6. 3RW34 72 | 57 135 162 235 352 | 216 292 344 | 356 381 417 | 187 189 224 | 127/94 248 286 | 61 22 29 | 327 332 336 | 16 27 45 | 6 (4) 6 (4) 6 (4) |
| 3RW34 83, 3RW34 84 3RW34 86 | 500, 700 1050 | 442 448 | 517 719 | 231 325 | 133 (3) 101/138/138 | 18 23 | 450 653 | 32 29 | 6 (8) 6 (8) |

1) The current values refer to the standard circuit.

for advanced applications

position of the lower bore holes

3RW34 5.:



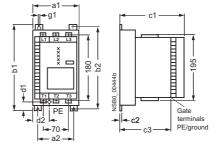
■ Distance to other devices:

For unobstructed supply and extraction of cooling air, the vertical distance to other devices must not be less than the following values:

3RW22 21 to 3RW22 31: 200 mm

Horizontal distance for connection of the control leads only necessary for 3RW22 21 to 3RW22 26.

3RW22 23 to 3RW22 31

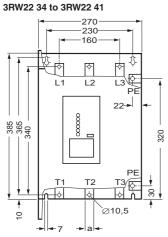


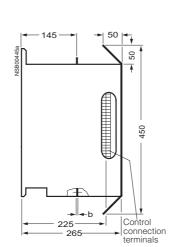
| Туре | a ₁ | a ₂ | b ₁ | b ₂ | C ₁ | C2 | c ₃ | d ₁ | d ₂ | g ₁ |
|----------|----------------|----------------|----------------|----------------|----------------|-----|----------------|----------------|----------------|----------------|
| 3RW22 23 | 125 | 95 | 240 | 230 | 177.5 | 2 | 130 | 30 | 45 | 4.6 |
| 3RW22 25 | 125 | 95 | 240 | 230 | 177.5 | 2 | 130 | 30 | 45 | 4.6 |
| 3RW22 26 | 165 | 135 | 240 | 230 | 180 | 2 | 132.5 | 30 | 65 | 4.6 |
| 3RW22 27 | 205 | 175 | 280 | 270 | 180 | 2 | 132.5 | 50 | 85 | 4.6 |
| 3RW22 28 | 205 | 175 | 280 | 270 | 180 | 2 | 132.5 | 50 | 85 | 4.6 |
| 3RW22 30 | 222.5 | 185 | 290 | 275 | 225 | 2.5 | 175 | 55 | 94 | 6.6 |
| 3RW22 31 | 222.5 | 185 | 290 | 275 | 225 | 2.5 | 175 | 55 | 94 | 6.6 |

SIRIUS/SIKOSTART Soft Starters For Standard and Advanced Applications

3RW22 42 to 3RW22 50

Project planning aids



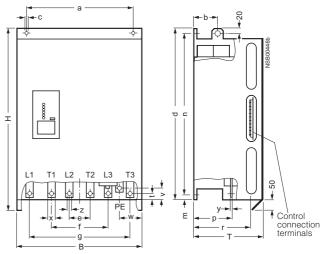


| Туре | а | b |
|------------------------------------|----|---|
| 3RW22 34 to 3RW22 36 | 20 | 3 |
| 3RW22 38 to 3RW22 41 ¹⁾ | 25 | 5 |

Distance to other devices: For unobstructed supply and extraction of cooling air, the vertical distance to other devices must not be less than the following values:

3RW22 34 to 3RW22 45: 200 mm 3RW22 47 and 3RW22 50: 400 mm

3RW22 40-0DB18 has identical dimensions to 3RW22 42-0DB15!

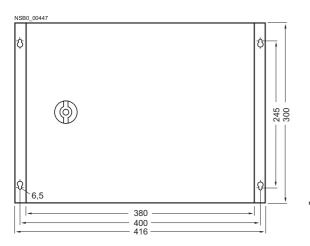


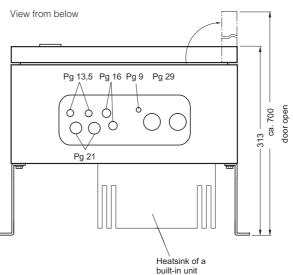
| Туре | Н | В | Т | а | b | С | d | е | f | g |
|------------------------------------|-----|-----|-----|-----|-----|----|-----|-----|-----|-----|
| 3RW22 42, 3RW22 43, 3RW22 45 | 655 | 465 | 255 | 400 | 90 | 11 | 605 | 80 | 210 | 370 |
| 3RW22 47 | 730 | 560 | 340 | 480 | 115 | 11 | 680 | 100 | 260 | 460 |
| 3RW22 50, 3RW22 47-0DB16 | 875 | 600 | 330 | 520 | 115 | 13 | 825 | 105 | 275 | 485 |
| | | | | | | | | | | |

| Туре | m | n | р | r | t | V | w | х | у | Z |
|------------------------------------|----|-----|-----|-----|----|----|------|----|----|----|
| 3RW22 42, 3RW22 43, 3RW22 45 | 15 | 570 | 145 | 215 | 20 | 25 | 87.5 | 30 | 5 | 11 |
| 3RW22 47 | 20 | 645 | 230 | 295 | 25 | 27 | 100 | 40 | 8 | 13 |
| 3RW22 50, 3RW22 47-0DB16 | 20 | 790 | 220 | 285 | 25 | 29 | 110 | 50 | 10 | 13 |

3RW29 20-0AB00

Top view





SIMOCODE-DP motor protection and control devices

Overview

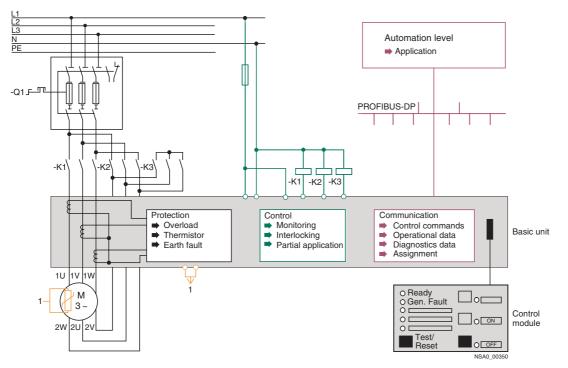


SIMOCODE-DP Basic Unit, Expansion Module and Operator Module

The communication-capable SIMOCODE-DP 3UF5 Motor Protection and Control Unit is used, in particular, in low-voltage controlgear for motor control centers in the process engineeringindustry and forms the intelligent connection between the motor feeder (motors with constant speed) and the process control system. With this technology, plant availability can be increased and at the same time, cost savings are achieved for construction, commissioning and during operation of a plant.

SIMOCODE-DP offers the solution for a wide range of different tasks in a single unit:

- Multifunctional, electronic motor protection and plant monitoring
- Comprehensive motor and plant diagnostics
- Integrated control programs (instead of extensive hardware wiring)
- Open communication via PROFIBUS DP, the standard for fieldbus systems.



Easy construction of a motor feeder with SIMOCODE-DP

Multifunctional, electronic motor protection and plant monitoring

SIMOCODE-DP features a combination of numerous protective mechanisms such as

- Current-sensitive motor protection (CLASS 5-30)
- Thermistor motor protection
- Rotor locking protection
- · Ground-fault monitoring, as well as
- Monitoring adjustable current limits

to ensure problem-free processes.

The current transformer for measuring the motor current is already built into SIMOCODE-DP.

Rated motor currents from 0.25 to 820 A are supported by just six variants.

Comprehensive motor and plant diagnostics

SIMOCODE-DP provides a variety of operating, service and diagnostic data, such as

- The currently flowing phase current
- Switching state of the motor
- Motor operating hours
- Number of switching cycles of the motor
- Number of overload tripping operations, as well as
- Detailed early warning messages or error messages.
- The following advantages result:
- Faults can be prevented
- The plant electrician or process operator is comprehensively informed about the operational status of the load feeder
- Errors can be diagnosed and rectified quickly.

Integrated control programs (instead of extensive hardware wiring)

In SIMOCODE-DP, many predefined motor control functions can be called up, such as

- Direct on-line starter
- Reversing starter
- Star-delta starter
- Two speeds, motors with a separate winding
- Two speeds, motors with a separate Dahlander winding
- Gate valve control
- Solenoid valve or
- Soft starter.

All the interlocks and logic operations necessary for operation of the required motor controls are included in their software and switch the motor contactors on or off directly by means of the SIMOCODE-DP relay outputs.

These ready-to-use control functions can also be adapted to each customized variant of a motor feeder by means of freelyparameterizable elements, such as timers, counters, logic operations (AND, OR, NOR, etc.).

Wiring overhead for the control circuit is reduced considerably and a high level of standardization is achieved for the motor feeder in terms of hardware structure and circuit diagrams.

SIMOCODE-DP motor protection and control devices

Open communication via PROFIBUS DP, the standard for fieldbus systems

SIMOCODE-DP with its integrated PROFIBUS DP interface replaces the complete system of single wires including marshalling racks, which would otherwise be necessary for data transfer to and from the higher-level automation system.

The otherwise complex and expensive cabling is thus reduced to a single 2-wire cable.

SIMOCODE-DP supports the communication functions of

- DP-V0 (cyclic data transfer, GSD configuration, diagnostics) and
- DP-V1 (non-cyclic data transfer, integration into engineering tools with EDD, interrupts).

With SIMOCODE-DP, the following baud rates (Kbits/s) are possible:

- •9.6
- 45.45
- 93.75
- 187.5
- 500
- 1500

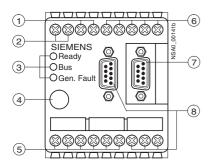
SIMOCODE-DP motor protection and control devices

Design

The SIMOCODE-DP system hardware comprises

- Basic unit
- Expansion module and
- Control module.

Basic unit



① Connection of thermistor or summation transformer

- ② Connection of control supply voltage
 - Three LEDs

3

- ④ Test/reset button for device test or manual reset
- ⑤ Four relay outputs, floating
- 6 Four inputs (24 V)
- ⑦ PC/system interface
- (8) PROFIBUS-DP interface

Front view of the basic unit

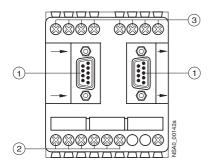
The following variants are available for the basic unit:

- Six different types of construction due to the integrated current transformer for currents up to 820 A; for devices with operating ranges up to 100 A, the current transformers are designed as straight-through current transformers, for higher currents, the current transformers have rail connections
- \bullet Three control voltage variants for DC 24 V, AC 115 V and AC 230 V
- Two variants of sensor input:
- Connection of a thermistor sensor (PTC/NTC/KTY) for direct temperature sensing in the motor winding or

 Connection of a separate summation transformer (3UL2 20.-.A) for detecting small ground-fault currents; this form of "external" ground-fault detection is normally used for networks that are grounded with a high impedance

• Two possible designs of relay outputs: Monostable response (tripping on failure of the control supply voltage) or bistable response (no tripping on failure of the control supply voltage).

Expansion module



PC/system interface
 Four relay outputs, floating

③ Eight inputs (24 V, 115 V, 230 V)

All basic units have four optically decoupled inputs that are supplied via a system-internal DC 24 V voltage. The inputs are freely programmable, i.e. any digital, floating signals can be applied to them for control/monitoring of the motor feeder.

There are also four floating, freely-programmable relay outputs with which any actuators can be controlled (e.g. the motor contactors).

The communication interfaces that are available on the basic unit are the PROFIBUS DP interface as well as an RS232 system interface. PROFIBUS DP can either be connected via a standard Sub-D connector or via terminals (optimal for installation in l.v. switchgear in draw-out design).

The RS232 system interface can be used either to connect additional system components, such as

- an expansion module
- a control module

or a PC complete with WIN-SIMOCODE-DP software.

Front view of expansion module

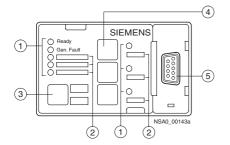
The expansion module with an additional eight freely programmable inputs and four relay outputs is only necessary when the number of inputs and outputs in the basic unit are not sufficient (approximately 10 % of applications).

The control voltage is supplied to the expansion module via the basic unit. The inputs must be supplied from an external supply voltage, alternatively DC 24 V, AC 115 V or AC 230 V.

The left-hand RS232 system interface establishes the connection to the basic unit, the control module or a PC with the appropriate Win-SIMOCODE-DP software can be connected to the right-hand system interface.

SIMOCODE-DP motor protection and control devices

Control module



1 Eight LEDs

- 2 Labelling strips
- ③ Test/reset button for device test or manual reset
- $\check{\textcircled{4}}$ Three control keys
- ⑤ PC/system interface, with cover

Front view of control module

The control module is used to control the motor feeder from the door of the control cabinet and therefore replaces all the conventional pushbuttons and indicator lights that would otherwise be necessary for monitoring and controlling the motor.

Via the RS232 system interface on the rear, the control module can be connected to the basic unit or the expansion module. Power is supplied from the basic unit.

The three pushbuttons are freely programmable, but it is appropriate to use them for controlling the motor feeder.

A total of eight LEDs are available, six of which are freely programmable. Depending on the application, various different signals can be indicated.

A PC with the Win-SIMOCODE-DP software can be connected via the front RS232 system interface (with cover for IP54).

Safe isolation

All electric circuits in SIMOCODE-DP (from product version 12, start of delivery 01/2000) are safely isolated from each other according to

- DIN VDE 0100 (similar to IEC 60364),
- DIN VDE 0106 (or new standard EN 50274),
- EN 50178.

That is, they are designed with double leakage paths and clearances. In the event of a fault, therefore, no parasitic voltages can be formed in neighboring circuits. In this context, compliance with the instructions in the test report *Safe isolation* No. 1610a is required.

Connection and mounting

Devices with current adjustment ranges from 1.25 to 100 A (overall width 70 mm) are designed for installation as a single unit due to the straight-through current transformer, i.e. they are either snapped onto a 35 mm standard rail to EN 50022 or screwed onto a mounting plate using push-in lugs that are available as accessories.

The main conductors are simply passed through the straightthrough current transformer integrated into the enclosure, using multiple loops, loads with rated motor currents of less than 1.25 A can also be protected.

With current adjustment ranges greater than 100 A to 820 A (overall widths: 120 mm, 145 mm and 230 mm), the devices can be directly fitted to the contactor via the connecting rails of the current transformer.

A screw fastening for these devices is integrated in the enclosure.

For the basic units (overall width: 120 mm), a baseplate for snapon attachment on a 75 mm standard mounting rail is available.

Functions

Protective and monitoring functions

For the protection of loads against impermissible high temperature rises

Types of overload protection:

 Current-sensitive, electronic overload protection with adjustable tripping characteristics (class times)

SIMOCODE-DP protects three-phase or AC motors from overloading in accordance with the requirements of IEC 60947-4-1. The class (trip class) indicates the maximum tripping time during which SIMOCODE-DP must trip at 7.2 times the operational current from cold. The trip class can be set in six stages from CLASS 5 to CLASS 30. The switch-off time can therefore be extremely finely adjusted to the load torque of the motor – to optimize utilization of the motor (see also the section *Characteristics*).

• Phase failure / unbalance monitoring

A signal is output for a phase unbalance greater than 40 %. The tripping times of the overload characteristic are reduced, because the heat generated in the motor rises under unbalanced conditions (additional eddy-current losses).

Thermistor motor protection

Temperature-dependent motor protection is based on direct temperature measurements in the motor. These protective functions should be used, in particular, in motors with high operating frequencies, heavy-duty starting, intermittent and/or braking operation, but also in the case of a blocked air supply or speeds lower than the rated speed. For this reason, a wide range of different temperature sensors are available that are installed in the stator winding or in the motor enclosure. SIMOCODE-DP can evaluate the following sensor types:

- Binary PTC sensors whose resistance rises sharply when the temperature limit is reached
- Analog temperature sensors, such as NTC, KTY83/84, which have an almost linear characteristic and can therefore be set to any warning or switch-off temperatures.

EEx e type of protection

The SIMOCODE-DP system is in accordance with the regulations for overload protection of explosion-protected motors of the EEx e "Increased safety" type of protection to

- EN 50019, IEC 60079-7 (increased safety e),
- EN 60079-14, IEC 60079-14 (explosive gas atmospheres),
- EN 50281 (presence of combustible dust),
- and the ATEX/PTB test regulations.

In the case of SIMOCODE-DP units with DC 24 V control infeed, isolation by battery or safety transformer in accordance with EN 61558-2-6 must be assured.

EU prototype test certificate No.: PTB01 ATEX 3219

Test report: PTB EX 01-30013

SIMOCODE-DP motor protection and control devices

Rotor locking protection

When the motor current rises above a rotor locking threshold that can be set, SIMOCODE-DP does not trip in accordance with the overload characteristic, but switches off immediately instead. The prevention of unnecessary thermal loads prevents premature aging of the motor. The rotor locking protection is not active for start-up monitoring until the class time has elapsed, e.g. for *CLASS 10* after 10 seconds.

Ground-fault monitoring

Two qualitatively different ground-fault monitoring functions are offered:

- "Internal" ground-fault monitoring by means of calculation The internal ground-fault monitoring is only suitable for motors with 3-wire connection and for networks that are grounded directly or with a low impedance. In this case, the ground-fault current is calculated by vector addition of the phase currents of the SIMOCODE-DP current transformer. An additional summation current transformer is not necessary. In fault-free systems, the vectorial summation current of the three phases is zero; if this is not the case, an ground-fault is signaled. Groundfault currents that are more than 30 % of the operating current *l*_e are detected.
- External ground-fault monitoring by means of measurement The external ground-fault detection is normally used in supply systems that have a high impedance ground. An additional summation current transformer (3UL2 20.-.A) is required for this method that is also suitable for extremely low ground-fault currents. Detected fault current, depending on the summation current transformer: 0.3/0.5/1 A.

Current limit monitoring I>, I<

Current limit monitoring is not used for motor protection, but for process monitoring.

It is used to detect developing irregularities in the plant early, e.g. motor bearings becoming tight (consequence: upper limit responds) or the belt coupling to the drive machine tears (consequence: lower limit responds).

Comprehensive motor and plant diagnostics

SIMOCODE-DP provides a variety of measuring, operating and diagnostics data concerning the load feeder:

- Up-to-date information during operation, e.g.
- The currently flowing phase current in %
- The switching state of the motor (On, Off, clockwise, counterclockwise, fast, slow) derived from the current flow
- Manual/automatic mode
- Test mode
- Cooling time activated after an overload tripping operation
- Detection of incipient faults, e.g.
- Overload warning
- Current limit overshoot
- Phase unbalance
- Thermistor warning
- Rapid diagnosis in the event of an alarm (up to 30 individual messages), e.g.
- Overload
- Thermistor motor protection
- Rotor locking
- Current limit overshoot
- Checkback error (e.g. no current following On command)
- Preventive maintenance by means of statistical data, e.g.:
- Number of starts
- Number of overload trips
- Tripping currents
- Operating hours.

Integrated standard programs for motor control

In SIMOCODE-DP, a number of different opportunities for controlling the motor have been predefined and can be called up in the form of control functions:

- Overload relay
- Direct on-line starter
- Reversing starter
- Star-delta starter
- Two speeds, Dahlander winding
- Two speeds, separate winding
- Valve
- Actuator
- Soft starter (SIKOSTART).

These control programs already include all the software interlocks and logic operations required for operation of the required motor functions.

It is also monitored whether the checkback for current from the motor feeder is compatible with the control command. If not, SIMOCODE-DP opens the motor contactor and generates an alarm indication.

The motor can be controlled by any equipment in accordance with the application:

- From the process control system of the PC via PROFIBUS DP
- From the control cabinet door via the operator module
- From a local control point on the motor, whereby the pushbuttons/switches are wired to the SIMOCODE-DP inputs.

The standard control functions can also be adapted to each customized variant of a motor feeder by means of freely-parameterizable elements, such as timers, counters, logic operations (AND, OR, NOR, etc.).

Furthermore, special standard function blocks are stored in SIMOCODE-DP:

- Automatic, time-discrete reactivation of motors following mains failure
 - The prerequisites are as follows:
 - Failure of the three-phase supply must take place via a separate voltage relay
 - The supply voltage of SIMOCODE-DP must not be interrupted
- Different error signaling modules with and without acknowledgement

These allow SIMOCODE-DP to trip as a result of external events (e.g. overspeed governor has tripped)

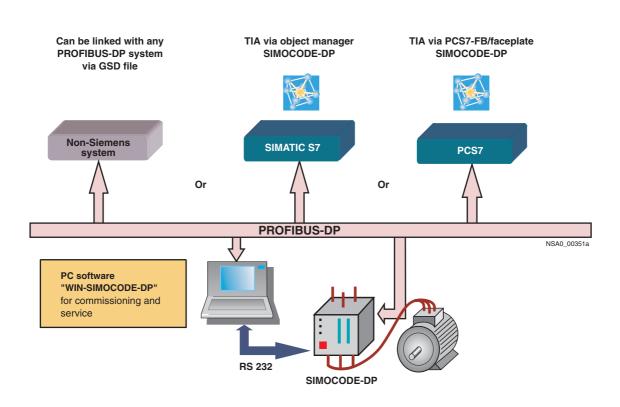
- The emergency start function This resets the thermal memory of SIMOCODE-DP immediately after overload tripping, i.e. immediate restarting is possible (important, for example, for a fire-extinguisher pump)
- The test function for the load feeder This can be activated by switching off the main switch Q1 (see the section Circuit Diagrams) and allows the control circuit to be checked with the motor branch at zero current.

Autonomous operation

A significant feature of SIMOCODE-DP is autonomous processing of all integral protection and control mechanisms, i.e. even in the event of failure of the bus system or automation system, correct functioning of the motor feeder is guaranteed.

SIMOCODE-DP motor protection and control devices





Universal application of SIMOCODE-DP in any automation system

In communication-capable controlgear, over and above the device function and hardware design a great deal of emphasis is placed on system integration, i.e. optimal integration capability in various different system configurations and process automation systems.

For this reason, the SIMOCODE-DP modular system offers as options a wide range of software packages for system-wide and time-saving configuring and diagnostics:

- PC software Win-SIMOCODE-DP for start-up and service
- Object manager OM-SIMOCODE for "totally integrated" in SIMATIC S7
- Function block FB-SIMOCODE for "totally integrated" in PCS7.

PC software Win-SIMOCODE-DP for start-up and service

Win-SIMOCODE-DP is "Plug and Play"-capable, process independent standard PC software for start-up and service.

- It offers a user-friendly and convenient user-interface for
- Parameterization
- Display and diagnostics
- Test functions
- Motor control

Win-SIMOCODE-DP is available in two versions:

- Win-SIMOCODE-DP / Smart Interfacing to SIMOCODE-DP via the RS232 interface, i.e. point-to-point
- Win-SIMOCODE-DP / Professional
- Interfacing to SIMOCODE-DP selectable - Distributed via RS232
- Centrally via PROFIBUS DP (V1).

SIMOCODE-DP motor protection and control devices

Object manager OM-SIMOCODE for "totally integrated" in SIMATIC S7

SIMOCODE-DP can be integrated into SIMATIC S7 in two different ways:

- Conventionally via GSD files

 i.e. integration in SIMATIC S7 is identical to integration in any
 other DP standard master system
- Via the OM-SIMOCODE-DP object manager i.e. SIMOCODE-DP becomes an integral component of STEP 7, the object manager OM-SIMOCODE-DP should, in this case, always be combined with the start-up and service software Win-SIMOCODE-DP/Professional.

Both software packages must be installed on the PG/PC on which the hardware configuration of SIMATIC S7 is performed.

This ensures that Win-SIMOCODE-DP/Professional can be called up directly from HW-Config.

Parameter sets created with Win-SIMOCODE-DP/Professional are loaded into the STEP 7 data storage by means of OM and automatically transferred to SIMOCODE-DP during start-up.

Functions specific to SIMATIC S7, such as diagnostic and hardware interrupts are supported, which means easier S7-wide configuration as well as optimal performance in the transfer of diagnostic data.

Function block FB-SIMOCODE for "totally integrated" in PCS7

System-compatible integration into the PCS7 process control system requires the appropriate function blocks and faceplates for the respective field device.

The PCS7-FB SIMOCODE-DP supports standard processing of the SIMOCODE-DP-specific data in the application program of the automation system.

The faceplate (picture block) SIMOCODE-DP offers a standardized user interface for SIMOCODE-DP on the Operator Station of PCS7.

It is then easy to integrate SIMOCODE-DP into PCS7 and timesavings are achieved during configuration.

The Process Device Manager "PDM" supports centralized parameterization and diagnosis of all field devices on PROFIBUS DP or using the Hart protocol from the PC S7 Engineering Station.

SIMOCODE-DP is integrated into PDM via an appropriate device description. The functional scope corresponds to that of Win-SIMOCODE-DP, the user-interface is, however, uniform for all the different types of field devices.

Technical specifications

| Shared data of basic unit, expansion module and operator modu | e |
|--|--|
| Permissible ambient temperature in °C | -25 +60 |
| Permissible storage temperature in °C | -40 +80 |
| Installation altitude above sea-level in m | ≤ 2000 |
| Degree of protection acc. to IEC 60529 | IP20 max. current setting $I_{\rm e} \le 100$ A; IP00 max. current setting $I_{\rm e} > 100$ A |
| Shock resistance (sine pulse) | 10 g/5 ms |
| Mounting position | Any |
| Mounting max. current setting <i>I</i>_e ≤ 100 A max. current setting <i>I</i>_e > 100 A | Snap-on mounting onto 35 mm standard rail or screw mounting with push-in lugs. Screw mounting directly onto contactor or screw mounting |
| EMC interference immunity • Line-induced interference, burst to IEC 61000-4-4 • Line-induced interference, surge to IEC 61000-4-5 • Electrostatic discharge to IEC 61000-4-2 • Field-related interference to IEC 61000-4-3 | 2 kV (corresponds to degree of severity 3) 2 kV (corresponds to degree of severity 3) 8 kV (corresponds to degree of severity 3) 10 V/m (corresponds to degree of severity 3) |
| EMC emitted interference | Emission limit class B to EN 55011 |
| Safe isolation acc. to DIN VDE 0100 (IEC 60364), DIN VDE 0106, EN 50178 (product version 12 upwards, start of delivery 01/2000) | All circuits in SIMOCODE-DP are safely isolated from each other, they are designed with doubled creepage paths and clearances Power circuit from the control/electronic circuits: Safe isolation up to 690 V or 1000 V between control and electronic circuits |
| | One below the other: Safe isolation up to 300 V |
| | Observe notes of test report "Safe Isolation" No. 1610a. |
| Basic unit | |
| Displays • green LED "Ready" | Continuous light: Ready Off: No control supply voltage" or "Function test not OK; device is disabled" |
| green LED "Bus" red LED "General Fault" | Continuous light: "Bus operation" Continuous light: "Fueder fault", e.g. overload tripping |
| Test/Reset button | By pressing the Test/Reset button, the device can be reset following a trip or its functions can be tested |
| System interface | RS 232 for connecting the expansion module, control module or PC |
| PROFIBUS DP interface | RS 485 for connecting the PROFIBUS DP line via terminals |

RS 485 for connecting the PROFIBUS DP line via terminals (conductor cross-sections as for auxiliary contacts) or 9-pole SUB D socket

SIMOCODE-DP motor protection and control devices

| Main circuit | | | | | |
|---|---|--|---|---|---|
| Rated insulation voltage U _i (for pollution severity 3) in • For uninsulated conductors (3UF5 001 to 3UF5 021) • For insulated conductors (3UF5 001 to 3UF5 021) • For insulated conductors (3UF5 001 to 3UF5 021) • For insulated conductors (3UF5 001 to 3UF5 021) | V | 690 1000 | | | |
| For uninsulated and insulated conductors (3UF5 031 to 3UF5 051) | | 1000 | | | |
| Rated impulse withstand voltage U _{imp} in • 3UF5 001 3UF5 021 • 3UF5 031 3UF5 051 | | 6 8 | | | |
| Rated frequency in Hz | | 50/60 | | | |
| Type of current | | Three-phase | | | |
| Short-circuit protection | | See table Short-circuit pr | otaction with | fucos for m | otor foodore |
| Diameter of feed-through openings (max. $I_{e} = 100 \text{ A}$) in mm | | | | | |
| • Devices with max. operational current $l_e = 25$ A • Devices with max. operational current $l_e = 100$ A • Devices with max. operational current $l_e > 100$ A | | 10 15 Construction with connec | cting bars | | |
| Bar connectionCurrent range in ATightening torque in Nm | | 50 205 M 8: 10 14 | 125 500 M 10: 14 | 24 | 200 820 M 10: 14 24 M 12: 20 35 |
| Solid with cable lug in mm ² Stranded with cable lug in mm ² | | 35 95 50 120 | 50 240 70 240 | | 50 240 70 240 |
| Auxiliary circuit/control circuit | | | | | |
| Rated control supply voltage U _s | | AC 50/60 Hz; 115 V and 2 | 230 V | 24 V DC | |
| Operating range | | AC 50/60 Hz; 0.85 to 1.1 | x U _s | DC 24 V; 0 |).85 1.2 × U _s (DIN 19240) |
| Power consumption | | AC 50/60 Hz; 5 VA | | DC 24 V; 5 | 5 W |
| Rated insulation voltage U _i in V | | 300 (at pollution degree 3 | 3) | | |
| Rated impulse withstand voltage U _{imp} in kV | | 4 | | | |
| Outputs Number Auxiliary contacts of the 4 outputs | | 3 outputs are jointly and they can be freely assigned star and delta contactors | be parame is separate ed to the cor and for sigr | terized with i ely connecte ntrol function naling the op | internal signal conditioning, ed to a common potential; as (e.g. for activating mains, berating status) |
| Specified short-circuit protection for auxiliary contacts (outputs) | | Fuse links, operational cla circuit-breaker 1.6 A, C c | | | ting 10 A; |
| Continuous rated current in A | | 5 | | | |
| Rated operating current (switching capacity) | | AC-15; 6 A/24 V; 6 A/120 DC-13; 2 A/24 V; 0.55 A/6 | | | |
| Inputs | | 4 inputs, supplied by the | device elect ecting proce | ronics (DC 2 ess signals s | 24 V), jointly connected to a such as local control points, |
| $\begin{array}{l} \mbox{Thermistor motor protection (binary PTC thermistor)}\\ \bullet \mbox{Total cold resistance in } k\Omega\\ \bullet \mbox{Response threshold in } k\Omega\\ \bullet \mbox{Return value in } k\Omega \end{array}$ | | 1.5 2.7 3.1 1.5 1.65 | | | |
| Conductor cross-sections Tightening torque in Nm Solid and stranded in mm² Solid with/without end sleeve in mm² | | 0.8 1.2 1 × (0.5 4.0); 2 × (0.5 . 1 × (0.5 2.5); 2 × (0.5 . | | | |
| Expansion module | | | | | |
| System interface | | RS 232 as connection to module or PC | the basic ur | nit and for co | onnecting the control |
| Rated insulation voltage U _i in V | | 300 (at pollution degree 3 | 3) | | |
| Rated impulse withstand voltage Uimp in kV | | 4 | | | |
| Outputs Number Auxiliary contacts of the 4 outputs | | via internal signal condition to common potential; the (e.g. for activating mains, | oning; 3 out y can be fre | outs jointly a ely assigned | onse can be parameterized ind 1 separately connected d to the control functions rs and signaling the operat- |
| Specified short-circuit protection for auxiliary contacts (outputs) | | ing status) Fuse links, operational cli Circuit-breaker 1.6 A, C c | | | ting 10 A; |
| Continuous rated current in A | | 5 | | | |
| Rated operating current (switching capacity) | | AC-15; 6 A/24 V; 6 A/120 DC-13; 2 A/24 V; 0.55 A/6 | | | |
| Inputs | | 8 externally supplied DC | 24 V, AC 11 ecting proce | 5 V, AC 230 ss signals s | V jointly connected to a such as local control points, |
| Conductor cross-sections | | , | | | |
| Tightening torque in Nm | | 0.8 1.2 | | | |
| Solid and stranded in mm² | | 1 × (0.5 4.0); 2 × (0.5 . | | | |
| • Finely stranded with/without end sleeve in mm ² | | 1 × (0.5 2.5); 2 × (0.5 . | | | |

SIMOCODE-DP motor protection and control devices

| Control module | |
|-----------------------------|--|
| Displays | |
| • green LED "Ready" | Continuous light: "Ready" Off: "No control supply voltage" or "Function test not OK; device is disabled" |
| red LED "General Fault" | Continuous light/steady light: "Feeder fault", e.g. overload tripping |
| • 3 green and 3 yellow LEDs | Feeder-specific displays, freely-assignable, e.g. manual/automatic mode, tripping of thermistor protection, clockwise/counterclockwise rotation etc. |
| Buttons | |
| • Test/Reset | By pressing the Test/Reset button, the device can be reset following a trip or its functions can be tested |
| Control keys | For controlling the motor feeder, freely programmable |
| System interface | RS 232 as connection to the basic unit or expansion module and for connection to a PC |

Short-circuit protection with fuses for motor feeders with short-circuit currents up to 50 kA at 690 V for 3RB1 2 and 3UF5 0, Part 1

| Overload | Contac- | CLASS | | | | | | | | | | | | | | |
|----------|-----------------------|----------|----------|----------|------------------------|-----------|-----|------|------|------|------|------|------|------|------|------|
| relay | tor | 5 and 1 | 0 | | 15 | | | 20 | | | 25 | | | 30 | | |
| | | Rated o | peration | al curre | nt / _e AC-: | 3 in A at | V | | | | | | | | | |
| | | 400 | 500 | 690 | 400 | 500 | 690 | 400 | 500 | 690 | 400 | 500 | 690 | 400 | 500 | 690 |
| Adjustm | ent range | 1.25 to | 6.3 A | | | | | | | | | | | | | |
| 3UF5 00 | 3RT1 015 | 6.3 | 5 | 4 | 6.3 | 5 | 4 | 6.3 | 5 | 4 | 6.3 | 5 | 4 | 6.3 | 5 | 4 |
| | 3RT1 016 | 6.3 | 6.3 | 5.2 | 6.3 | 6.3 | 5.2 | 6.3 | 6.3 | 5.2 | 6.3 | 6.3 | 5.2 | 6.3 | 6.3 | 5.2 |
| | 3RT1 017 | 6.3 | 6.3 | 6.3 | 6.3 | 6.3 | 6.3 | 6.3 | 6.3 | 6.3 | 6.3 | 6.3 | 6.3 | 6.3 | 6.3 | 6.3 |
| Adjustm | ent range | 6.3 to 2 | 25 A | | | | | | | | | | | | | |
| 3UF5 01 | 3RT1 015 | | | | 7 | | | 7 | | | 7 | | | 7 | | |
| | 3RT1 016 | 9 | 6.5 | | 9 | 6.5 | | 9 | 6.5 | | 9 | 6.5 | | 9 | 6.5 | |
| | 3RT1 017 | 12 | 9 | 6.3 | 11 | 9 | 6.3 | 10 | 9 | 6.3 | 9.5 | 9 | 6.3 | 9 | 9 | 6.3 |
| | 3RT10 24 | 12 | 12 | 9 | 12 | 12 | 9 | 12 | 12 | 9 | 12 | 12 | 9 | 12 | 12 | 9 |
| | 3RT10 25 | 17 | 17 | 13 | 17 | 17 | 13 | 16 | 16 | 13 | 15 | 15 | 13 | 14 | 14 | 13 |
| | | 25 | 18 | 13 | 18 | 18 | 13 | 16 | 16 | 13 | 15 | 15 | 13 | 14 | 14 | 13 |
| | 3RT10 34 | | 25 | 20 | 25 | 25 | 20 | 22.3 | 22.3 | 20 | 20.3 | 20.3 | 20.3 | 19.1 | 19.1 | 19.1 |
| | 3RT10 35 | | 25 | 24 | 25 | 25 | 24 | 25 | 25 | 24 | 25 | 25 | 24 | 25 | 25 | 24 |
| | ent range | | | | | | | | | _ | _ | | | | | |
| 3UF5 02 | 3RT10 34 | | 32 | 20 | 25.5 | 25.5 | 20 | 22.3 | 22.3 | 20 | 20.3 | 20.3 | 20 | 19.1 | 19.1 | 19.1 |
| | 3RT10 35 | | 40 | 24 | 33 | 33 | 24 | 29.4 | 29.4 | 24 | 28 | 28 | 24 | 26.5 | 26.5 | 24 |
| | | 50 | 50 | 24 | 38.5 | 38.5 | 24 | 32.7 | 32.7 | 24 | 29.4 | 29.4 | 24 | 26.5 | 26.5 | 24 |
| | 3RT10 44 | 65 | 65 | 47 | 56 | 56 | 47 | 49 | 49 | 47 | 45 | 45 | 45 | 41.7 | 41.7 | 41.7 |
| | 3RT10 45 | | 80 | 58 | 61 | 61 | 58 | 53 | 53 | 53 | 47 | 47 | 47 | 45 | 45 | 45 |
| | 3RT10 46 | | 95 | 58 | 69 | 69 | 58 | 59 | 59 | 58 | 53 | 53 | 53 | 50 | 50 | 50 |
| - | ent range | | | 445 | 00 | 00 | 00 | 00 | 00 | 0.0 | 75 | 75 | 75 | 00 | 00 | 00 |
| 3UF5 03 | 3RT10 54 | | 115 | 115 | 93 | 93 | 93 | 82 | 82 | 82 | 75 | 75 | 75 | 69 | 69 | 69 |
| | 3RT10 55 | 150 | 150 | 150 | 122 | 122 | 122 | 107 | 107 | 107 | 98 | 98 | 98 | 90 | 90 | 90 |
| Adiustin | 3RT10 56 ent range | | 185 | 170 | 150 | 150 | 150 | 131 | 131 | 131 | 120 | 120 | 120 | 111 | 111 | 111 |
| 3UF5 04 | 3RT10 64 | | 225 | 225 | 182 | 182 | 182 | 160 | 160 | 160 | 146 | 146 | 146 | 135 | 135 | 135 |
| 30F3 04 | 3RT10.65 | 265 | 265 | 265 | 215 | 215 | 215 | 188 | 188 | 188 | 172 | 172 | 140 | 159 | 159 | 159 |
| | 3RT10 66 | 300 | 300 | 280 | 243 | 243 | 243 | 213 | 213 | 213 | 195 | 195 | 195 | 180 | 180 | 180 |
| | 3RT10 75 | 400 | 400 | 400 | 324 | 324 | 324 | 284 | 284 | 284 | 260 | 260 | 260 | 240 | 240 | 240 |
| | 3RT10 76 | 500 | 500 | 450 | 405 | 405 | 405 | 355 | 355 | 355 | 325 | 325 | 325 | 300 | 300 | 300 |
| | 3RT12 64 | 225 | 225 | 225 | 225 | 225 | 225 | 225 | 225 | 225 | 194 | 194 | 194 | 173 | 173 | 173 |
| | 3RT12 65 | 265 | 265 | 265 | 265 | 265 | 265 | 265 | 265 | 265 | 228 | 228 | 228 | 204 | 204 | 204 |
| | 3RT12 66 | 300 | 300 | 300 | 300 | 300 | 300 | 300 | 300 | 300 | 258 | 258 | 258 | 231 | 231 | 231 |
| | 3RT12 75 | 400 | 400 | 400 | 400 | 400 | 400 | 400 | 400 | 400 | 344 | 344 | 344 | 308 | 308 | 308 |
| | 3RT12 76 | | 500 | 500 | 500 | 500 | 500 | 500 | 500 | 500 | 430 | 430 | 430 | 385 | 385 | 385 |
| Adiustm | ent range | | | | | | | | | 2.30 | | | | | | 500 |
| 3UF5 05 | 3TF68 ¹⁾ | 630 | 630 | 630 | 502 | 502 | 502 | 440 | 440 | 440 | 408 | 408 | 408 | 376 | 376 | 376 |
| | 3TF69 ¹⁾ | 820 | 820 | 820 | 662 | 662 | 662 | 572 | 572 | 572 | 531 | 531 | 531 | 500 | 500 | 500 |

1) Contactors mountable.

2) Pay attention to operating voltage.

3) Type of coordination and short-circuit protection devices according to IEC 60947-4-1/DIN VDE 660 Part 102:
Type of coordination "1": In the event of a short-circuit, the contactor or starter must not endanger persons or the installation. They do not have to be suitable for further operation without repair and the renewal of parts.

SIMOCODE-DP motor protection and control devices

Short-circuit protection with fuses for motor feeders with short-circuit currents up to 50 kA at 690 V for 3RB1 2 and 3UF5 0, Part 2

| Overload relay | Contactor | Fuse links ²⁾ | | | | |
|----------------|---------------------|--|---------------------------------------|-------------|---------------------------------|--------------------------|
| | | 690 V | | | 415 V | 600 V |
| | | NH, DIAZED, NEOZED opera- tional class gL (g | Type 3NA, Type 5SB, Type 5SE G) | Type 3ND aM | British Standards BS88 fuses | UL-listed fuses RK5/L |
| | | Type of coordinat | ion ³⁾ | | | |
| | | 1 | 2 | | | 500 |
| Adjustment ran | ge 1.25 to 6.3 A | | | | | |
| 3UF5 00 | 3RT1 015 | 35 | 20 | | 20 | 25 |
| | 3RT1 016 | 35 | 20 | | 20 | 25 |
| | 3RT1 017 | 35 | 20 | | 20 | 25 |
| Adjustment ran | ge 6.3 to 25 A | | | | | |
| 3UF5 01 | 3RT1 015 | 35 | 20 | | 20 | 60 |
| | 3RT1 016 | 35 | 20 | | 20 | 60 |
| | 3RT1 017 | 35 | 20 | | 20 | 60 |
| | 3RT10 24 | 63 | 25 | 20 | 25 | 70 |
| | 3RT10 25 | 63 | 25 | 20 | 25 | 70 |
| | 3RT10 26 | 100 | 35 | 20 | 25 | 100 |
| | 3RT10 34 | 125 | 63 | 50 | 63 | 100 |
| | 3RT10 35 | 125 | 63 | 50 | 63 | 100 |
| Adjustment ran | | | | | | |
| 3UF5 02 | 3RT10 34 | 125 | 63 | 50 | 63 | 125 |
| | 3RT10 35 | 125 | 63 | 50 | 80 | 160 |
| | 3RT10 36 | 160 | 80 | 50 | 80 | 200 |
| | 3RT10 44 | 250 | 125 | 63 | 125 | 250 |
| | 3RT10 45 | 250 | 160 | 80 | 160 | 250 |
| | 3RT10 46 | 250 | 160 | 100 | 160 | 350 |
| Adjustment ran | ae 50 to 205 A | | | | | |
| 3UF5 03 | 3RT10 54 | 355 | 315 | 160 | 250 | 450 |
| | 3RT10 55 | 355 | 315 | 200 | 315 | 500 |
| | 3RT10 56 | 355 | 315 | 200 | 315 | 500 |
| Adiustment ran | ge 125 to 500 A | | | | | |
| 3UF5 04 | 3RT10 64 | 500 | 400 | 250 | 400 | 700 |
| | 3RT10 65 | 500 | 400 | 315 | 400 | 700 |
| | 3RT10 66 | 500 | 400 | 315 | 400 | 700 |
| | 3RT10 75 | 630 | 400 | 400 | 450 | 1000 |
| | 3RT10 76 | 630 | 500 | 500 | 500 | 1200 |
| | 3RT12 64 | 500 | 500 | 400 | 450 | 800 |
| | 3RT12 65 | 500 | 500 | 400 | 450 | 800 |
| | 3RT12 66 | 500 | 500 | 400 | 450 | 800 |
| | 3RT12 75 | 800 | 800 | 630 | 800 | 1200 |
| | 3RT12 76 | 800 | 800 | 630 | 800 | 1200 |
| Adjustment ran | | | | | | .200 |
| 3UF5 05 | 3TF68 ¹⁾ | 1000 | 500 ⁴⁾ | 630 | 500 | 1200 |
| 301 0 00 | 3TF69 ¹⁾ | 1250 | 630 ⁴⁾ | 630 | 630 | 2000 CLASS L |

• Type of coordination "2": In the event of a short-circuit, the contactor or starter must not endanger persons or the installation. They must be suitable for further operation. There is a danger of contact welding.

 Ensure that the maximum AC-3 operating current is sufficiently different from the rated fuse current.

SIMOCODE-DP motor protection and control devices

Selection and ordering data

| | Version | | | DT | Order No. | PS* | Weight per PU approx. |
|--|---|---|-----------------------------|----|------------------|--------|-----------------------------|
| Basic unit | | | | | | | kg |
| | 4 inputs, 4 outputs for snap-on mounting onto | o 35 mm standar | d mounting rail to EN 50022 | | | | |
| COCCCCCCCC | Contactors that can be mounted externally | Width | Adjustment range | | | | |
| | Туре | mm | А | | | | |
| | - | 70 | 1.25 ¹⁾ 6.3 | С | 3UF5 001-3□□□0-1 | 1 unit | 0.800 |
| AND ADDRESS AND ADDRESS ADDRES | - | 70 | 6.3 25 | С | 3UF5 011-3□□□0-1 | 1 unit | 0.800 |
| 000000000 | - | 70 | 25 100 | С | 3UF5 021-3□□□0-1 | 1 unit | 0.800 |
| 3UF5 001 021 | | | | | | | |
| | 3RT1 05 | 120 | 50 205 | С | 3UF5 031-3□□□0-1 | 1 unit | 1.640 |
| Martine P | 3RT1 06, 3RT1 07 3RT1 26, 3RT1 27 | 145 | 125 500 | С | 3UF5 041-3□□□0-1 | 1 unit | 2.420 |
| | 3TF6 8, 3TF6 9 | 230 | 200 820 | С | 3UF5 051-3□□□0-1 | 1 unit | 4.330 |
| | Inputs | | | | | | |
| A REAL PROPERTY AND A REAL | Input for thermistor motor | protection | | | A | | |
| 3UF5 031 051 | Ground-fault detection inp (sensing of ground fault cu mation current transforme Protective Devices: Overlo SIRIUS Solid-State Overlo | urrents of sizes 0 rs 3UL2 20A, s bad Relays -> S | IRIUS Overload Relays -> | - | В | | |
| | Rated control voltage | | | | | | |
| | 24 V DC | | | _ | В | | |
| | 115 V AC | | | | J | | |
| | 230 V AC | | | _ | N | | |
| | Behavior of the outputs in | case of control : | supply voltage failure | | | | |
| | Monostable | | | | 0 | | |
| | Bistable | | | | 1 | | |

1) The current adjustment range from 0.25 to 1.25 A is attained by looping the main conducting paths.

SIMOCODE-DP motor protection and control devices

| | Version | DT | Order No. | PS* | Weight per PU approx. kg |
|---|--|-------------|--|----------------------------|-----------------------------------|
| Expansion module | 8 inputs, 4 outputs for snap-on mounting on 35 mm standard mounting rail to EN 50022, external supply voltage for the inputs AC 230 V AC 115 V DC 24 V | A C A | 3UF5 100-0AN00 3UF5 100-0AJ00 3UF5 100-0AB00 | 1 unit 1 unit 1 unit | 0.445 0.442 0.422 |
| Control module | For installation in the control cabinet door can be snapped onto basic unit or expansion module | A | 3UF5 202-1AA00-1 | 1 unit | 0.137 |
| Configuration software | Win-SIMOCODE-DP/Professional Parameterization, control, visualization and testing: Via PROFIBUS DPV1 or via RS 232 PC/PG requirement: Windows 95/98/2000/NT/ME or Windows XP PC/PG interface requirement: PROFIBUS system interface from Siemens or RS 232 with compatible 3RW2 920-1DA00 interface cable SIMOCODE-DP requirement: Delivery stage E10 (as of June 1998) Type of delivery: CD, English/German (selectable) incl. online Help and example parameter files, single license | A | 3UF5 710-0AA00-0 | 1 unit | 0.230 |
| Win-SIMOCODE-DP Smart SIRIUS NET SUF57 711-0AA00-0 | Win-SIMOCODE-DP/Smart Parameterization, control, visualization and testing: Via RS 232 PC/PG requirement: Windows 95/98/2000/NT/ME or Windows XP PC/PG interface requirement: RS 232 with compatible 3RW29 920-1DA00 interface cable Type of delivery: CD, English/German (selectable) incl. online Help and example parameter files, single license | A | 3UF5 711-0AA00-0 | 1 unit | 0.231 |
| | OM-SIMOCODE-DP STEP 7 Object Manager for integrating SIMOCODE-DP as S7 slave and for call of Win-SIMOCODE-DP/Professional from STEP 7 • Requirements: STEP 7, Version 4.0 or higher • SIMOCODE-DP requirement: Delivery stage E10 (as of June 1998) • Type of delivery: CD-ROM, English/German (selectable) incl. online Help, single license PCS 7 SIMOCODE-DP function modules | A | 3UF5 712-0AA00-0 | 1 unit | 0.231 |
| 1) Start of delivery please enquire | Function module for integrating SIMOCODE-DP in the PCS 7 user program and for visualizing SIMOCODE-DP-specific data in a faceplate. SIMOCODE-DP requirement: Delivery stage E10 and higher (since June 1998) Type of delivery: CD-ROM, English/German, single user license PCS 7 prerequisites: PCS 7 Version 4.2 to 5.2 PCS 7 Version 6.0 ¹) | AA | 3UF5 720-0AA00-0 3UF5 720-0AA10-0 | 1 unit 1 unit | 0.240 0.240 |

1) Start of delivery, please enquire.

SIMOCODE-DP motor protection and control devices

| Documentation | Version | DT | Order No. | PS* | Weight per PU approx. kg |
|---|---|-------------|--|----------------------------|-----------------------------------|
| | System manual with description of communication via PROFIBUS DP and configuration example with token fee • German • English | n A D | 3UF5 700-0AA00-0 3UF5 700-0AA00-1 | 1 unit 1 unit | 0.841 0.842 |
| Connecting cable, ins | stallation material Connecting cable for PC communication via the RS 232 system interface, 5 m long | • | 3RW2 920-1DA00 | 1 unit | 0.176 |
| | Connecting plug/connecting lead with 3UF5 9/3UF1 9 connectors For connecting the basic unit to the expansion unit, 9-pole, 0.03 m tab connector shielded For connecting the basic unit to the expansion unit or | A | 3UF5 900-1AA00 | 1 unit | 0.020 |
| 3UF1 900-1A 3UF1 900-1B 3UF1 900-1C | operator module, 9-pole - 0.5 m long, shielded plug 45° angular - 2.0 m long, shielded plug 45° angular - 2.5 m long, shielded plug 45° angular | A A A | 3UF1 900-1AA00 3UF1 900-1BA00 3UF1 900-1CA00 | 1 unit 1 unit 1 unit | 0.076 0.161 0.190 |
| | 0.5 m long, with flat plug, shielded 1.0 m long, with flat plug, shielded For connecting basic unit/expansion module to the control cabinet door It is possible to set parameters, operate and monitor using the PC from | A A n | 3UF1 900-1DA00 3UF1 900-1EA00 | 1 unit 1 unit | 0.063 0.092 |
| 3UF1 900-1D 3UF1 900-1E | the control cabinet door, 9-pole - 0.5 m long, with tab connector and socket, shielded - 1.0 m long, with tab connector and socket, shielded T-shaped terminal | A A A | 3UF5 900-0AA00 3UF5 900-0BA00 3UF5 900-1GA00 | 1 unit 1 unit 1 unit | 0.066 0.093 0.045 |
| | Terminal for bus connection to PROFIBUS DP - RS 485 Bus termination Bus termination module with separate supply voltage for terminating the bus following the last unit on the bus line. Supply voltage: | | | | |
| | AC 115/230 V DC 24 V | A A | 3UF1 900-1KA00 3UF1 900-1KB00 | 1 unit 1 unit | 0.286 0.192 |

SIMOCODE-DP motor protection and control devices

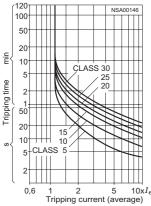
| Poison Poison Poison Poison Base plate For snap-on mounting onto 75 mm standard rail. Only for 3UFS 0 A 3UF1 900-0JA00 1 unit 0.200 With 120 mm overall width with 120 mm overall width A 3UF1 900-0JA00 1 unit 0.200 Base plate For snap-on mounting on mounting plate A 3UF1 900-0JA00 1 unit 0.200 With 120 mm overall width For screw mounting on mounting plate B 3RB1 900-0B 1 unit 0.200 With 900-0B For screw mounting on mounting plate 2 units are required for each 3UFS 0 3RB1 900-0B 1 unit 0.044 Strat 506-0A • For individual mounting or on the outgoing side with direct mounting - 3UF5 0G1 B 3TX7 506-0A 1 unit 0.044 • 3UF5 0G1 with 3TF6 8 B 3TX7 506-0A 1 unit 0.042 • 3UF5 0G1 with 3TF6 9 B 3TX7 506-0B 1 unit 0.019 • 3UF5 0G1 with 3TF6 9 B 3TX7 506-0B 1 unit 0.019 • 3UF5 0G1 with 3TF6 9 B 3TX7 506-0B 1 unit 0.019 • 3UF5 0G1 with 3TF6 9 B 3TX7 506-0B 1 unit 0.019 • 3UF5 0G1 with 3TF6 8 B 3TX7 506-0B 1 unit 0.019 | | Version | DT | Order No. | PS* | Weight |
|--|-----------------------------|--|----|------------------|---------|--------|
| Base plate Ig Base plate For snap-on mounting onto 75 mm standard rail. Only for 3UF5 0 A 3UF1 900-0JA00 1 unit 0.200 3UF1 900-0JA00 1 unit 0.200 Ig Ig 1 unit 0.200 Push-in lugs For screw mounting on mounting plate. > Ig Ig Ig 2.000 Push-in lugs For individual mounting plate. > Ig Ig 2.000 3RB1 900-0B 1 Ig Ig Ig 2.000 Init 0.044 2.000 3RB1 900-0B 1 Ig Ig Ig Ig 2.000 Init 0.044 2.000 Ig 1.014 0.044 2.000 Ig 0.015 Ig 0.014 Ig 0.044 2.015 0.014 Ig 0.014 Ig 0.042 Ig 0.014 Ig 0.014 Ig 0.014 Ig 0.014 Ig 0.014 Ig Ig 0.014 Ig Ig 0.014 Ig Ig | | Version | DI | Order No. | гэ | per PU |
| Base plate For snap-on mounting onto 75 mm standard rail. Only for 3UF5 0 A 3UF1 900-0JA00 1 unit 0.200 SUF1 900-0JA00 SuF1 900-0JA00 1 unit 0.200 0 <td< th=""><th></th><th></th><th></th><th></th><th></th><th></th></td<> | | | | | | |
| For snap-on mounting onto 75 mm standard rail. Only for 3UF5 0 A 3UF1 900-0J000 1 unit 0.200 Suppose the standard rail. Only for 3UF5 0 A Suppose the standard rail. Only for 3UF5 0 A Suppose the standard rail. Only for 3UF5 0 A Suppose the standard rail. Only for 3UF5 0 A Suppose the standard rail. Only for 3UF5 0 A Suppose the standard rail. Only for 3UF5 0 A Suppose the standard rail. Only for 3UF5 0 A Suppose the standard rail. Only for 3UF5 0 A Suppose the standard rail. Only for 3UF5 0 A A Suppose the standard rail. Only for 3UF5 0 A A Suppose the standard rail. Only for 3UF5 0 A | Reco plata | | | | | kg |
| with 120 mm overall width with 120 mm overall width 3UF1 900-0100 Push-in lugs Push-in lugs For screw mounting on mounting plate and the screw mount of the sc | Base plate | For app on mounting apto 75 mm standard roil. Only for 20155 0 | ٨ | 21151 000 0 1400 | 1 unit | 0.200 |
| Push-in lugs For screw mounting on mounting plate 2 units are required for each 3UF5 0 3RB1 900-0B 10 2.000 units 3RB1 900-0B 2 units are required for each 3UF5 0 alk 500 alk 500-0B 1 unit 0.044 Terminal cover • For individual mounting or on the outgoing side with direct mounting - 3UF5 031 B 3TX7 506-0A 2 units 0.112 3UF5 041 B 3TX7 506-0A 2 units 0.112 - 3UF5 051 with 3TF6 8 B 3TX7 506-0A 1 unit 0.042 - 3UF5 051 with 3TF6 9 B 3TX7 506-0A 1 set 0.402 • Between contactor and overload relay for direct mounting - 3UF5 051 with 3TF6 8 B 3TX7 506-0B 1 unit 0.019 - 3UF5 051 with 3TF6 8 B 3TX7 506-0B 1 unit 0.055 - 3UF5 051 with 3TF6 8 B 3TX7 566-0B 1 unit 0.055 - 3UF5 051 with 3TF6 9 B 3TX7 566-0B 1 unit 0.035 - 3UF5 051 with 3TF6 9 B 3TX7 666-0B 1 unit 0.035 - 3UF5 051 with 3TF6 9 B 3TX7 666-0B 1 unit 0.033 Communications processors for SIMATIC S7 </th <th></th> <th>with 120 mm overall width</th> <th>A</th> <th>30F1 900-03A00</th> <th>T UML</th> <th>0.200</th> | | with 120 mm overall width | A | 30F1 900-03A00 | T UML | 0.200 |
| For screw mounting on mounting plate 2 units are required for each 3UF5 0 3RB1 900-0B 10 2.000 3RB1 900-0B Terminal cover • For individual mounting or on the outgoing side with direct mounting - 3UF5 031 B 3TX7 506-0A 1 unit 0.044 3UF5 051 - 3UF5 051 B 3TX7 506-0A 1 unit 0.044 - 3UF5 051 with 3TF6 8 B 3TX7 506-0A 1 set 0.410 - 3UF5 051 with 3TF6 9 B 3TX7 506-0A 1 set 0.402 • Between contactor and overload relay for direct mounting - 3UF5 051 with 3TF6 9 B 3TX7 506-0B 1 unit 0.019 • 3UF5 051 with 3TF6 9 B 3TX7 506-0B 1 unit 0.055 • 3UF5 051 with 3TF6 9 B 3TX7 506-0B 1 unit 0.055 • 3UF5 051 with 3TF6 9 B 3TX7 666-0B 1 unit 0.053 • 3UF5 051 with 3TF6 9 B 3TX7 696-0B 1 unit 0.053 • 3UF5 051 with 3TF6 9 B 3TX7 696-0B 1 unit 0.033 Communications processors for SIMATIC S7 See ST 70 Catalog See IK PI Catalog See IK PI Catalog See IK PI Catalog See IK PI | | | | | | |
| 2 units are required for each 3UF5 0 units 3RB1 900-0B units Terminal cover • For individual mounting or on the outgoing side with direct mounting 3UF5 051 B 3TX7 506-0A 1 unit 0.044 3UF5 051 with 3TF6 8 3UF5 051 with 3TF6 9 B 3TX7 506-0A 1 set 0.402 ************************************ | Push-in lugs | | | | | |
| Terminal cover For individual mounting or on the outgoing side with direct mounting 3UF5 031 3UF5 031 3UF5 041 3UF5 051 with 3TF6 8 3UF5 051 with 3TF6 9 3TX7 506-0A 1 unit 0.044 3UF5 051 with 3TF6 8 B 3TX7 506-0A 1 unit 0.402 3TX7 506-0A • Between contactor and overload relay for direct mounting 1 unit 0.402 • Between contactor and overload relay for direct mounting • SUF5 051 with 3TF6 8 B 3TX7 506-0B 1 unit 0.019 • JUF5 051 • Between contactor and overload relay for direct mounting • JUF5 051 • JUF5 051 1 unit 0.019 • 3UF5 051 with 3TF6 8 B 3TX7 506-0B 1 unit 0.019 • 3UF5 051 with 3TF6 8 B 3TX7 536-0B 1 unit 0.005 • 3UF5 051 with 3TF6 8 B 3TX7 586-0B 1 unit 0.005 • 3UF5 051 with 3TF6 8 B 3TX7 586-0B 1 unit 0.008 • 3UF5 051 with 3TF6 8 B 3TX7 586-0B 1 unit 0.008 • 3UF5 051 with 3TF6 9 B | 3BB1 900-0B | For screw mounting on mounting plate 2 units are required for each 3UF5 0 | • | 3RB1 900-0B | | 2.000 |
| For individual mounting or on the outgoing side with direct mounting - 3UF5 031 - 3UF5 031 - 3UF5 041 - 3UF5 051 with 3TF6 8 - 3UF5 051 with 3TF6 8 - 3UF5 051 with 3TF6 9 - 3UF5 051 - 3UF5 051 - 3UF5 051 - 3UF5 051 with 3TF6 8 - 3UF5 051 with 3TF6 9 - 3UF5 051 wi | | | | | | |
| - 3UF5 041 B 3TX7 536-0A 2 units 0.112 - 3UF5 051 with 3TF6 8 B 3TX7 686-0A 1 set 0.402 - 3UF5 051 with 3TF6 9 B 3TX7 696-0A 1 set 0.402 - 3UF5 051 with 3TF6 9 B 3TX7 506-0A 1 set 0.402 - 3UF5 051 with 3TF6 9 B 3TX7 506-0B 1 unit 0.019 - 3UF5 051 - 3UF5 051 B 3TX7 506-0B 1 unit 0.019 - 3UF5 051 - 3UF5 051 with 3TF6 8 B 3TX7 506-0B 1 unit 0.055 - 3UF5 051 with 3TF6 8 B 3TX7 696-0B 1 unit 0.055 - 3UF5 051 with 3TF6 9 B 3TX7 696-0B 1 unit 0.055 - 3UF5 051 with 3TF6 9 B 3TX7 696-0B 1 unit 0.035 Communications processors for SIMATIC ST See IK PI Catalog 1 unit 0.103 See IK PI Catalog See IK PI Catalog 5 5 5 See IK PI Catalog 5 5 5 5 5 See IK PI Catalog 5 5 5 5 5 <tr< td=""><td>en to be as</td><td>For individual mounting or on the outgoing side with direct mounting</td><td></td><th></th><td></td><td></td></tr<> | en to be as | For individual mounting or on the outgoing side with direct mounting | | | | |
| - 3UF5 051 with 3TF6 8 B 3TX7 686-0A 1 set 0.410 - 3UF5 051 with 3TF6 9 B 3TX7 696-0A 1 set 0.402 - 3UF5 051 with 3TF6 9 B 3TX7 506-0A 1 set 0.402 - 3UF5 051 with 3TF6 9 B 3TX7 506-0B 1 unit 0.019 - 3UF5 051 - 3UF5 051 B 3TX7 506-0B 1 unit 0.019 - 3UF5 051 - 3UF5 051 with 3TF6 8 B 3TX7 506-0B 1 unit 0.055 3TX7 506-0B - 3UF5 051 with 3TF6 9 B 3TX7 686-0B 1 unit 0.055 1 unit 0.055 1 unit 0.019 1 unit 0.055 3TX7 506-0B B 3TX7 686-0B 1 unit 0.055 1 unit 0.019 1 unit 0.019 1 unit 0.010 1 unit 0.013 Communications processors for SIMATIC S7 See IK PI Catalog See IK PI Catalog | and the second second | - 3UF5 031 | В | 3TX7 506-0A | 1 unit | 0.044 |
| - 3UF5 051 with 3TF6 9 B 3TX7 696-0A 1 set 0.402 3TX7 506-0A - 8etween contactor and overload relay for direct mounting - - - - - - - - - 0.402 - 3UF5 051 - 8etween contactor and overload relay for direct mounting - <td< td=""><td></td><td>- 3UF5 041</td><td>В</td><th>3TX7 536-0A</th><td>2 units</td><td>0.112</td></td<> | | - 3UF5 041 | В | 3TX7 536-0A | 2 units | 0.112 |
| 3TX7 506-0A • Between contactor and overload relay for direct mounting • 3UF5 031 B 3TX7 506-0B 1 unit 0.019 • 3UF5 031 B 3TX7 506-0B 1 unit 0.055 • 3UF5 051 with 3TF6 8 B 3TX7 686-0B 1 unit 0.055 • 3UF5 051 with 3TF6 9 B 3TX7 696-0B 1 unit 0.085 • 3UF5 051 with 3TF6 9 B 3TX7 696-0B 1 unit 0.085 • 3UF5 051 with 3TF6 9 B 3TX7 696-0B 1 unit 0.085 • 3UF5 051 with 3TF6 9 B 3TX7 696-0B 1 unit 0.103 Communications processors for SIMATIC S7 See ST 70 Catalog I I I See IK PI Catalog I See IK PI Catalog I I I I See IK PI Catalog I See IK PI Catalog I I I I I See IK PI Catalog I See IK PI Catalog I I I I I See IK PI Catalog I See IK PI Catalog I I I I I I See IK PI Catalog | e k k V | - 3UF5 051 with 3TF6 8 | В | 3TX7 686-0A | 1 set | 0.410 |
| - 3UF5 031 B 3TX7 506-0B 1 unit 0.019 - 3UF5 041 B 3TX7 536-0B 1 unit 0.055 - 3UF5 051 with 3TF6 8 B 3TX7 686-0B 1 unit 0.085 - 3UF5 051 with 3TF6 9 B 3TX7 696-0B 1 unit 0.085 - 3UF5 051 with 3TF6 9 B 3TX7 696-0B 1 unit 0.085 - 3UF5 051 with 3TF6 9 B 3TX7 696-0B 1 unit 0.103 Communications processors for SIMATIC S7 - - - - See ST 70 Catalog - - - - - Bus lines for PROFIBUS - - - - - - See IK PI Catalog - | 3TX7 506-0A | - 3UF5 051 with 3TF6 9 | В | 3TX7 696-0A | 1 set | 0.402 |
| - 3UF5 031 B 3TX7 506-0B 1 unit 0.019 - 3UF5 041 B 3TX7 536-0B 1 unit 0.055 - 3UF5 051 with 3TF6 8 B 3TX7 686-0B 1 unit 0.085 - 3UF5 051 with 3TF6 9 B 3TX7 696-0B 1 unit 0.085 - 3UF5 051 with 3TF6 9 B 3TX7 696-0B 1 unit 0.085 - 3UF5 051 with 3TF6 9 B 3TX7 696-0B 1 unit 0.103 Communications processors for SIMATIC S7 - - - - See ST 70 Catalog - - - - - Bus lines for PROFIBUS - - - - - - See IK PI Catalog - | | Between contactor and overload relay for direct mounting | | | | |
| - 3UF5 041 B 3TX7 536-0B 1 unit 0.055 3TX7 506-0B - 3UF5 051 with 3TF6 8 B 3TX7 686-0B 1 unit 0.085 3TX7 506-0B - 3UF5 051 with 3TF6 9 B 3TX7 696-0B 1 unit 0.085 Communications processors for SIMATIC S7 See ST 70 Catalog Bus lines for PROFIBUS See IK PI Catalog See IK PI Catalog See IK PI Catalog See IK PI Catalog Components for optical-fiber connection | | , | В | 3TX7 506-0B | 1 unit | 0.019 |
| - 3UF5 051 with 3TF6 8B3TX7 686-0B1 unit0.0853TX7 506-0B- 3UF5 051 with 3TF6 9B3TX7 696-0B1 unit0.103Communications processors for SIMATIC S7 See ST 70 CatalogSee ST 70 CatalogSee IK PI CatalogComponents for optical-fiber connection | Balla M. | | | | | |
| 3TX7 506-0B - 3UF5 051 with 3TF6 9 B 3TX7 696-0B 1 unit 0.103 Communications processors for SIMATIC S7 See ST 70 Catalog Bus lines for PROFIBUS See IK PI Catalog 9-pin bus connectors with bus termination resistor See IK PI Catalog Components for optical-fiber connection | | | | | | |
| See ST 70 Catalog Bus lines for PROFIBUS See IK PI Catalog 9-pin bus connectors with bus termination resistor See IK PI Catalog Components for optical-fiber connection | 3TX7 506-0B | - 3UF5 051 with 3TF6 9 | В | 3TX7 696-0B | 1 unit | 0.103 |
| See ST 70 Catalog Bus lines for PROFIBUS See IK PI Catalog 9-pin bus connectors with bus termination resistor See IK PI Catalog Components for optical-fiber connection | Communications processor | | _ | | | |
| Bus lines for PROFIBUS See IK PI Catalog 9-pin bus connectors with bus termination resistor See IK PI Catalog Components for optical-fiber connection | - communications processor | | | | | |
| See IK PI Catalog 9-pin bus connectors with bus termination resistor See IK PI Catalog Components for optical-fiber connection | Bus lines for PROFIBUS | | | | | |
| 9-pin bus connectors with bus termination resistor See IK PI Catalog Components for optical-fiber connection | | See IK PI Catalog | | • | | |
| See IK PI Catalog Components for optical-fiber connection | 9-pin bus connectors with b | | | | | |
| Components for optical-fiber connection | | | | • | | |
| | Components for optical-fibe | | | | | |
| | | | | | | |

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SIMOCODE-DP motor protection and control devices

Characteristics

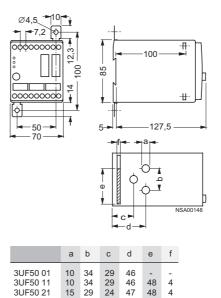
Tripping characteristic for 3-pole loading





Dimension drawings

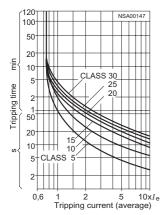
3UF5 001, 3UF5 011 and 3UF5 021 basic units



The current-time curves for 3-pole symmetrical load show the re-lationship between the release time from cold and multiples of the operational current

If the device is pre-loaded with 100 % of the current setting, the tripping times are reduced.

Tripping characteristic for 2-pole loading



In the case of 2-pole loading (failure of one phase) or current unbalance > 40 % of the current setting, the tripping times are re-duced, because the heat generated due to the unbalanced loading of the motor rises.

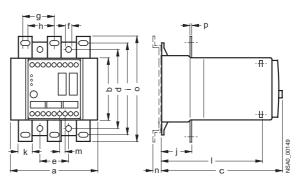
3UF5 031, 3UF5 041 and 3UF5 051 basic units

15 29

3UF50 21

46 48 4 4

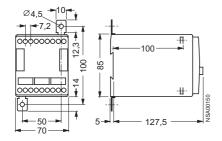
47 48

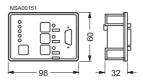


| | а | b | С | d | е | f | g | h |
|----------|-----|----|-----|-----|-----|------|-----|----|
| 3UF5 031 | 120 | 85 | 155 | 110 | 40 | Ø7 | 42 | 37 |
| 3UF5 041 | 145 | 85 | 175 | 105 | 50 | Ø 9 | 52 | 48 |
| 3UF5 051 | 230 | 85 | 190 | 120 | 70 | Ø 11 | 70 | - |
| | | | | | | | | |
| | | | | | | | | |
| | i | j | k | Ι | m | n | 0 | р |
| 3UF5 031 | 125 | 41 | 20 | 131 | 7,2 | 13 | 145 | 4 |
| 3UF5 041 | 130 | 46 | 30 | 151 | 7,2 | _ | 160 | 6 |
| 3UF5 051 | 135 | 55 | 40 | 166 | 7,2 | - | 175 | 8 |

SIMOCODE-DP motor protection and control devices

3UF5 2 control module

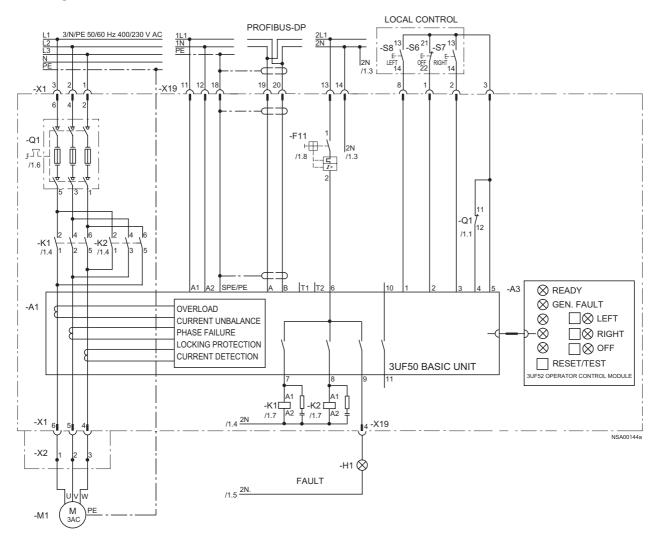




Circuit diagrams

3UF5 1 expansion module

Reversing starter circuit with SIMOCODE-DP



Further circuit diagrams for the control functions overload, direct online starter, star-delta starter, pole reversing, Dahlander polechanging circuit, solenoid valve, gate valve (servo drive) and SIKOSTART 3RW2 2 and a configuration example are included in the 3UF5 7 system manual.

SIMOCODE-DP motor protection and control devices

Further information

System manual

For selection of equipment and for planning, it is recommended that the 3UF5 7 system manual is consulted (see Selection and ordering data page 3/88).

CD-ROM "SIMOCODE-DP, Intelligence at the Field Level"

Concise introduction to the system landscape of SIMOCODE-DP, including 3UF57 manual, Win-SIMOCODE-DP/Smart demo parameterization software, example circuit diagrams, etc. (Order No. E2001-D1140-P21S-X-7400)

Configuration course

Two-day configuration course for SIMOCODE-DP (device spectrum, functions, communications capability, practical exercises). For further details and registration, please contact:

• Tel: +49 (9131) 7-2 79 72

• Fax:+49 (9131) 7-2 81 72

Internet

You can find further information on the Internet at:

www.siemens.de/simocode-dp

The 3UF1 8 current transformers convert the maximum current of the corresponding operating range into the standard signal

1 A secondary.

Current transformers for overload protection

Overview

The 3UF1 8 current transformers are protection transformers and are used for actuating overload relays. Protection transformers are designed to ensure proportional current transfer up to a multiple of the primary rated current.

Technical specifications

| Climatic environmental conditions | | | | | | | | | | | | | |
|--|-----------------------------------|--|------------------------|------------------------|-------------|---------------------------|----------------------------------|----------------------------------|--|--|--|--|--|
| Ambient temperature in °C | | | | | | | | | | | | | |
| Operation | -25 +60 | | | | | | | | | | | | |
| Storage/transport | -40 +85 | | | | | | | | | | | | |
| Temperature change in °C/h | | | | | | | | | | | | | |
| Operation | max. 10 | ax. 10 | | | | | | | | | | | |
| Storage/transport | max. 20 | | | | | | | | | | | | |
| Relative humidity in % | 15 95 (ind | 15 95 (indoor, acc. to DIN 40040, no condensation) | | | | | | | | | | | |
| Air pressure in hPa | | | | | | | | | | | | | |
| Operation | 860 1060 | | | | | | | | | | | | |
| Storage/transport | 650 1060 | | | | | | | | | | | | |
| Contaminants in ppm | | | | | | | | | | | | | |
| • SO ₂ | 0.5 (relative | humidity < 60 | 0 %, no cond | ensation) | | | | | | | | | |
| • H ₂ S | • | | 0 %, no cond | · · | | | | | | | | | |
| Mechanical environmental conditions | | | o ,o, no oona | onounony | | | | | | | | | |
| Vibrations in Hz acc. to IEC 60068-2-6 | 10 57 (for | r constant am | plitude 0.15 i | nm) | | | | | | | | | |
| | | | cceleration 2 | | | | | | | | | | |
| Shock to IEC 60068-2-27 | 12 shocks (| half sine 15 g | j/11 ms) | | | | | | | | | | |
| Requirements acc. to IEC, DIN and VDE | | J | , | | | | | | | | | | |
| Degree of protection to IEC 60529 | IP20 | | | | | | | | | | | | |
| Rated insulation voltage in V acc.to IEC 60664 | 690/1000 (ty | /pe-depende | ent) | | | | | | | | | | |
| Rating of the insulation in V (to UL/CSA) | 600 | | | | | | | | | | | | |
| Trip class acc. to IEC 60947-4-1 | suitable from CLASS 5 to CLASS 30 | | | | | | | | | | | | |
| Power loss per conducting path of the transformers | Operating r | | for setting | • | | | | | | | | | |
| | | | to the lower | limit | | to the upper | limit | | | | | | |
| | ٨ | | | | | | | | | | | | |
| • 3UF1 845 | 12.5 50 | | 33 (38) | | | mW (mVA) 570 (650) | | | | | | | |
| • 3UF1 848 | 25 100 | | 110 (120) | | 1700 (1900) | | | | | | | | |
| | 32 130 | | | | | . , | | | | | | | |
| • 3UF1 850 | | | 135 (150) | | | 2400 (2700) | | | | | | | |
| • 3UF1 852 | 50 200 | | 170 (190) | | | 2600 (2900) | | | | | | | |
| • 3UF1 856 | 100 400 | | 450 (500) | | | 6500 (7000) | | | | | | | |
| • 3UF1 857 | 125 500 | | 850 (940) | | | 13000 (15000) | | | | | | | |
| • 3UF1 868-3F | 160 630 | | 900 (1000) | | | 17000 (1900 | · | | | | | | |
| • 3UF1 868-3G | 205 820 | | 1400 (1600) |) | | 22000 (2500 |)0) | | | | | | |
| Conductor cross-sections (one or two conductors connectable) | Current tran | sformers | | | | | | | | | | | |
| | on second- ary side | on primary : | side | | | | | | | | | | |
| | | 3UF1 845 | 3UF1 848 ¹⁾ | 3UF1 850 ¹⁾ | 3UF1 852 | 3UF1 856 3UF1 857 | 3UF1 868- 3FA00 ²⁾ | 3UF1 868- 3GA00 ²⁾ | | | | | |
| Terminal screw | M 3.5 | For con. | For con. | For con. | M 8 | M 10 | M 10 | M 12 | | | | | |
| • Solid in mm ² | 2 × 1.5 2.5 | data see 3RT con- | data see 3RT con- | data see 3RT con- | - | - | - | - | | | | | |
| • Stranded in mm ² | 2 × 1.5 2.5 | tactors in Part 2 | tactors in Part 2 | tactors in Part 2 | - | - | - | - | | | | | |
| Finely stranded without end sleeve in mm² | - | | | | | | | _ | | | | | |
| Finely stranded without end sleeve in mm² | - 2 × 1.5 | | | | | | | | | | | | |
| Finely stranded with end sleeve in min Finely stranded with cable lug in mm² | 2 ~ 1.5 | | | | - 35 95 | - 50 240 ³⁾ | 50 240 | - 185 240 | | | | | |
| , | - | | | | | | | | | | | | |
| Stranded with cable lug in mm ² | - | | | | 50 120 | 70 240 ³⁾ | | 185 240 | | | | | |
| Connecting bars in mm | - | | | | 20 × 4 | 25 × 6.30 × 6 | 30 × 5 | 50 × 5 | | | | | |
| Tightening torque in Nm | 0.8 1.4 | | | | 10 14 | 14 24 | 14 24 | 14 24 | | | | | |
| Tightening torque in Ib.in | 7 12 | | | | 89 124 | 124 210 | 124 210 | | | | | | |
| | 1 12 | | | | 55 124 | 127210 | 127210 | 127210 | | | | | |

1) With or without box terminal.

Conductor cross-sections for box terminals, see 3TF68 and 3TF69 contac-tors in section contactors and contactor combinations.

3) With max. conductor cross-section, a terminal cover for maintaining the phase spacing is required.

Current transformers for overload protection

Short-circuit protection with fuses for motor feeders for short-circuit currents up to 50 kA at 690 V⁴), 50/60 Hz

| Overload relay | Contactor | Rated oper | ational curre | ent AC-3 in A | at 400 V and 0 | CLASS | Type of c | pordination ²⁾ | | |
|----------------|--------------|------------|---------------|---------------|----------------|-------|--|---------------------------|-----------------|----------------------|
| | | 5 and 10 | 15 | 20 | 25 | 30 | 1 Fuse link | | | |
| | | | | | | | NH, Type DIAZED, NEOZED gL/gG | | Type 3ND, aM | British Standards |
| | | | | | | | | | | BS88 fuse |
| Operating rang | - | | | | | | | | | |
| 3UF1 843-1BA00 | | 2.5 | 2.5 | 2.5 | 2.5 | 2.5 | 25 | 10 | - | - |
| Operating rang | - | | | | | | | | | |
| 3UF1 843-1AA00 | 3RT1 015 | 7 | 7 | 7 | 7 | 7 | 25 | 10 | - | - |
| | 3RT1 016 | 9 | 9 | 9 | 9 | 9 | 25 | 10 | - | - |
| | 3RT1 017 | 12 | 11 | 10 | 9.5 | 9 | 25 | 10 | - | - |
| | 3RT1 024 | 12 | 12 | 12 | 12 | 12 | 35 | 16 | 20 | 35 |
| | 3RT1 025 | 12.5 | 12.5 | 12.5 | 12.5 | 12.5 | 35 | 16 | 20 | 35 |
| Operating rang | ge 2.5 to 25 | A | | | | | | | | |
| 3UF1 843-2BA00 | 3RT1 015 | 7 | 7 | 7 | 7 | 7 | 25 | 10 | - | - |
| | 3RT1 016 | 9 | 9 | 9 | 9 | 9 | 25 | 10 | - | - |
| | 3RT1 017 | 12 | 11 | 10 | 9.5 | 9 | 25 | 10 | - | - |
| | 3RT1 024 | 12 | 12 | 12 | 12 | 12 | 63 | 25 | 20 | 35 |
| | 3RT1 025 | 17 | 17 | 16 | 15 | 14 | 63 | 25 | 20 | 35 |
| | 3RT1 026 | 25 | 18 | 16 | 15 | 14 | 63 | 25 | 35 | 50 |
| | 3RT1 034 | - | 25 | 22.3 | 20.3 | 19.1 | 63 | 25 | - | - |
| | 3RT1 035 | - | - | 25 | 25 | 25 | 63 | 25 | - | - |
| Operating rang | ge 12.5 to 5 | 0 A | | | | | | | | |
| 3UF1 845-2CA00 | 3RT1 025 | 17 | 17 | 16 | 15 | 14 | 63 | 25 | 20 | 35 |
| | 3RT1 026 | 25 | 18 | 16 | 15 | 14 | 100 | 35 | 35 | 50 |
| | 3RT1 034 | 32 | 25.5 | 22.3 | 20.3 | 19.1 | 100 | 63 | - | - |
| | 3RT1 035 | 40 | 33 | 29.4 | 28 | 26.5 | 100 | 63 | - | - |
| | 3RT1 036 | 50 | 38.5 | 32.7 | 29.4 | 26.5 | 100 | 80 | - | - |
| | 3RT1 044 | - | 50 | 49 | 45 | 41.7 | 100 | 80 | - | - |
| | 3RT1 045 | - | - | 50 | 47 | 45 | 100 | 80 | - | - |
| | 3RT1 046 | - | - | - | 50 | 50 | 100 | 80 | - | - |
| Operating rang | ge 16 to 65 | Α | | | | | | | | |
| 3UF1 847-2DA00 | - | 32 | 25.5 | 22.3 | 20.3 | 19.1 | 125 | 63 | - | - |
| | 3RT1 035 | 40 | 33 | 29.4 | 28 | 26.5 | 125 | 63 | - | - |
| | 3RT1 036 | 50 | 38.5 | 32.7 | 29.4 | 26.5 | 160 | 80 | - | - |
| | 3RT1 044 | 65 | 56 | 49 | 45 | 41.7 | 160 | 125 | - | - |
| | 3RT1 045 | 65 | 61 | 53 | 47 | 45 | 160 | 125 | - | - |
| | 3RT1 046 | - | 65 | 59 | 53 | 50 | 160 | 125 | - | - |
| | 3TF5 0 | 65 | 65 | 65 | 65 | 65 | 160 | 125 | 80 | 100 |
| | | | | | | | | | | |

1) Pay attention to operating voltage.

2) Type of coordination and short-circuit protection devices according to IEC 60947-4-1/VDE 660 Part 102:
Type of coordination 1 In the event of a short-circuit, persons and equipment must not be

endangered by the contactor or starter. They do not have to be suitable for further operation without repair and the renewal of parts.

 Type of coordination 2
 In the event of a short-circuit, persons and equipment must not be in danger from the contactor or starter. These must be suitable for subsequent operation. There is a danger of contact welding.

3) Operating range +5 %.

Current transformers for overload protection

| Overload relay | Contactor | Rated operation | ating current A | C-3 in A at 40 | 0 V and CLAS | S | Type of coordination ²⁾ | | | | | |
|-----------------------|--------------|-----------------|-----------------|----------------|--------------|------|---|-------------------|-----------------|----------------------|--|--|
| | | 5 and 10 | 15 | 20 | 25 | 30 | 1 | 2 | | | | |
| | | | | | | | Fuse links i | n A ¹⁾ | | | | |
| | | | | | | | NH, Type 3N DIAZED, Tyj NEOZED, Ty gL/gG | pe 5SB | Type 3ND, aM | British Standards | | |
| | | | | | | | | | | BS88 fuses | | |
| Operating rang | ge 25 to 100 | Α | | | | | | | | | | |
| 3UF1 848 -2EA00 | 3RT1 044 | 65 | 65 | 49 | 45 | 41.7 | 250 | 125 | - | - | | |
| | 3RT1 045 | 80 | 61 | 53 | 47 | 45 | 250 | 160 | - | - | | |
| | 3RT1 046 | 95 | 69 | 59 | 53 | 50 | 250 | 160 | - | - | | |
| | 3RT1 054 | 100 | 93 | 82 | 75 | 69 | 250 | 160 | 125 | 125 | | |
| | 3RT1 055 | - | 100 | 100 | 98 | 90 | 250 | 160 | 125 | 125 | | |
| | 3RT1 056 | - | - | - | 100 | 100 | 250 | 160 | 125 | 125 | | |
| Operating rang | ge 32 to 130 | A | | | | | | | | | | |
| 3UF1 850-3AA00 | 3RT1 044 | 65 | 56 | 49 | 45 | 41.7 | 250 | 125 | - | - | | |
| | 3RT1 045 | 80 | 61 | 53 | 47 | 45 | 250 | 160 | - | - | | |
| | 3RT1 046 | 95 | 69 | 59 | 53 | 50 | 250 | 160 | - | - | | |
| | 3RT1 054 | 115 | 93 | 82 | 75 | 69 | 315 | 224 | 160 | 160 | | |
| | 3RT1 055 | 130 | 122 | 107 | 98 | 90 | 315 | 224 | 160 | 160 | | |
| | 3RT1 056 | - | 130 | 130 | 120 | 111 | 315 | 224 | 160 | 160 | | |
| | 3RT1 064 | - | - | - | 130 | 130 | 315 | 224 | 160 | 160 | | |
| Operating rang | ge 50 to 200 |) A | | | | | | | | | | |
| 3UF1 852-3BA00 | 3RT1 054 | 115 | 93 | 82 | 75 | 69 | 355 | 224 | 160 | 160 | | |
| | 3RT1 055 | 150 | 122 | 107 | 98 | 90 | 355 | 224 | 160 | 200 | | |
| | 3RT1 056 | 185 | 150 | 131 | 120 | 111 | 355 | 224 | 160 | 200 | | |
| | 3RT1 064 | 200 | 182 | 160 | 146 | 135 | 355 | 224 | 160 | 200 | | |
| | 3RT1 065 | - | 200 | 188 | 172 | 159 | 355 | 224 | 160 | 200 | | |
| | 3RT1 066 | - | - | 200 | 195 | 180 | 355 | 224 | 160 | 200 | | |
| | 3RT1 075 | - | - | - | 200 | 200 | 355 | 224 | 160 | 200 | | |

1) Pay attention to operating voltage.

2) Type of coordination and short-circuit protection devices according to IEC 60947-4-1/VDE 660 Part 102:
Type of coordination 1 In the event of a short-circuit, persons and equipment must not be in danger from the contactor or starter. They do not have to be suitable for further operation without repair and the renewal of parts.
Type of coordination 2.

Type of coordination 2 In the event of a short-circuit, persons and equipment must not be in danger from the contactor or starter.

These must be suitable for subsequent operation. There is a danger of contact welding.

Current transformers for overload protection

| Overload relay | Contactor | Rated oper | ating curren | t AC-3 in A at | t 400 V and Cl | _ASS | Type of c | oordination ²⁾ | | |
|----------------|--------------|------------|--------------|----------------|----------------|------|-----------|-------------------------------|-----------------|----------------------|
| | | 5 and 10 | 15 | 20 | 25 | 30 | 1 | 2 | | |
| | | | | | | | Fuse link | (s in A ¹⁾ | | |
| | | | | | NH, DIAZ | | | 3NA Type 5SB , Type 5SE | Type 3ND, aM | British Standards |
| | | | | | | | | | | BS88 fuses |
| Operating rang | ge 63 to 250 |) A | | | | | | | | |
| 3UF1 854-3CA00 | 3RT1 056 | 185 | 150 | 131 | 120 | 111 | 355 | 250 | 160 | 200 |
| | 3RT1 064 | 225 | 182 | 160 | 146 | 135 | 400 | 250 | 250 | 355 |
| | 3RT1 065 | 250 | 215 | 188 | 172 | 159 | 500 | 400 | 315 | 355 |
| | 3RT1 066 | - | 243 | 213 | 195 | 180 | 500 | 400 | 315 | 355 |
| | 3RT1 075 | - | 250 | 250 | 250 | 240 | 500 | 400 | 400 | 355 |
| | 3RT1 076 | - | - | - | - | 250 | 500 | 400 | 400 | 355 |
| Operating rang | ge 100 to 40 | 00 A | | | | | | | | |
| 3UF1 856-3DA00 | 3RT1 065 | 265 | 215 | 188 | 172 | 159 | 500 | 400 | 315 | 400 |
| | 3RT1 066 | 300 | 243 | 213 | 195 | 180 | 500 | 400 | 315 | 400 |
| | 3RT1 075 | 400 | 324 | 284 | 260 | 240 | 630 | 500 | 400 | 450 |
| | 3RT1 076 | - | 400 | 355 | 325 | 300 | 630 | 500 | 500 | 450 |
| | 3TF6 8 | - | - | 400 | 400 | 400 | 800 | 500 | 630 | 450 |
| Operating rang | ge 125 to 50 | 00 A | | | | | | | | |
| 3UF1 857-3EA00 | 3RT1 066 | 300 | 243 | 213 | 195 | 180 | 500 | 400 | 315 | 400 |
| | 3RT1 075 | 400 | 324 | 284 | 260 | 240 | 800 | 500 | 400 | 450 |
| | 3RT1 076 | 500 | 405 | 355 | 325 | 300 | 800 | 500 | 500 | 450 |
| | 3TF6 8 | - | 500 | 500 | 479 | 441 | 800 | 500 | 630 | 450 |
| | 3TF6 9 | - | - | - | 500 | 500 | 800 | 500 | 630 | 450 |
| Operating rang | ge 160 to 63 | 30 A | | | | | | | | |
| 3UF1 868-3FA00 | 3RT1 075 | 400 | 324 | 284 | 260 | 240 | 800 | 500 | 400 | 450 |
| | 3RT1 076 | 500 | 405 | 355 | 325 | 300 | 800 | 500 | 500 | 450 |
| | 3TF6 8 | 630 | 630 | 536 | 479 | 441 | 1000 | 500 | 630 | 450 |
| | 3TF6 9 | - | - | - | 531 | 500 | 1000 | 500 | 630 | 450 |
| Operating rang | ge 200 to 82 | 20 A | | | | | | | | |
| 3UF1 869-3GA00 | 3TF6 8 | 630 | 630 | 536 | 479 | 441 | 1000 | 500 | 630 | 450 |
| | 3TF6 9 | 820 | 662 | 572 | 531 | 500 | 1000 | 500 | 630 | 450 |

1) Pay attention to operating voltage.

2) Type of coordination and short-circuit protection devices according to IEC 60947-4-1/VDE 660 Part 102:

Type of coordination 1
 Type of coordination 1
 In the event of a short-circuit, persons and equipment must not be in danger from the contactor or starter.
 They do not have to be suitable for further operation without repair

and the renewal of parts.Type of coordination 2

In the event of a short-circuit, persons and equipment must not be in

danger from the contactor or starter. These must be suitable for subsequent operation. There is a danger of contact welding.

Current transformers for overload protection

| | Version | DT | Order No. | PS* | Weigh per Pl appro |
|--|--|--------|----------------------------------|------------------|--------------------------|
| Current transformers | for stand-alone installation | | | | kg |
| | for snap-on and screw mounting, suitable for snapping on to | | | | |
| ALL! | 35 mm standard mounting rails accord. to EN 50022 | | | | |
| 000 | Operating range | | | | |
| SIEMENS | A | | | | |
| FIGURE STATE | $0.25 \dots 2.5^{(1)}$ | A | 3UF1 843-1BA00 | 1 unit | 0.48 |
| | 1.25 12.5 ¹⁾ 2.5 25 ¹⁾ | D D | 3UF1 843-2AA00 3UF1 843-2BA00 | 1 unit 1 unit | 0.48 0.49 |
| 6666 | 12.5 50 | D | 3UF1 845-2CA00 | 1 unit | 0.69 |
| ver | 16 65 | D | 3UF1 847-2DA00 | 1 unit | 1.18 |
| UF1 843 | 25 100 | D | 3UF1 848-2EA00 | 1 unit | 1.23 |
| Current transformers | for mounting on contactors and stand-alone installation | | | | |
| 0 00 00 | for screw mounting | | | | |
| | Operating range | | | | |
| Here 10 miles | A | | | | |
| And a lot of the second | 32 130 | D | 3UF1 850-3AA00 | 1 unit | 1.74 |
| 210 4444 | 50 200 63 250 | D D | 3UF1 852-3BA00 3UF1 854-3CA00 | 1 unit 1 unit | 1.89 3.61 |
| UF1 868 | 100 400 | D | 3UF1 856-3DA00 | 1 unit | 3.85 |
| 011000 | 125 500 | D | 3UF1 857-3EA00 | 1 unit | 4.13 |
| | 160 630 205 820 | D | 3UF1 868-3FA00 3UF1 868-3GA00 | 1 unit 1 unit | 7.78 8.92 |
| Ferminal covers | 203 020 | D | 30F1 808-3GA00 | T UIIII | 0.92 |
| and the the set | for converter/contactor combinations and stand-alone mounting for | | | | |
| the property and | converters with and without box terminals | | | | |
| 14-1 () | (cover required per connection side) | | | | |
| der 1 | 3UF1 845 3UF1 848 | B B | 3TX7 446-0A 3TX7 466-0A | 1 unit | 0.00 |
| ~ 10 | 3UF1 850, 3UF1 852 | B | 3TX7 506-0A | 1 unit 1 unit | 0.04 |
| 4 | 3UF1 854 3UF1 857 | В | 3TX7 536-0A | 2 units | 0.1 |
| | 3UF1 868-3FA00 | B | 3TX7 686-0A 3TX7 696-0A | 1 set | 0.4 |
| / | 3UF1 868-3GA00 | D | 31X/ 090-UA | 1 set | 0.40 |
| TX7 466-0A | for covering the screw connection for direct mounting on contactor (one cover required per contactor/converter combination) | | | | |
| | 3UF1 848 | С | 3TX7 466-0B | 1 unit | 0.0 |
| | 3UF1 850, 3UF1 852 | В | 3TX7 506-0B | 1 unit | 0.0 |
| | 3UF1 854 3UF1 857 3UF1 868-3FA00 | B B | 3TX7 536-0B 3TX7 686-0B | 1 unit 1 unit | 0.05 0.08 |
| | 3UF1 868-3GA00 | B | 3TX7 696-0B | 1 unit | 0.00 |
| Box terminal blocks | | | | | |
| | for stand-alone installation | | | | |
| | 3UF1 847, 3UF1 848 | В | 3TX7 460-0E | 1 unit | 0.09 |

 The following adjustment ranges applicable:

 3UF1 843-1BA00, 0.25 ... 1.25 A

 3UF1 843-2AA00, 1.25 ... 6.3 A

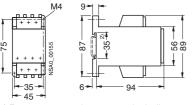
 3UF1 843-2BA00, 2.5 ... 12.5 A

control functions pole reversal and Dahlander circuit. Please note the configuring aids in the 3UF5 7 system manual.

Current transformers for overload protection

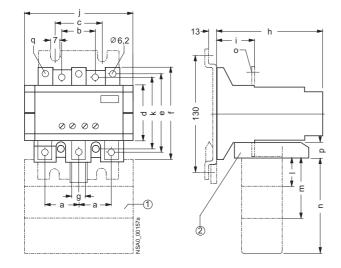
Dimension drawings

3UF1 843 current transformer



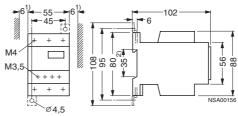
2) For snap-on mounting onto standard rails to DIN EN 50 022-35 x 7,5 or DIN EN 50 022-35 x 15.

3UF1 847 to 3UF1 852 current transformers for snap-on mounting on 75 mm standard mounting rails acc. to EN 50023 with base plate



| 3UF1 845 current transfor | rmer |
|---------------------------|------|
|---------------------------|------|

for individual mounting: for snap-on and screw mounting, suitable for snapping on to 35 mm standard mounting rails acc. to EN 50022



Clearance to earthed parts.
 For snap-on mounting onto standard rails to DIN EN 50 022-35 x 7,5 or DIN EN 50 022-35 x 15.

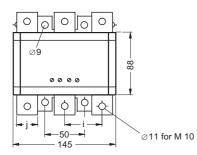
| Current transformers | 3UF1 847, 3UF1 848 | 3UF1 850-0JA00 | 3UF1 852-0JA00 |
|-------------------------|-----------------------|--|--|
| Base plate | 3UF1 900-0KA00 | 3UF1 900-0JA00 (for snap-on mounting only) | 3UF1 900-0JA00 (for snap-on mounting only) |
| Box terminal block | 3TX7 460-0E | 3TX7 500-0E | - |
| Additional cover | 3TX7 466-0A | 3TX7 506-0A | 3TX7 506-0A |

1 Additional cover, can be shortened ② Box terminal block

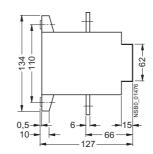
| Transformers | а | b | С | d | е | f | g | h | i | j | k | Ι | m | n | 0 | р | q | r |
|---------------------|------|----|----|--------------|-----|-----|------|----|----|----|-----|----|----|----|------------|----|-------|----------------------|
| 3UF1847, 3UF1848 | 26,5 | 25 | 50 | 82 | 111 | 122 | 10,5 | 90 | 46 | 90 | 105 | 35 | 62 | 89 | - | 19 | Ø 6,2 | Ø 5,8 (M5) |
| 3UF1850 3UF1852 | | , | | 71,5 71,5 | | | | | | | | | | | - M8x25 | | | Ø 7 (M6) Ø 7 (M6) |

Current transformers for overload protection

3UF1 854 to 3UF1 857 current transformers

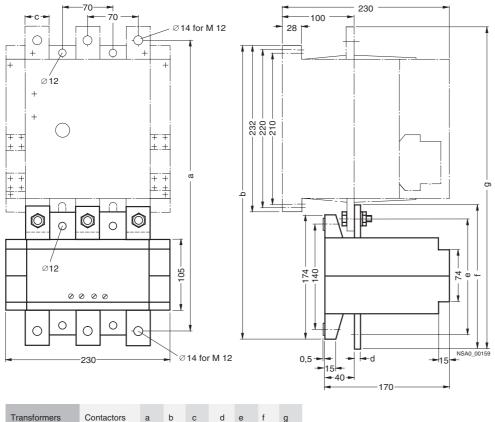


| Transformers | i | j | |
|----------------------|----|----|--|
| 3UF18 54 3UF18 56 | 48 | 25 | |
| 3UF18 57 | 52 | 30 | |



Current transformers for overload protection

3UF1 868-3FA00, 3UF1 868-3GA00 current transformers for 3TF6 8 contactors



| Transformers | Contactors | а | D | С | a | e | T | g | |
|----------------------------------|------------|------------|------------|---|--------|------------|---|------------|--|
| 3UF18 68-3FA00 3UF18 68-3GA00 | | 390 410 | 398 408 | | 5 8 | 145 155 | | 420 450 | |

Overview



The compact, user-friendly, and low-cost solution for simple control tasks

- Compact, user-friendly, can be used universally without accessories.
- "All in one": the display and operator panel are integrated.
- 34 different functions can be linked at a press of a button or with PC software; up to 130 times in total
- Functions can be changed simply via buttons; no complicated rewiring

Area of application

The LOGO! logic module is the user-friendly, low-cost solution for simple control tasks.

LOGO! is universally applicable, e.g.:

- Building installation and wiring (lighting, shutters, awnings, doors, access control, barriers, ventilation systems, etc.)
- Controlgear cubicle installation
- Machine and device construction (pumps, small presses, compressors, hydraulic lifts, conveyors ...)
- Special controls for conservatories and greenhouses
- Signal preprocessing for other controllers

The LOGO! Modular logic modules can be expanded easily for each application.

Marine approvals

American Bureau of Shipping, Bureau Veritas, Det Norske Veritas, Germanischer Lloyd, Lloyds Register of Shipping, Polski Rejestr Statków

Design

LOGO! The modular design is available in different variants for different supply voltages (DC 12 V, DC 24 V; AC 24 V, DC 115/230 V, AC 115/230 V):

- Basic variants
- Low-cost pure variants without operator control and display panels

The LOGO! variants have the following distinguishing characteristics:

- R: Relay output
- C: Clock/time switch
- o: Without display

LOGO! is simple

- Operator control panel and front panel in one unit; no other tools are necessary
- Non-volatile storage of control program and setpoints (e.g. times) in integrated EEPROM

LOGO! is space-saving

- e. g. LOGO! 230RC: 72 x 90 x 55 mm (W x H x D)
- Fitted mounting in the distribution box (same mounting dimensions as the ground-fault circuit interrupter)

LOGO! offers maximum flexibility and is universal

Expandability;

depending on the application, additional expansion modules can be connected.

LOGO! is communication-capable

 Optional communication modules support interfacing to AS-Interface and <u>instabus</u> EIB networks

Functions

LOGO! is "All in one"

The display and operator panel are integrated. It is compact, easy to use, low cost and can be used universally without the need for any accessories. 34 different functions can be used in each LOGO! They are simply linked by pressing a button or by means of PC software. It is therefore possible to adapt it to changes quickly in the future without the need for expensive rewiring.

LOGO! is simple

- Integrated basic functions (e.g. AND, OR) and special functions (e.g. timers, counters, latching relay) of the electronics
- Program generation simply by combining stored functions at the press of a key or PC software
- Easy-to-use and simple duplication of the control program with an optional program module

LOGO! offers maximum flexibility and is universal

- Easy modification by reconnecting the functions at a press of a key; no need for time-consuming rewiring
- Optional operation from the PC; For creating, simulating, online testing, and archiving the control program on the PC, including documentation facility

General data

LOGO! modular basic variants

Overview



The space-saving basic variants

• With interface for connecting extension modules

Desian

- Relay outputs with up to 10 A output current (not LOGO! 24)
- Integrated front panel with background illumination (4 x 12 characters)
- Integrated operator control panel
- Integrated basic and special functions
- Integrated EEPROM for storing control program and setpoints
- Optional programming module
- Integrated clock with automatic summertime/wintertime changeover (not LOGO! 24)
- 130 function blocks can be combined
- 8 digital inputs, 4 digital outputs
- 2 inputs as analog inputs for DC 12/24 V versions (0 to 10 V); inputs can also be used as digitally
- 2 inputs for counting up to 2 kHz can be used (for DC variants only)
- Interface for connecting expansion modules, max. 24 digital inputs, 16 digital outputs and 8 analog inputs can be addressed

Functions

- Basic functions:
 AND, OR, NOT, NAND, NOR, XOR
 - Positive/negative edge evaluation
- Special functions:
- ON delay Latching ON delay
- OFF delay
- Pulse relay
- Latching relay
- Clock-pulse relay
 Counter (forward/backward)
- Time switch
- Interval time-delay relay
- Working hour meter
- Threshold switch
- Asynchronous pulse encoder
- Yearly timer switch
- Easy-to-use switch function
- Random generator
- Staircase lighting function acc. to DIN 18015-2
- Edge-triggered interval time-delay relay
- Combined ON/OFF delay
- Analog comparator
- Analog threshold switch
- Analog delta threshold switch
- Analog watchdog
- Analog amplifier
- Text and variable display
- Shift register
- Softkey function
- 24 flags (including start-up flag)
- Integrated retentivity
 - Password protection

Optional functions

 Additional know-how protection with the optional program module

LOGO! modular basic variants

Selection and ordering data

| Version | DT | Order No. | PS* | Weight per PU approx. kg |
|---|-----------------------|---|--|---|
| LOGO! logic module 24 Supply voltage DC 24 V 8 digital inputs DC 24 V, of which 2 can be used as analog inputs (0 to 10 V), 4 digital outputs DC 24 V, 0.3 A; 130 function blocks can be combined, modular expandability | A | 6ED1 052-1CC00-0BA4 | 1 unit | 0.189 |
| LOGO! logic module 12/24RC Supply voltage DC 12/24 V, 3 digital inputs DC 12/24 V, of which 2 can be used as analog inputs (0 to 10 V), 4 relay outputs 10 A, ntegrated time switch; 130 function blocks can be combined, modular expandability | A | 6ED1 052-1MD00-0BA4 | 1 unit | 0.220 |
| LOGO! logic module 24RC Supply voltage AC/DC 24 V, 3 digital inputs AC/DC 24 V, 4 relay outputs 10 A, Integrated time switch; 130 function blocks can be combined, modular expandability | A | 6ED1 052-1HB00-0BA4 | 1 unit | 0.228 |
| LOGO! logic module 230RC Supply voltage AC/DC 115/230 V, 3 digital inputs AC/DC 115/230 V, 4 relay outputs 10 A, integrated time switch; 130 function blocks can be combined, modular expandability | A | 6ED1 052-1FB00-0BA4 | 1 unit | 0.232 |
| Accessories | | | | |
| LOGO! Manual 9 German 9 English 9 French 9 Spanish 9 Italian | A A X X X | 6ED1 050-1AA00-0AE5 6ED1 050-1AA00-0BE5 6ED1 050-1AA00-0CE5 6ED1 050-1AA00-0DE5 6ED1 050-1AA00-0EE5 | 1 unit 1 unit 1 unit 1 unit 1 unit | 0.353 0.359 0.353 0.353 0.353 |
| LOGO! Memory card | А | 6ED1 056-5CA00-0BA0 | 1 unit | 0.003 |
| LOGO! Soft Comfort V4.0 or programming on the PC in LAD/FBD; runs on Windows 95, Linux, MAC OSX; on CD-ROM | A | 6ED1 058-0BA00-0YA0 | 1 unit | 0.100 |
| .OGO! Soft Comfort Upgrade or V1.0 and higher on V4.0 | А | 6ED1 058-0CA00-0YE0 | 1 unit | 0.100 |
| .OGO! PC cable or transferring programs between LOGO! and PC | А | 6ED1 057-1AA00-0BA0 | 1 unit | 0.168 |
| .OGO! News Box, 12/24 V contains LOGO! 12/24RC, LOGO! PC cable, LOGO!Soft Comfort, Tips&Tricks manual, ccrew driver, information material German English | A | 6ED1 057-3BA00-0AA3 6ED1 057-3BA00-0BA3 | 1 unit 1 unit | 2.200 2.200 |
| LOGO! News Box, 230V contains LOGO! 230RC, LOGO! PC cable, LOGO!Soft Comfort, Tips&Tricks manual, screw driver, information material | | | , unit | 2.200 |
| • German • English | A A | 6ED1 057-3AA00-0AA8 6ED1 057-3AA00-0BA8 | 1 unit 1 unit | 2.200 2.340 |

LOGO! modular pure variants

Overview



The cost-effective pure variants

• With integrated interface for connecting extension modules

Design

- Relay outputs with up to 10 A output signal
- Integrated basic and special functions
- Integrated EEPROM for storing control program and setpoints
- Optional programming module
- Integrated clock with automatic summertime/wintertime changeover
- 130 function blocks can be combined
- 8 digital inputs, 4 digital outputs
- 2 inputs as analog inputs for DC 12/24 V versions (0 to 10 V); can also be used as digital inputs
- 2 inputs for counting up to 2 kHz can be used (for DC variants only)
- Interface for connecting expansion modules, max. 24 digital inputs, 16 digital outputs and 8 analog inputs can be addressed

Functions

- Basic functions: AND, OR, NOT, NAND, NOR, XOR
 - Positive/negative edge evaluation
- Special functions:
- ON delay Latching ON delay
- OFF delay
- Pulse relay
- Latching relay
- Clock-pulse relay
 Counter (forwards/backwards)
- Time switch
- Interval time-delay relay
- Working hour meter
- Threshold switch
- Asynchronous pulse encoder
- Twelve-month time switch
- Easy-to-use switch function
- Random generator
- Staircase lighting function acc. to DIN 18015-2
 Edge-triggered interval time-delay relay
- Combined ON/OFF delay
- Analog comparator
- Analog threshold switch
- Analog delta threshold switch
- Analog watchdog
- Analog amplifier
- Text and variable display
- Shift register
- Softkey function
- 24 flags (including start-up flag)
- Integrated retentivity
 - Password protection

Optional functions

 Additional know-how protection with the optional program module

LOGO! modular pure variants

Selection and ordering data

| Version | DT | Order No. | PS* | Weight per PU approx. |
|--|-----------------------|---|--|--|
| LOGO! logic module 24o Supply voltage DC 24 V, 8 digital inputs DC 24 V, of which 2 can be used as analog inputs (0 to 10 V), 4 digital outputs DC 24 V, 0.3 A; Without display and keyboard; 130 function blocks can be combined, modular expandability | A | 6ED1 052-2CC00-0BA4 | 1 unit | kg 0.172 |
| LOGO! logic module 12/24RCo Supply voltage DC 12/24 V, 8 digital inputs DC12/ 24 V, of which 2 can be used as analog inputs (0 to 10 V), 4 relay outputs 10 A, Integrated time switch; Without display and keyboard; 130 function blocks can be combined, modular expandability | A | 6ED1 052-2MD00-0BA4 | 1 unit | 0.216 |
| LOGO! logic module 24RCo Supply voltage AC/DC 24 V, 8 digital inputs AC/DC 24 V, 4 relay outputs 10 A, Integrated time switch; Without display and keyboard; 130 function blocks can be combined, modular expandability | A | 6ED1 052-2HB00-0BA4 | 1 unit | 0.218 |
| LOGO! logic module 230RCo Supply voltage AC/DC 115/230 V, 8 digital inputs AC/DC 115/230 V, 4 relay outputs 10 A, integrated time switch; Without display and keyboard; 130 function blocks can be combined, modular expandability | A | 6ED1 052-2FB00-0BA4 | 1 unit | 0.221 |
| Accessories | | | | |
| LOGO! Manual • German • English • French • Spanish • Italian | A A X X X | 6ED1 050-1AA00-0AE5 6ED1 050-1AA00-0BE5 6ED1 050-1AA00-0CE5 6ED1 050-1AA00-0DE5 6ED1 050-1AA00-0EE5 | 1 unit 1 unit 1 unit 1 unit 1 unit | 0.353 0.359 0.353 0.353 0.353 0.353 |
| LOGO! Memory card for copying with know-how protection | А | 6ED1 056-5CA00-0BA0 | 1 unit | 0.003 |
| LOGO! Soft Comfort V4.0 for programming on the PC in LAD/FBD; runs on Windows 95, Linux, MAC OSX; on CD-ROM | A | 6ED1 058-0BA00-0YA0 | 1 unit | 0.100 |
| LOGO! Soft Comfort Upgrade for V1.0 and higher on V4.0 | А | 6ED1 058-0CA00-0YE0 | 1 unit | 0.100 |
| LOGO! PC cable for transferring programs between LOGO! and PC | А | 6ED1 057-1AA00-0BA0 | 1 unit | 0.168 |
| LOGO! News Box, 12/24 V contains LOGO! 12/24RC, LOGO! PC cable, LOGO!Soft Comfort, Tips&Tricks manual, screw driver, information material • German | A | 6ED1 057-3BA00-0AA3 | 1 unit | 2.200 |
| • English | A | 6ED1 057-3BA00-0BA3 | 1 unit | 2.200 |
| LOGO! News Box, 230 V contains LOGO! 230RC, LOGO! PC cable, LOGO!Soft Comfort, Tips&Tricks manual, screw driver, information material • German • English | A A | 6ED1 057-3AA00-0AA8 6ED1 057-3AA00-0BA8 | 1 unit 1 unit | 2.200 2.340 |

LOGO! modular extension modules

Overview



Expansion modules for connection of LOGO! Modular

• With digital inputs and outputs or analog inputs

Selection and ordering data

Version DT Order No. PS³ Weight per PU approx. kg LOGO! DM8 24 А 6ED1 055-1CB00-0BA0 1 unit 0.120 Supply voltage DC 24 V, 4 digital inputs DC 24 V, 4 digital outputs DC 24 V, 0.3 A 6ED1 055-1MB00-0BA1 LOGO! DM8 12/24R 0.157 Δ 1 unit Supply voltage DC 12/24 V, 4 digital inputs DC 12/24 V, 4 relay outputs 5 A 6ED1 055-1HB00-0BA0 LOGO! DM8 24R А 1 unit 0.157 Supply voltage AC/DC 24 V, 4 digital inputs AC/DC 24 V, 4 relay outputs 5 A LOGO! DM8 230R А 6ED1 055-1FB00-0BA1 1 unit 0.160 Supply voltage AC/DC 115/230 V, 4 digital inputs AC/DC 115/230 V, 4 relay outputs 5 A 6ED1 055-1MA00-0BA0 LOGO! AM2 А 1 unit 0.112 Supply voltage DC 12/24 V, 2 analog inputs 0 to 10 V or 0 to 20 mA, 10-bit resolution LOGO! AM2 PT 100 А 6ED1 055-1MD00-0BA0 1 unit 0.123 Supply voltage DC 12/24 V, 2 analog inputs Pt100, temperature range -50 °C to 200 °C Accessories LOGO! Manual German А 6ED1 050-1AA00-0AE5 1 unit 0.353 English A X 6ED1 050-1AA00-0BE5 6ED1 050-1AA00-0CE5 1 unit 0.359 • French 1 unit X 6ED1 050-1AA00-0DE5 0.353 Spanish 1 unit Italian Х 6ED1 050-1AA00-0EE5 0.353 1 unit LOGO! Memory card for copying with know-how protection А 6ED1 056-5CA00-0BA0 1 unit 0.003 LOGO!Soft Comfort V4.0 6ED1 058-0BA00-0YA0 0.100 А 1 unit for programming on the PC in LAD/FBD; runs on Windows 95, Linux, MAC OSX; on CD-ROM LOGO!Soft Comfort Upgrade А 6ED1 058-0CA00-0YE0 0.100 1 unit for V1.0 and higher on V4.0 6ED1 057-1AA00-0BA0 LOGO! PC cable А 1 unit 0.168 for transferring programs between LOGO! and PC LOGO! News Box, 12/24 V contains LOGO! 12/24RC, LOGO! PC cable, LOGO!Soft Comfort, Tips&Tricks manual, screw driver, information material 6ED1 057-3BA00-0AA3 2.200 • German А 1 unit 6ED1 057-3BA00-0BA3 • English А 1 unit 2.200 LOGO! News Box, 230V

contains LOGO! 200RC, LOGO! PC cable, LOGO!Soft Comfort, Tips&Tricks manual, screw driver, information material

- German
 English
- English

Design

- Relay outputs with up to 5 A output signal
- 4 digital inputs, 4 digital outputs or 2 analog inputs
- Interface for connection of LOGO! Modular logic modules

1 unit

1 unit

2.200

2.340

6ED1 057-3AA00-0AA8

6ED1 057-3AA00-0BA8

А

Δ

LOGO! modular communications modules

Design

- Up to 16 digital inputs (virtual)
- Up to 12 digital outputs (virtual)
- Up to 8 analog inputs (virtual)
- For mounting onto 35 mm standard rail
- Width: 2 modular widths

Functions

- For communication between the LOGO! master and external *EIB* components via *EIB*
- Stations on the *EIB*; allow LOGO! to communicate with other *EIB* components by exchanging *EIB* message frames
- Output of the current states of the configured *EIB* stations for LOGO!;

the control can combine these with the help of its logical functions and timers.

• Parameters can be set, changed or combined quickly an easily using LOGO! without the need for a programming device.

Expansion module for the LOGO! basic variants

• For communication between the LOGO! master and external *EIB* components via *EIB*

Area of application

Overview

The CM EIB/KNX communication module allows communication between the LOGO! master and external *EIB* components via *EIB*. The module can be used to integrate LOGO! into an *EIB* system.

The module is connected to the LOGO! basic variants as an expansion module.

Selection and ordering data

| Version | DT | Order No. | PS* | Weight per PU approx. |
|--|----|---------------------|--------|-----------------------------|
| | | | | kg |
| LOGO! communication module CM EIB KNX for connection to <i>EIB</i> , supply voltage DC 24 V | В | 6BK1 700-0BA00-0AA0 | 1 unit | 0.050 |

LOGO!Contact

Overview



Switching module for switching resistive loads and motors directly

Area of application

LOGO!Contact is a switching module for direct switching of resistive loads up (to 20 A) and motors (up to 4 kW). LOGO!Contact operates hum-free without noise pollution.

LOGO!Contact is universal

- Buildings/electrical installations
- Industry and commerce

Design

- LOGO!Contact is available in two variants:
- Operating voltage DC 24 V
- Operating voltage AC 230 V, 50/60 Hz

unechy

| Selection and ordering data | | | | |
|---|--------|--|------------------|-----------------------------|
| Version | DT | Order No. | PS* | Weight per PU approx. |
| LOGO!Contact | | | | kg |
| Switching module for direct switching of resistive loads up to 20 A and motors up to 4 kW • Operating voltage 24 V • Operating voltage 230 V | A A | 6ED1 057-4CA00-0AA0 6ED1 057-4EA00-0AA0 | 1 unit 1 unit | 0.160 0.160 |

Overview



The user-friendly software for switchgear program generation on the PC

- Switchgear program generation for function diagrams (FBD) or contact diagrams (LAD)
- Additional testing, simulation, online testing and archiving of the switchgear programs
- Professional documentation with the help of various comment and print functions

Area of application

LOGO!Soft Comfort is the multilingual software for switchgear program generation with LOGO! on the PC. How to place the functions on the drawing board by means of "Drag and Drop" is almost self-explanatory. The integrated offline simulation allows the switchgear programs to be tested on the PC beforehand. During the online test the current values for LOGO! are displayed on screen.

Various print options permit professional documentation.

LOGO!Soft Comfort V4.0 can be used to program all components of the LOGO! family.

Design

The connection between LOGO! and the PC is established with the help of the LOGO! PC cable (serial interface)

Minimum system requirements:

Windows 95/98, NT 4.0, ME, 2000 or XP

- Pentium PC
- 90 MB free on hard disk
- 64 MB RAM
- SVGA graphics card with minimum 800 x 600 resolution (256 colors)

LOGO!Soft

Mac OS X

 PowerMac G3, G4, G4 Cube, IMac, PowerBook G3, G4 or iBook

Linux (tested with Caldera OpenLinux 2.4)

- Runs on all Linux releases on which Java 2 SDK Version 1.3.1
 runs
- Please consult your Linux release for hardware requirements.

Functions

- Control program generation with the programming languages FBD and LAD (switchable)
- Comprehensive documentation functions
- Program simulation (offline)
- Program test (online)
- Comprehensive, context-sensitive online help functions
- The following functions are available:
- Basic functions (AND, OR, NOT, NAND, NOR, XOR, positive edge evaluation, negative edge evaluation)
- ON delay
- OFF delay
- Current impulse relay
- Latching
- Clock-pulse relay
- Latching ON delay
- Working hour meter
- Interval time-delay relay/pulse output mode
- Up/down counter
- Threshold switch
- Pulse encoder
- Twelve-month time switch
- Time switch
- ON/OFF delay
- Random generator
- Edge-triggered interval time-delay relay
- Analog threshold switch
- Analog comparator
- Analog delta threshold switch
- Analog watchdog
- Analog amplifier
- Staircase lighting switch
- · Easy-to-use switch
- Message texts
- Shift register
- Softkey

| Selection | and | orderi | ing c | lata |
|-----------|-----|--------|-------|------|
|-----------|-----|--------|-------|------|

| Version | DT | Order No. | PS* | Weight per PU approx. |
|--|----|---------------------|--------|-----------------------------|
| LOGO!Soft Comfort V4.0 for programming on the PC in LAD/FBD; runs on Windows 95, Linux, MAC OSX; on CD-ROM | A | 6ED1 058-0BA00-0YA0 | 1 unit | kg 0.100 |
| LOGO!Soft Comfort Upgrade for V1.0 and higher on V4.0 | A | 6ED1 058-0CA00-0YE0 | 1 unit | 0.100 |

System overview

Overview

AS-Interface - The System

AS-Interface - Just another bus system?

AS-Interface has been available since 1994. It allows digital and analog signals generated by processes or machines to be transferred in binary form. AS interface is the universal interface between the higher-level control level and simple binary actuators and sensors.

Why was AS-Interface developed?

High costs due to immense wiring outlays, which resulted from connecting the field level to the PLCs, demanded a structural change in automation technology:

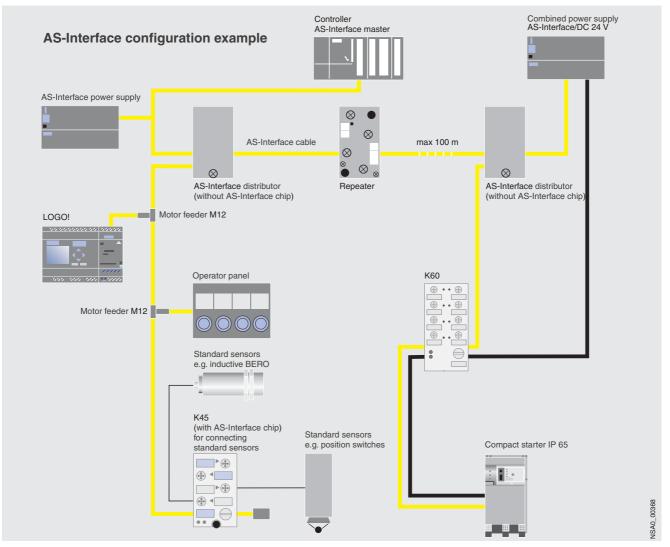
Every single actuator or sensor had to be connected to the control unit and a power supply.

This not only resulted in significant material and wiring costs, but also increased the number of possible causes for faults. Until 1997, 36 % of all machine and plant downtimes were due to installation faults.

The solution is distributed technology -

first in automation technology, but also in drive and control technology.

What does this mean? It's very simple: conventional, high-cost parallel wiring has been replaced with a serial fieldbus i.e. a two-wire conductor with which all automation stations are connected.



AS-Interface configuration example

Benefits

Your advantages at a glance

| | Rating | Your advantages |
|-------------------------|---|--|
| Minimal wiring overhead | A single cable is sufficient for wiring up sensors, actuators, and operator panels. Simple serial connection to the control unit via AS-Inter- face instead of a parallel connection with many cables! | Material savingsNo thick cable harnessesLess space required in the control cabinets |
| Fast installation | Sensors and actuators are easily installed with modules connected to the AS-Interface cable. Contact blades in the modules penetrate the insulation of the cable and make contact with the copper conductor. | Minimum time required for installation. |
| Safe installation | Reversed polarity is virtually impossible due to the geometry of the cable and the insulation piercing method used during installation. | No wasted time or money due to wrong installation or plant downtimes. |
| Flexible engineering | Distributed and modular installation allows partial solutions to be tested in parallel before the overall solution has been implemented. Changes and expansions can be implemented flexibly. | Saves time for new installations and allows flexibility for existing plants. |
| Open system | AS-Interface is an open system according to international standard EN 50295. | AS-Interface is a multi-vendor, future-oriented system. Siemens offers the complete system with all products for complete solutions with AS-Interface. |

Technical specifications

Up to 31 slaves can be connected to a single standard AS-Interface system. Each slave can have up to 4 inputs and 4 outputs (in total therefore up to 124 inputs and 124 outputs).

According to extended AS-Interface specification 2.1, up to 62 A/B slaves can be connected to a single AS-Interface system. These have up to 4 inputs and 3 outputs (i.e. up to 248 inputs and 186 outputs within a single AS-Interface system).

Intelligent sensors with integrated AS-Interface chips are given their own slave address and behave like "normal" slaves withrespect to the master.

| - +- 00 |
|---|
| |
| p to 62 |
| inputs + 186 outputs |
| a and supply up to 7 A |
| -shielded cable 2 x 1.5 mm ² |
| ms |
| grated into the master |
| analog values per 16 bits |
| ter/slave |
| m, with repeater up to 500 m |
| o Category 4 acc. to EN 954-1 |
| r gr a |

System overview

Further information

9 9

We have adapted our catalog structure to current developments. This has resulted in several changes. Our AS-Interface core products can now be found in Catalog IK PI (Order No. E86060-K6710-A101-B3-7600).

The table below lists in detail in which catalog our AS-Interface products can be found.

| AS-Interface pro (AS-Interface ac | ducts c. to EN 50295) | Catalog | Section |
|---|--|--|--|
| AS-Interface po AS-Interface ca AS-Interface lig AS-Interface LS | fety monitors fe compact modules sistion switches ble-operated switches ht curtains and light arrays Category 4 4 laser scanners MERGENCY OFF pushbuttons ter | Catalog IK PI 2004, Order No. E86060-K6710-A101-B3- 7600 | Section 6, AS-Interface acc. to EN 50295 |
| I/O modules for Special integra Modules with s SIGNUM pusht | operation in the field operation in the control cabinet IP20 ted solutions becial functions buttons and indicator lights innection for LOGO! | | |
| Transmission me • AS-Interface sh | | | |
| System compone | nts and accessories | | |
| AS-Interface mot load feeders IP6 AS-Interface mot load feeders IP20 | 5/67 or starters and | Catalog LV 10 2004 and Catalog IK PI 2004, Order No. E86060-K6710-A101-B3-7600 | Section 6, Load feeders -> Commu cation-capable load feeders and Section 6, AS-Interface to EN 50298 |
| Communication- | apable contactors | Catalog LV 10 2004 | Section 2, Controlgear: Contactors and contactor assemblies -> Conta tors for switching motors -> SIRIUS contactors, 3-pole, 3 250 kW |
| SIGUARD safety integrated AS-Int | | Catalog LV 10 2004 | Section 11, SIGUARD safety syster -> SIGUARD signal columns |
| Opto-BERO phot K 80 type of cons | pelectrical proximity switches, struction | Catalog LV 20, Order No. E86060-K1803-A101-A3- 7600 | Section 4, Opto-BERO -> K 80 type of construction |

To order our catalogs, please use a fax ordering form¹⁾ or contact your local Siemens representative.

1) See Appendix -> Fax Order - Simply copy it, fill it in, and fax it